

Ensemble-Based Data Assimilation and Hurricane Prediction

Ryan D. Torn, Univ. at Albany, SUNY

Chris Davis, Steven Cavallo, Chris Snyder,
Wei Wang, James Done, NCAR/MMM



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State University of New York

2009 National Workshop on
Mesoscale Probabilistic Prediction

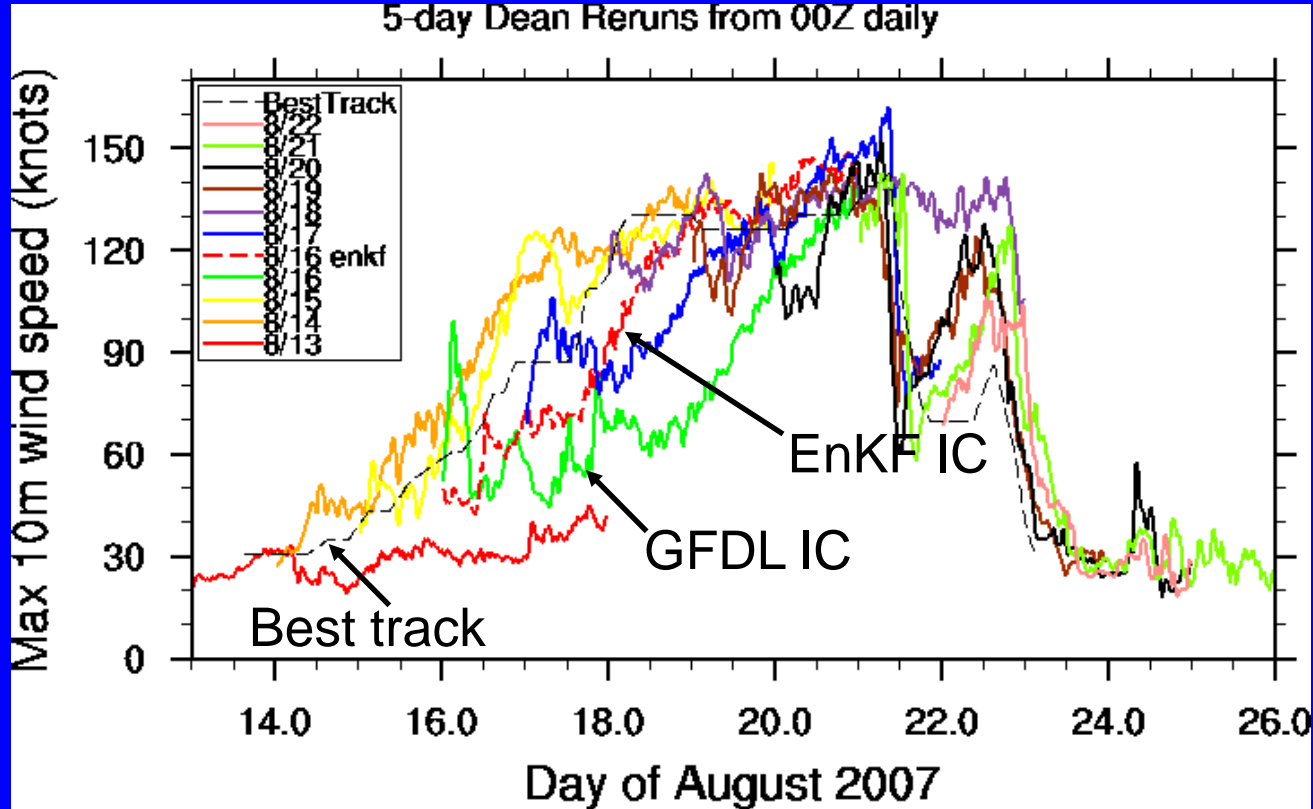
23 September 2009, Boulder, CO

Background

- Observation “assimilation” in the vicinity of TC consists of:
 - Vortex bogusing (e.g., GFDL)
 - Vortex repositioning (e.g., NCEP)
 - Do nothing
- One reason for these special techniques is there are few good error statistic models for within or near a TC
- Ensemble assimilation systems offer promise for TC because error statistics are computed from ensemble, thus providing flow-dependent estimate of how to correct state

Background

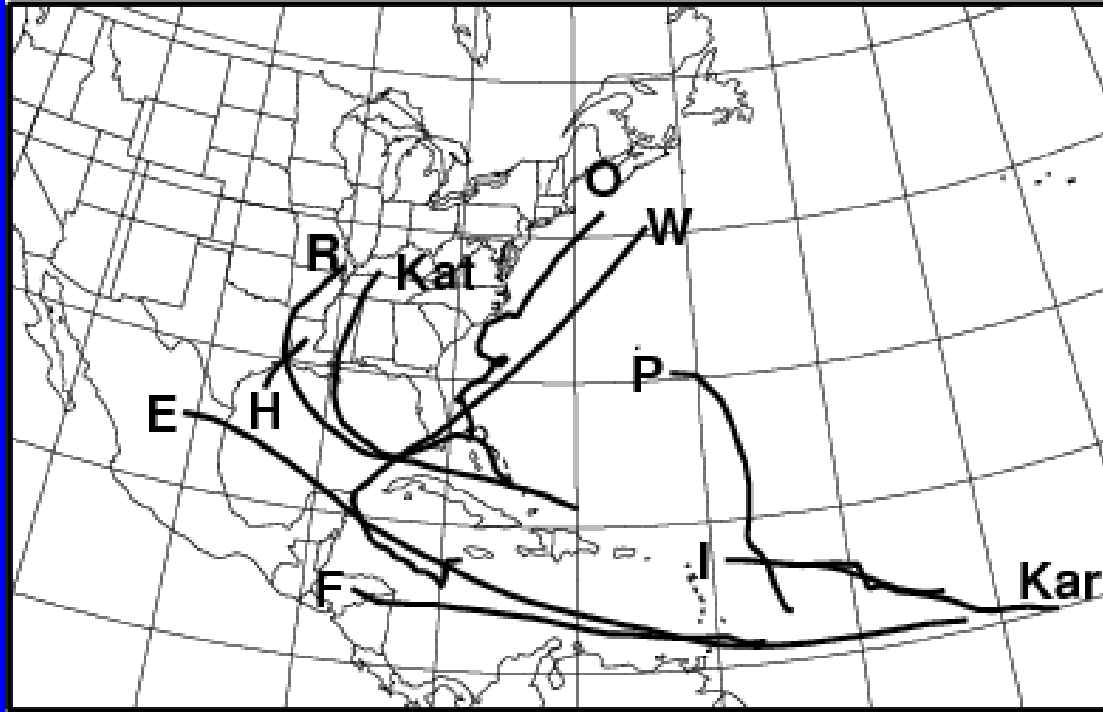
- Models need high spatial resolution to resolve important features within TC such as eyewall, rainbands, etc.
- Initializing from bogus vortex can be problematic:



Overview

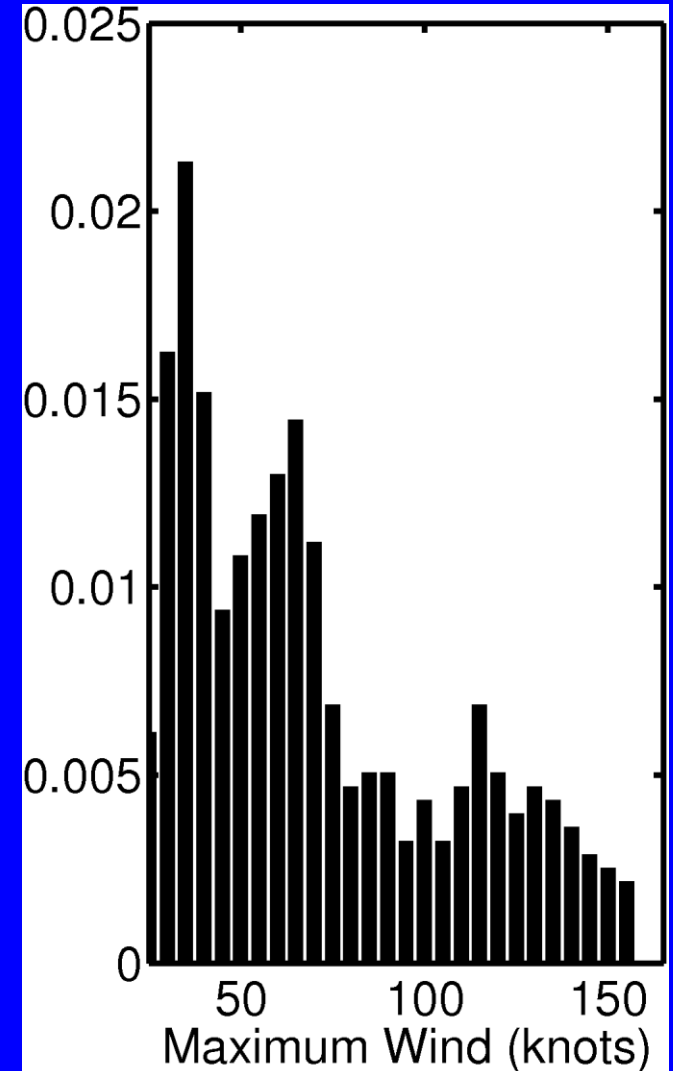
- For NCAR/MMM's participation in DTC HRH test, generated mesoscale initial conditions for the 10 different storms determined by NHC forecasters
- Goal was to generate initial conditions that:
 - Have a good estimate of environment
 - Have a “decent” estimate of TC structure
 - Does not lead to initialization problem
- Provides a good opportunity to evaluate value of ensemble assimilation system over wide range of storms

HRH Storms



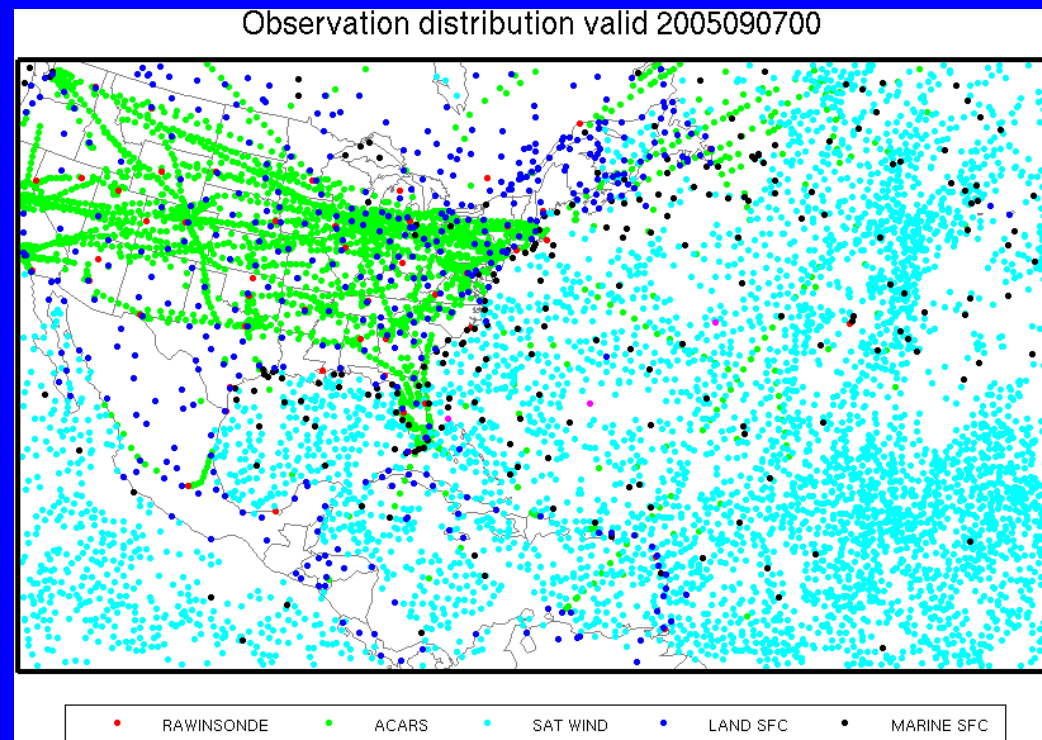
2005 – Emily, Katrina, Ophelia, Philippe,
Rita, Wilma

2007 – Felix, Humberto, Ingrid, Karen

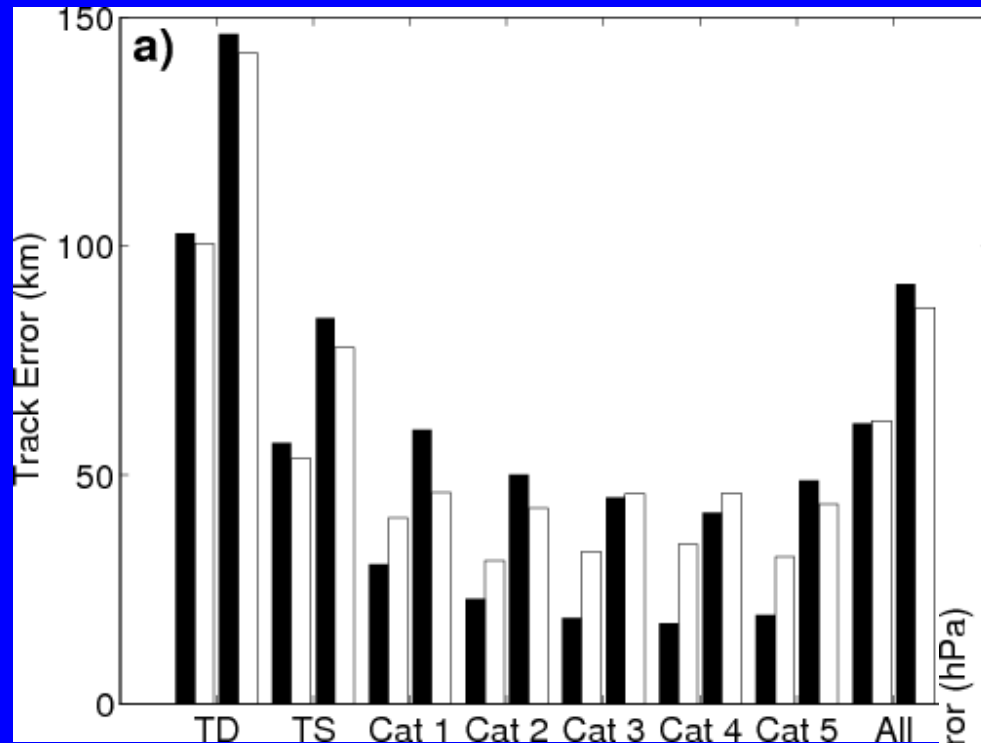


Assimilation System

- WRF ARW (v2.2.1), 36 km horizontal resolution, 96 ensemble members
- Observations assimilated each six hours from surface and marine stations (P_{sfc}), rawinsondes, synoptic dropsondes, ACARS, sat. winds, TC position and minimum SLP
- Cycle system from 3-4 days prior to TD declaration to last TC time, 90 total days over six different periods.

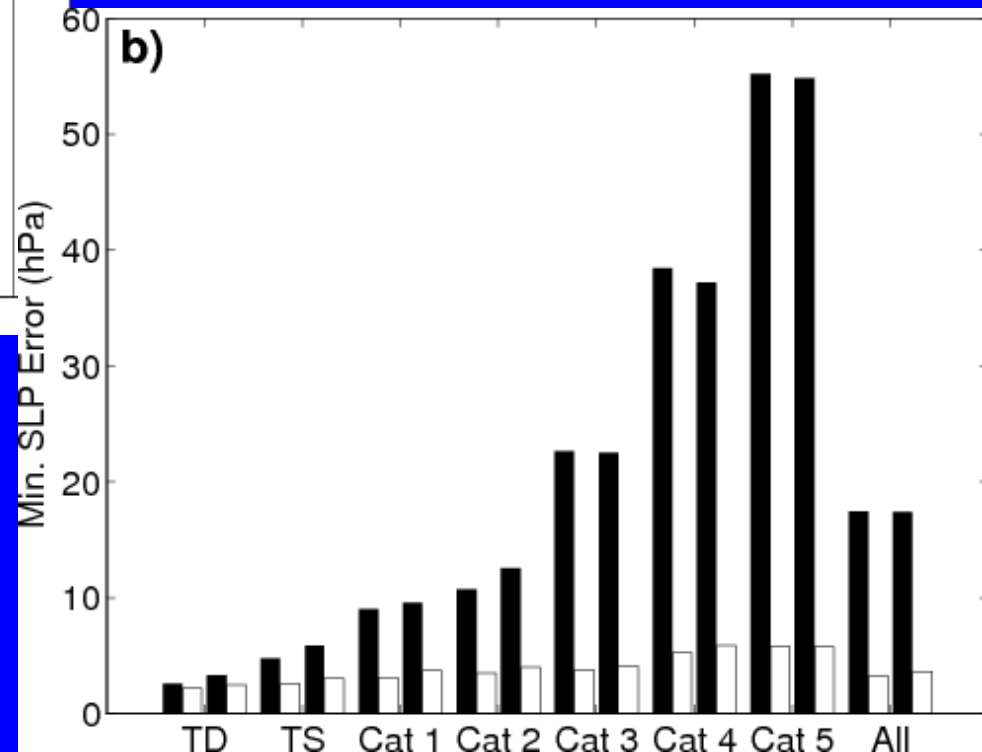


Cycling Errors

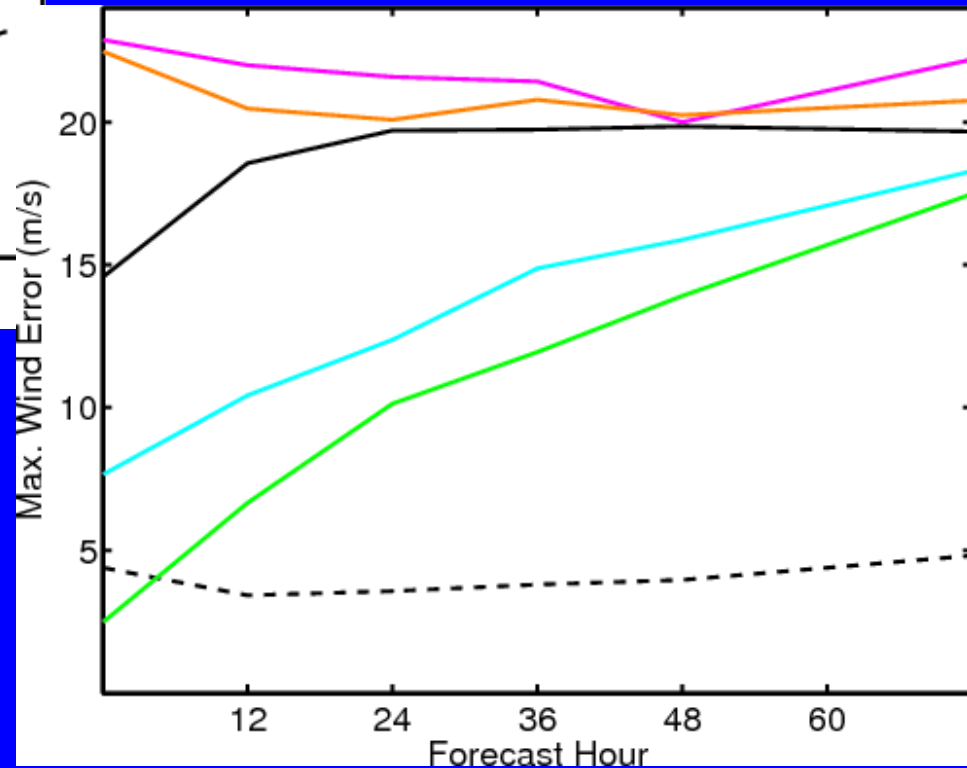
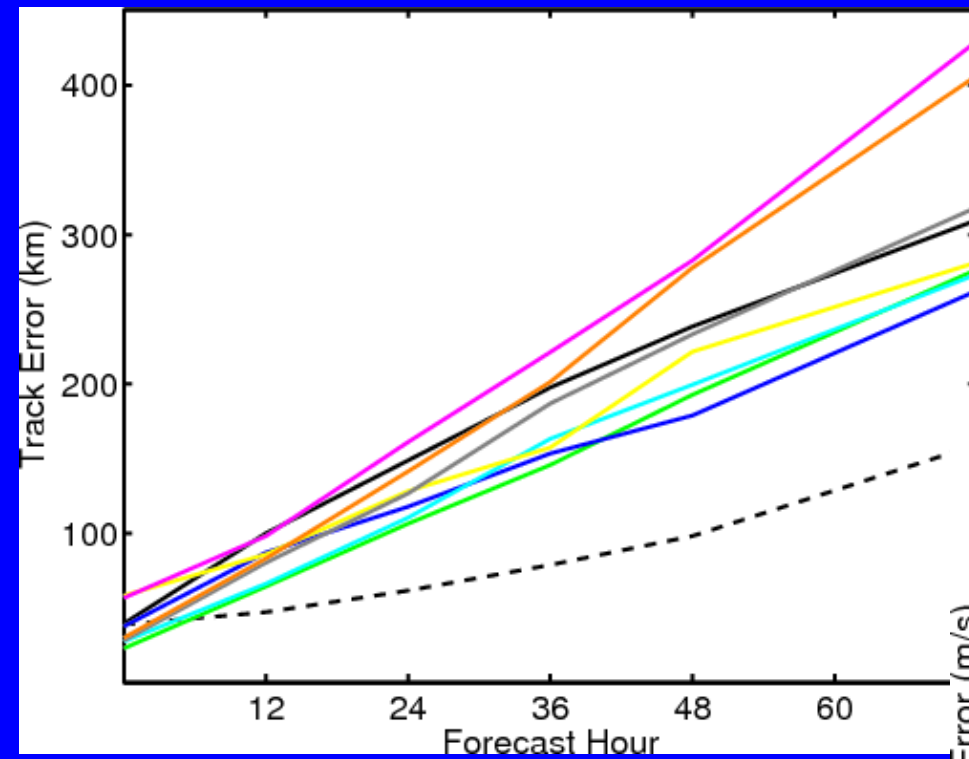


TC Position

TC Minimum SLP

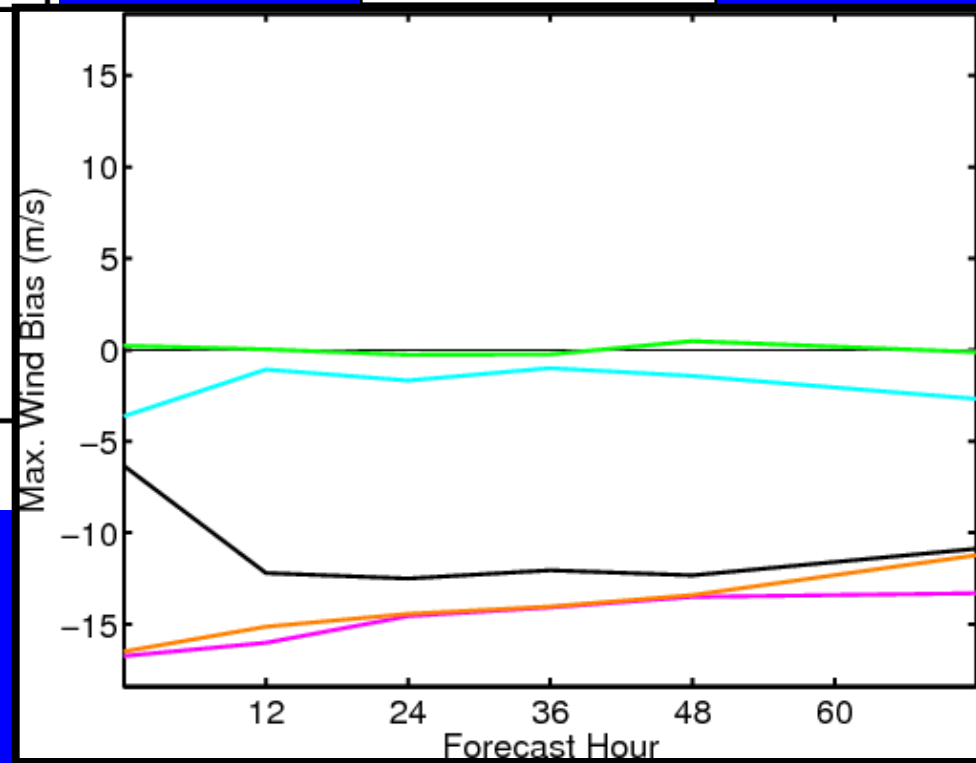
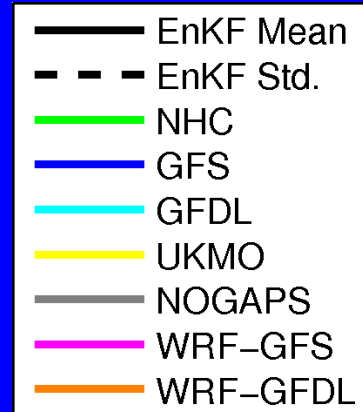
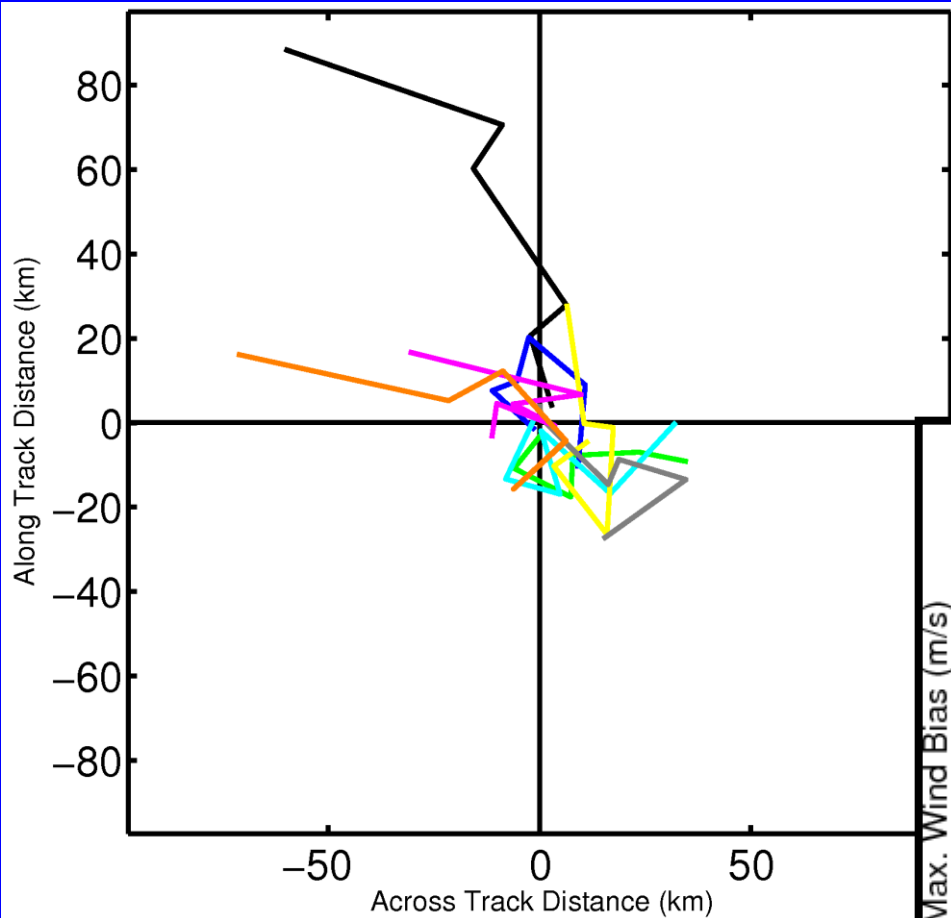


Forecast Errors

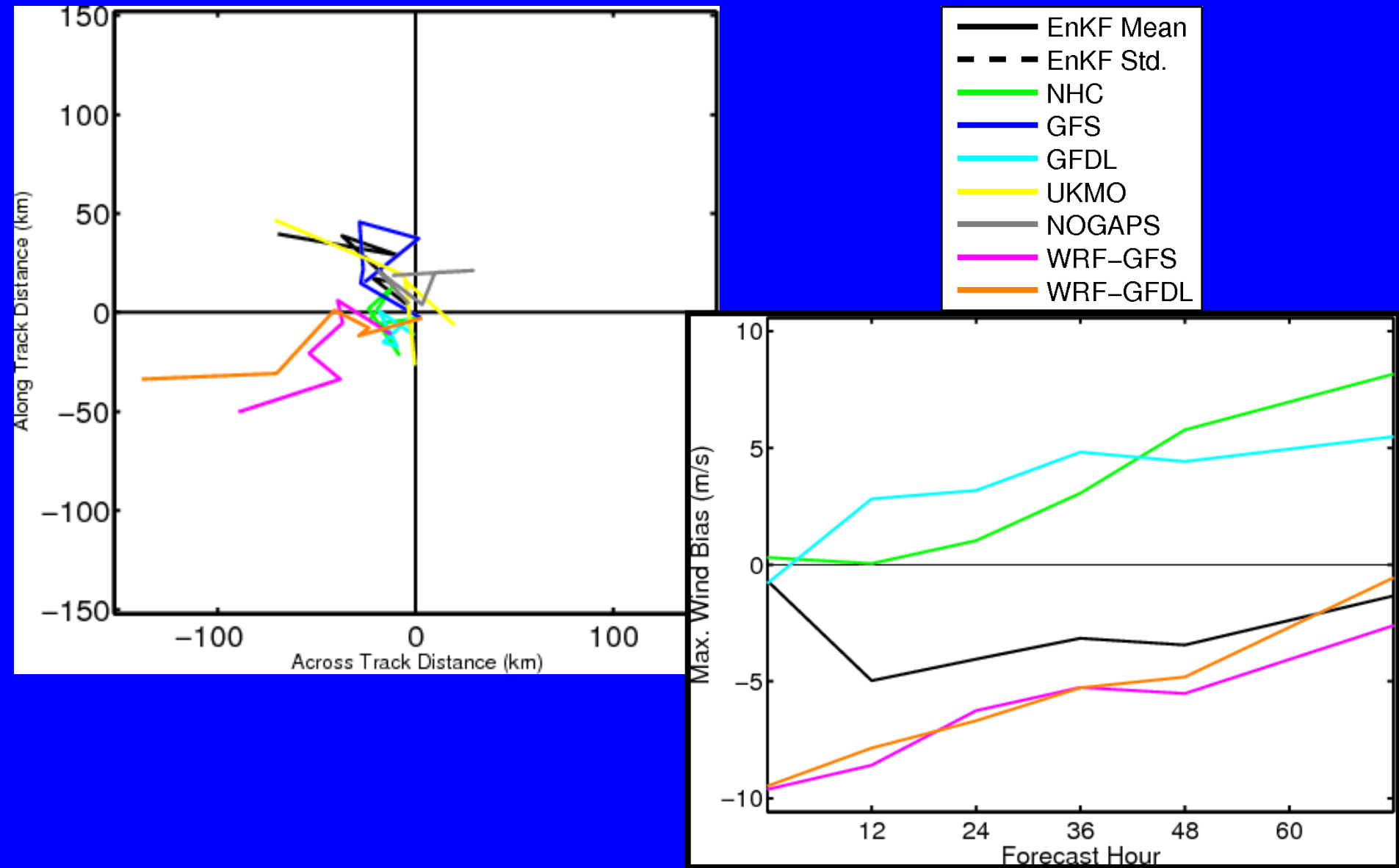


- EnKF Mean
- - - EnKF Std.
- NHC
- GFS
- GFDL
- UKMO
- NOGAPS
- WRF-GFS
- WRF-GFDL

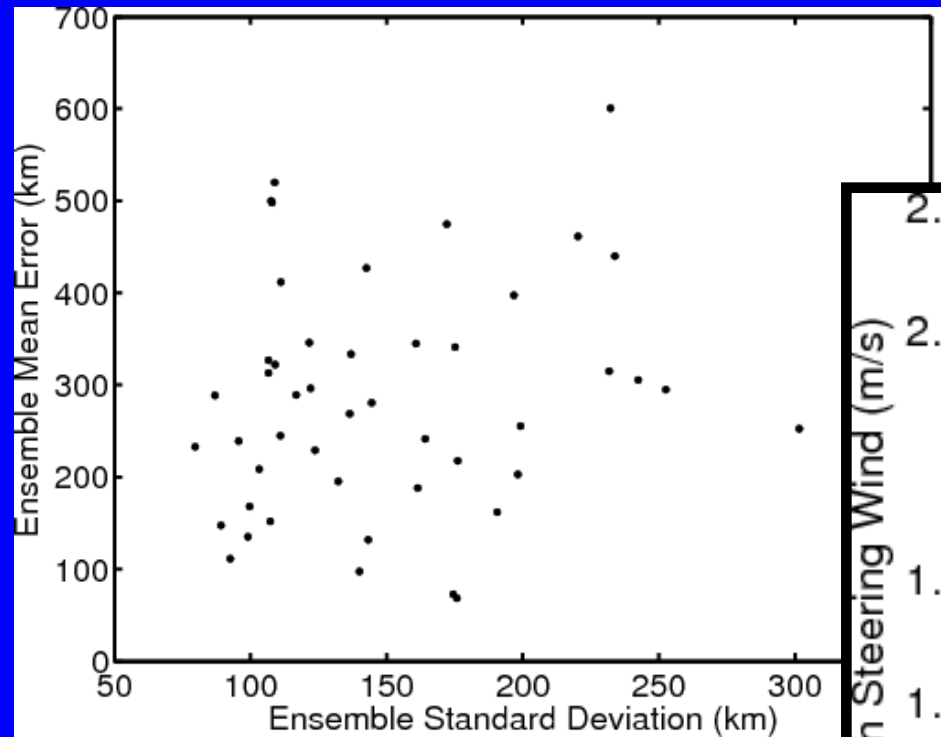
Forecast Biases



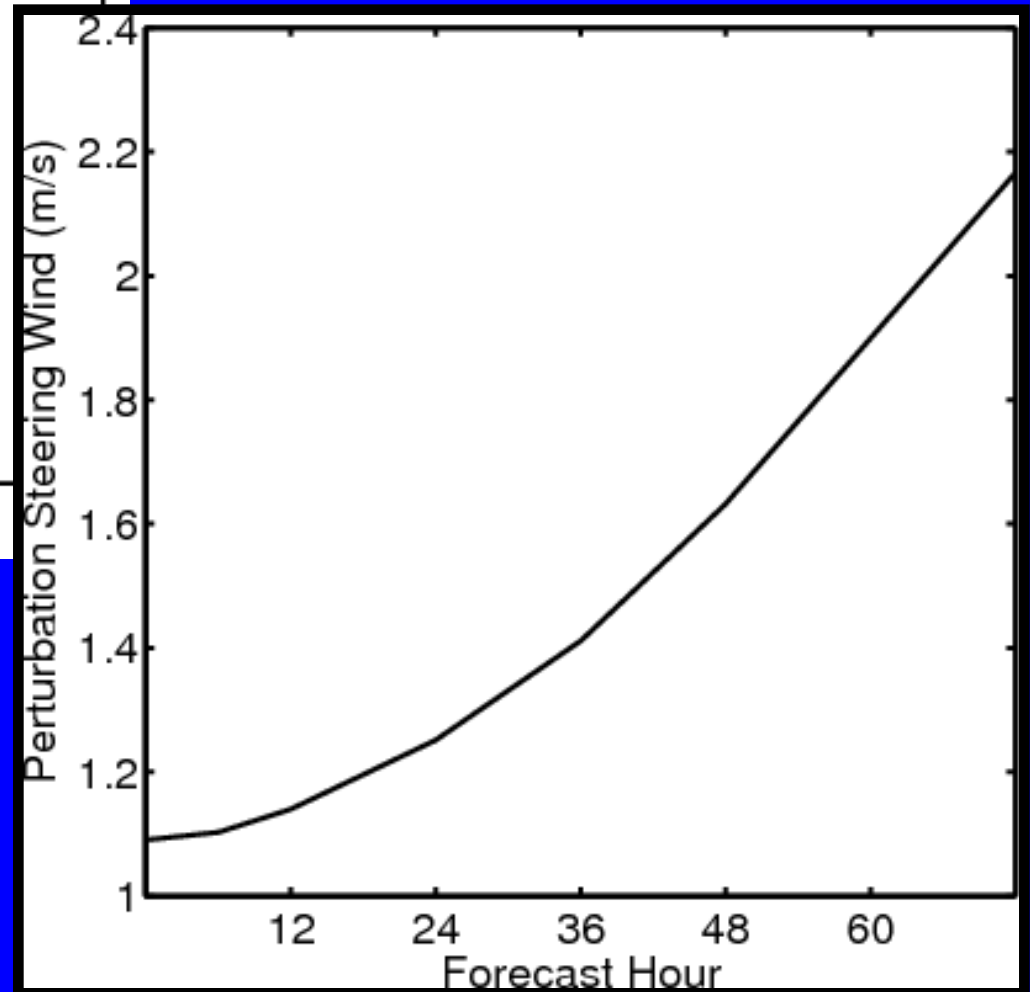
Forecast Biases



Track Error vs. Spread



Asymmetric Wind Magnitude



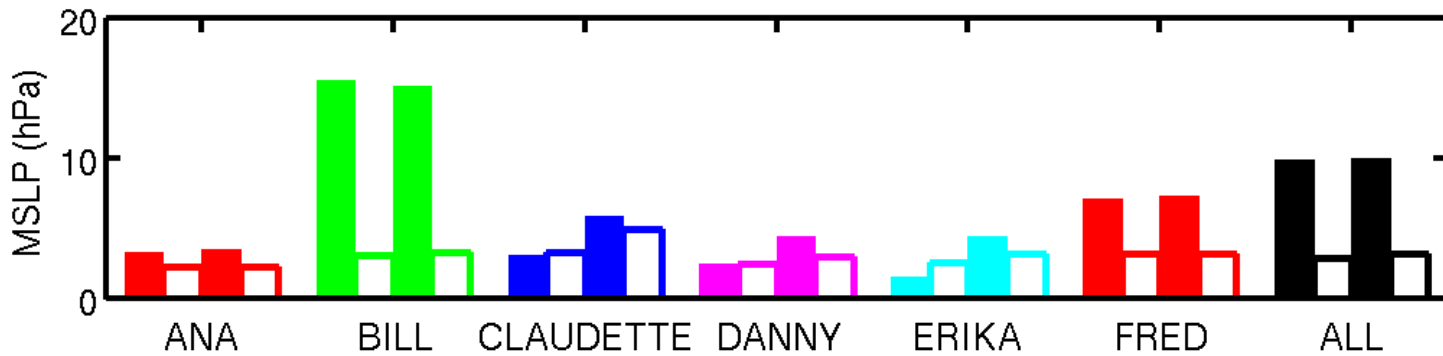
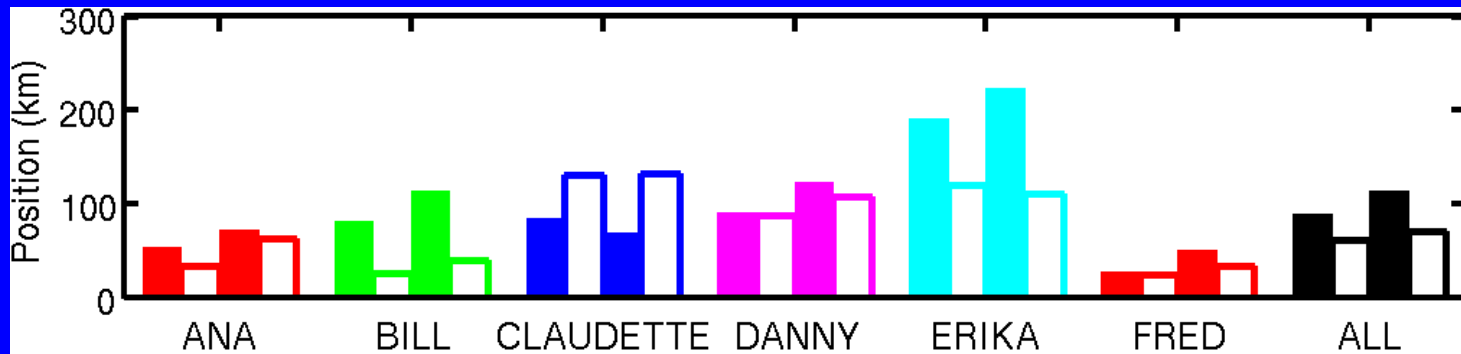
Spread vs. Error

Towards Real-time

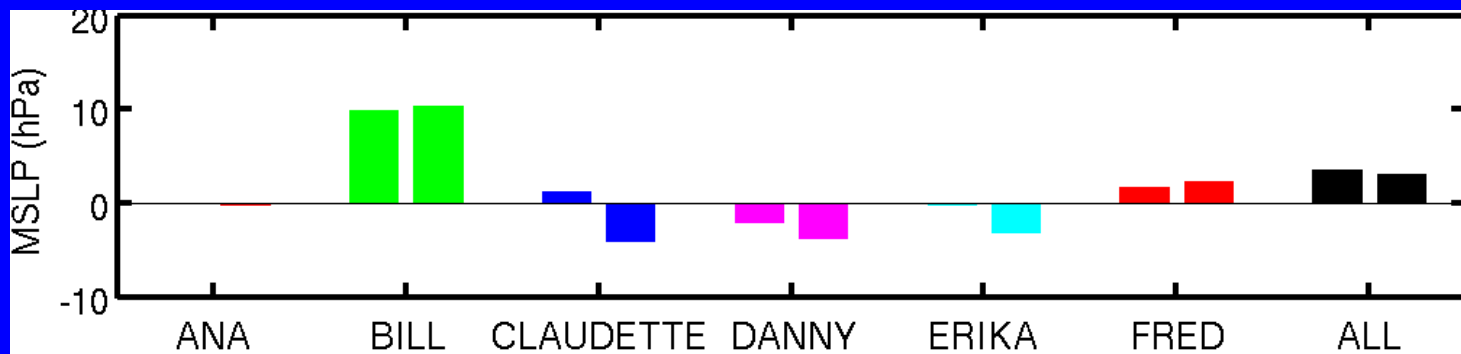
- Given the performance of the high-resolution forecasts, we decided to run a comparable system in real-time during 2009 (tested using 2008 period)
- Initialized on 0000 UTC 10 Aug., captured every storm thus far at genesis
- Run one high-resolution forecast using member that minimizes a cost function involving initial position and intensity

Cycling Errors

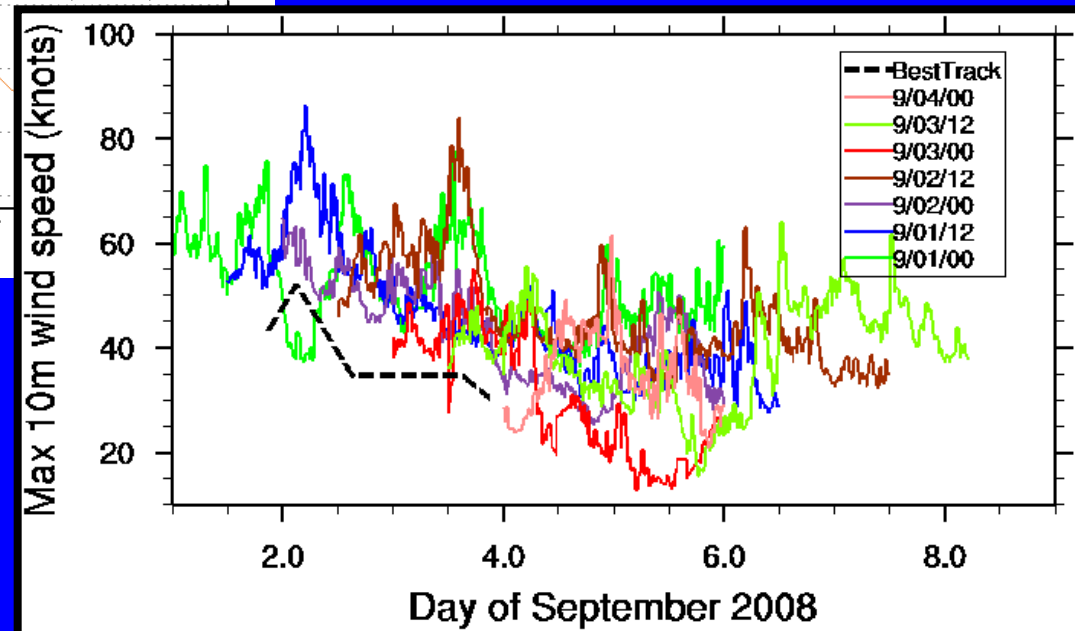
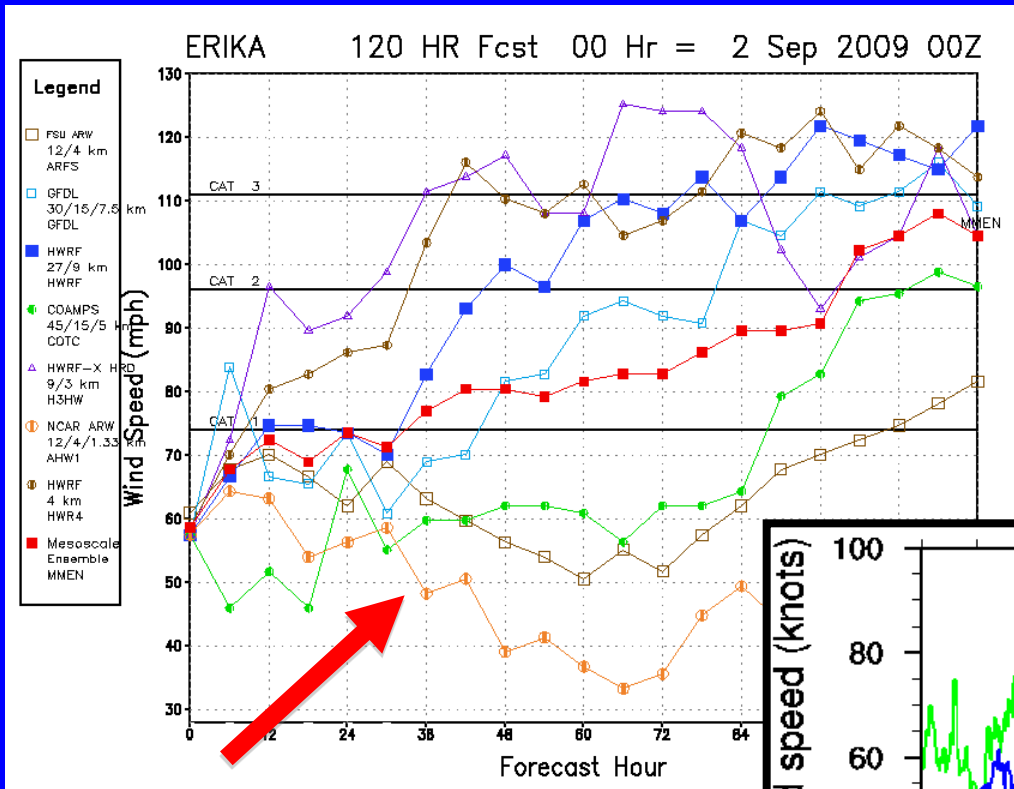
RMS Error



Bias



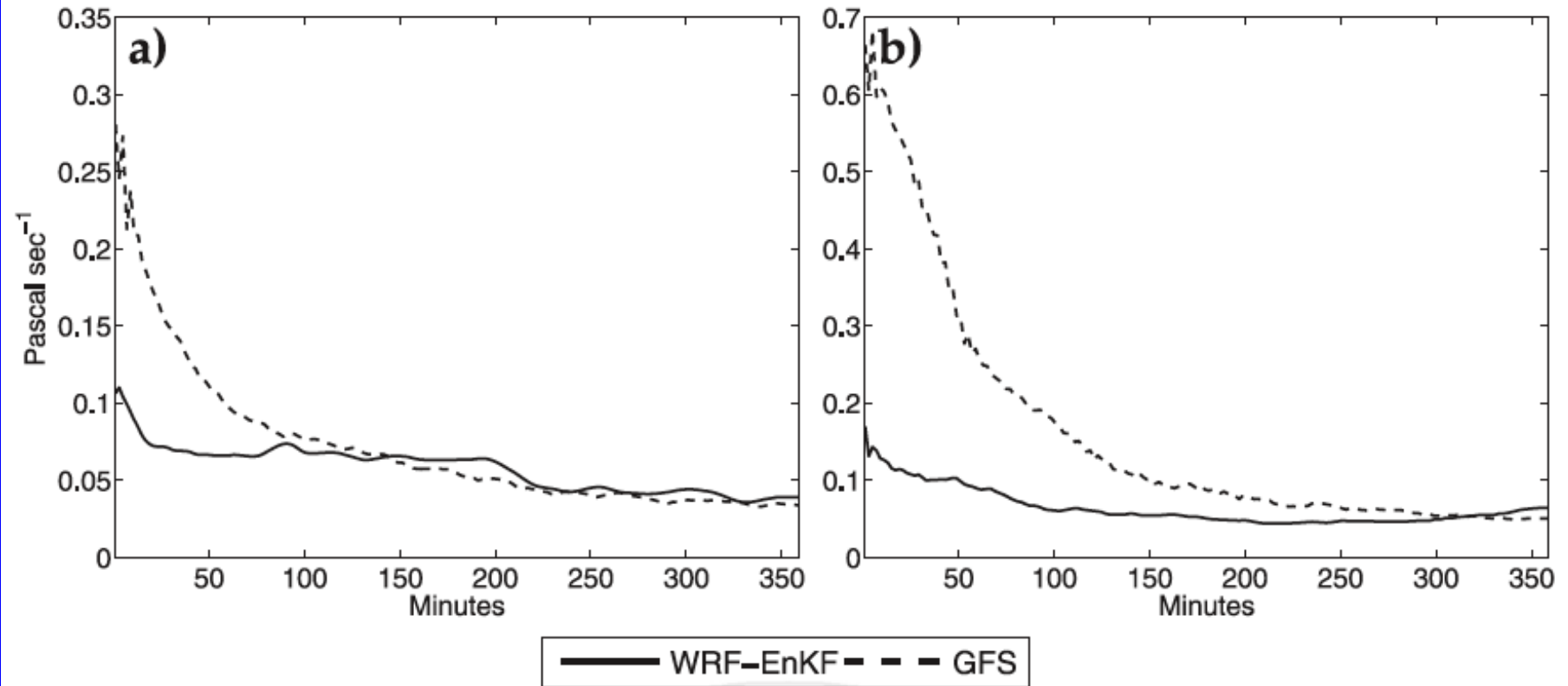
Erika Forecast



Summary

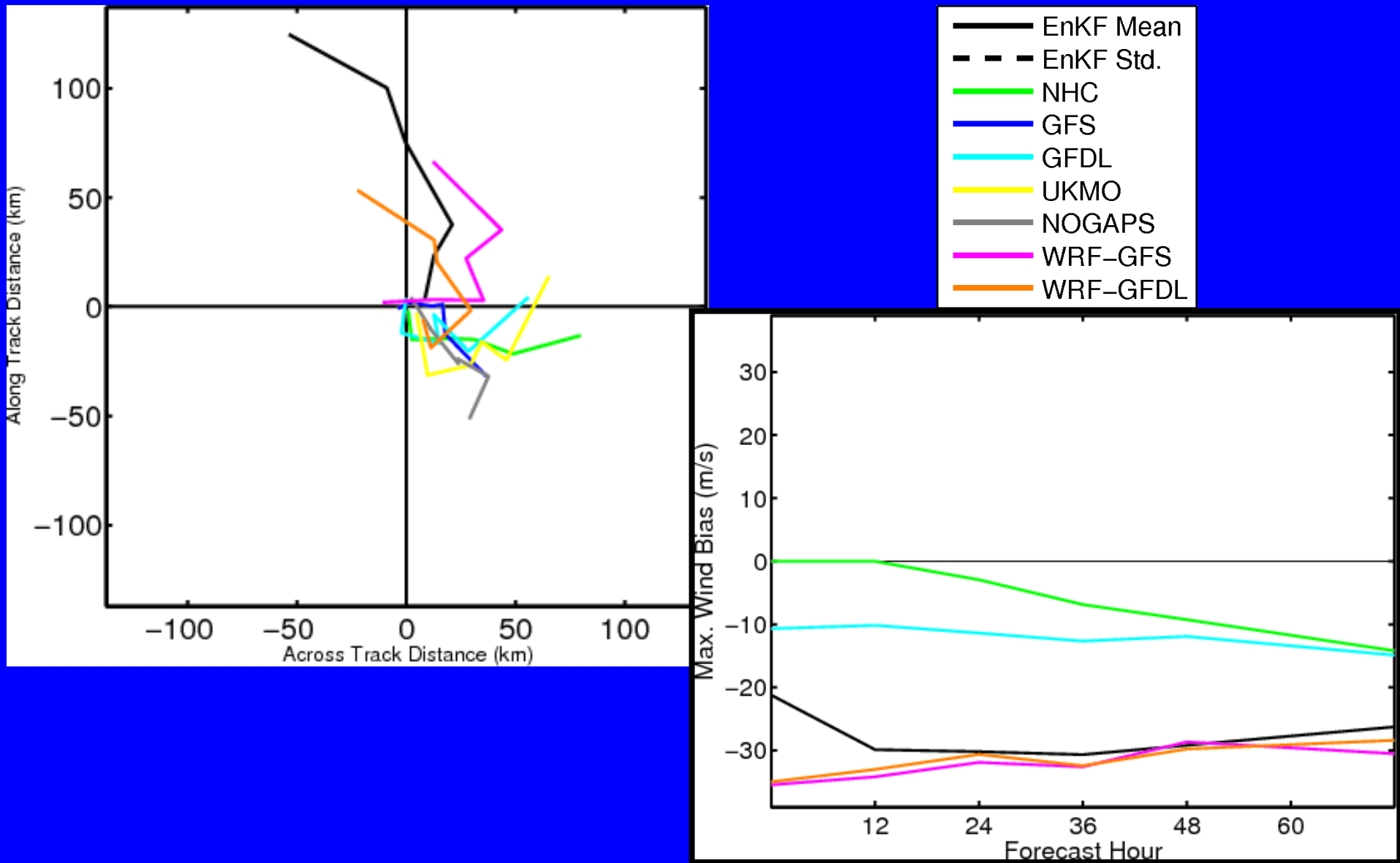
- Ran mesoscale ensemble assimilation system during DTC HRH tests. Focus on generating good analysis of environment, not storm structure
- Track and intensity errors slightly larger than operational models, comparable when statistics computed for weak storms
- Consistent growth in ensemble variance with time (track, intensity, steering wind), though too small
- Real-time convective-resolving forecasts appear to benefit from using EnKF analysis, especially for weak sheared storms (i.e., Ana, Danny, Erika)
- Analysis plots available from MMM WRF site

EnKF Initialization

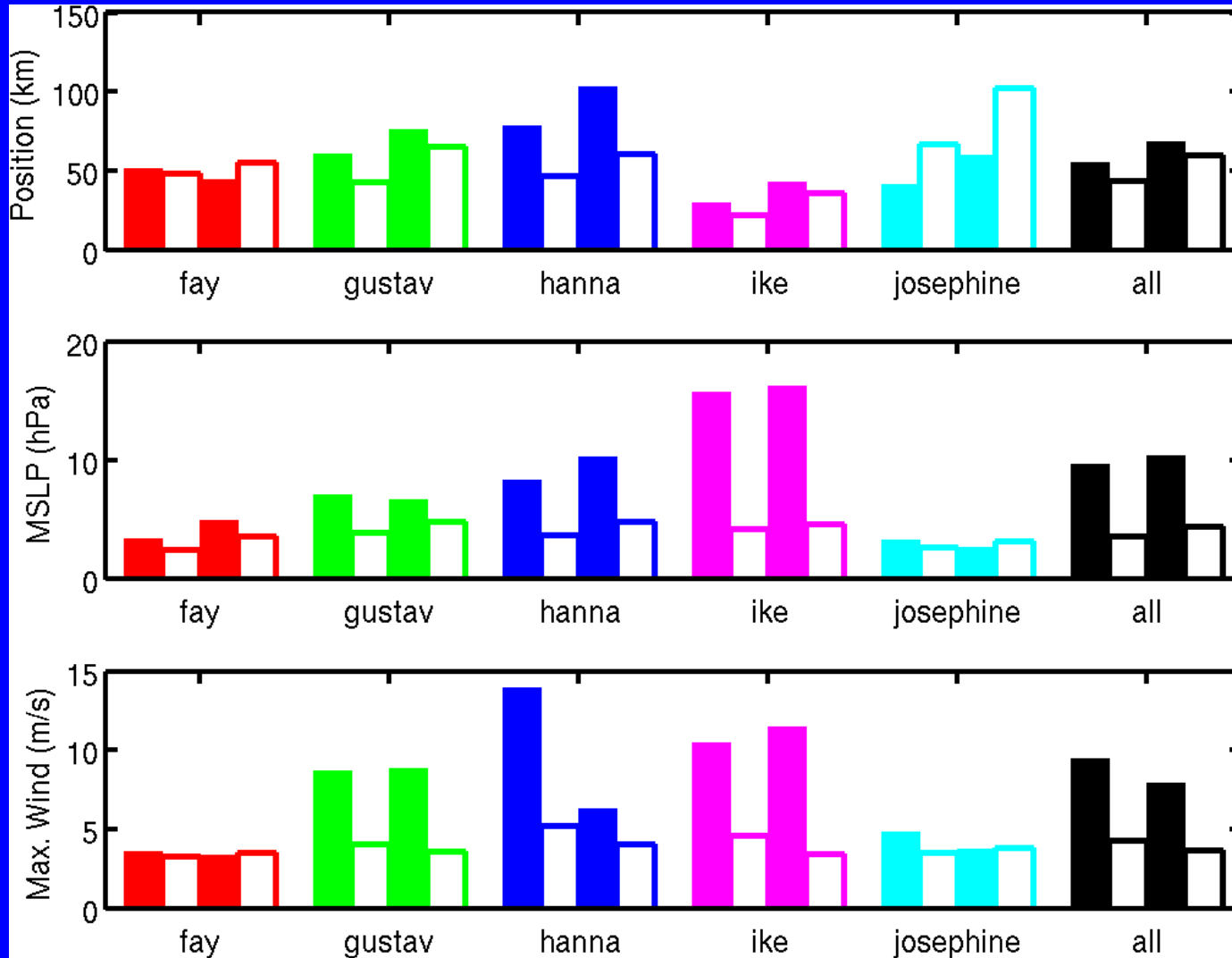


Torn and Hakim (2009) MWR

Forecast Biases



2008 Retrospective Errors



2008 Retrospective Biases

