

# Verification of Eastern Pacific Cloud Forecasts

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# Outline

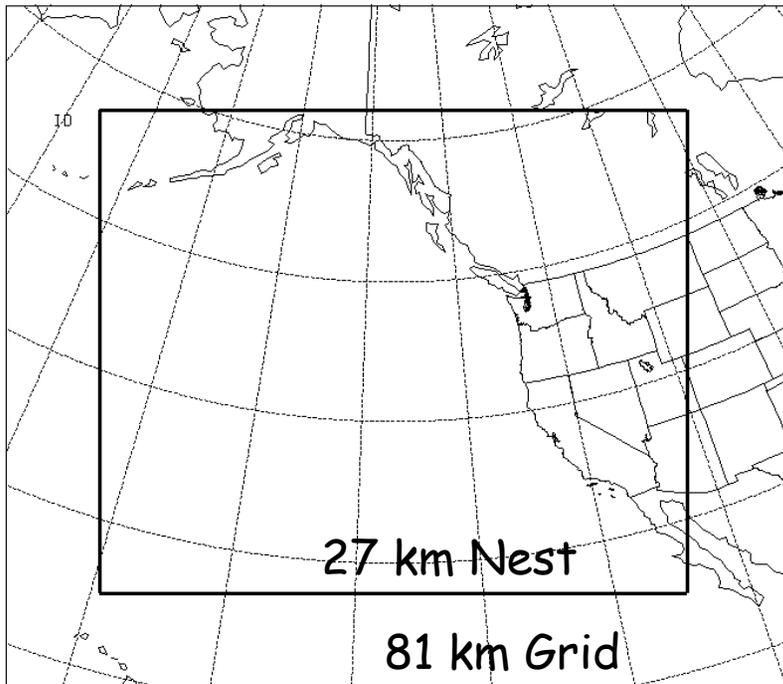
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- Data and methods
- The challenge of cloud verification
- Composite verification
- Fuzzy verification
- Summary

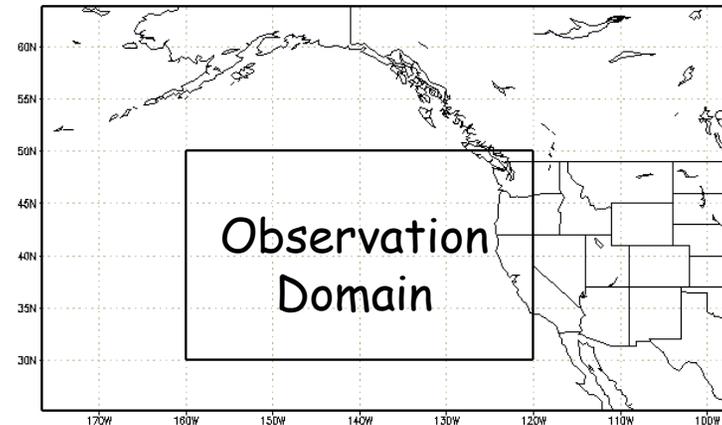
# Forecast and Data Overview

## Operational COAMPS® Forecasts



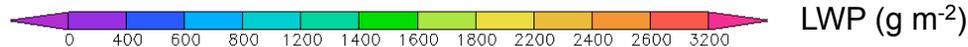
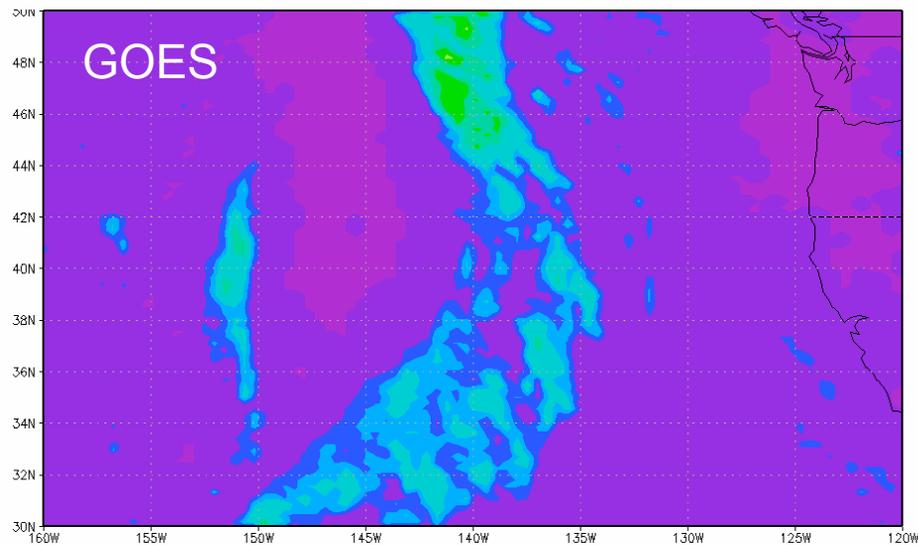
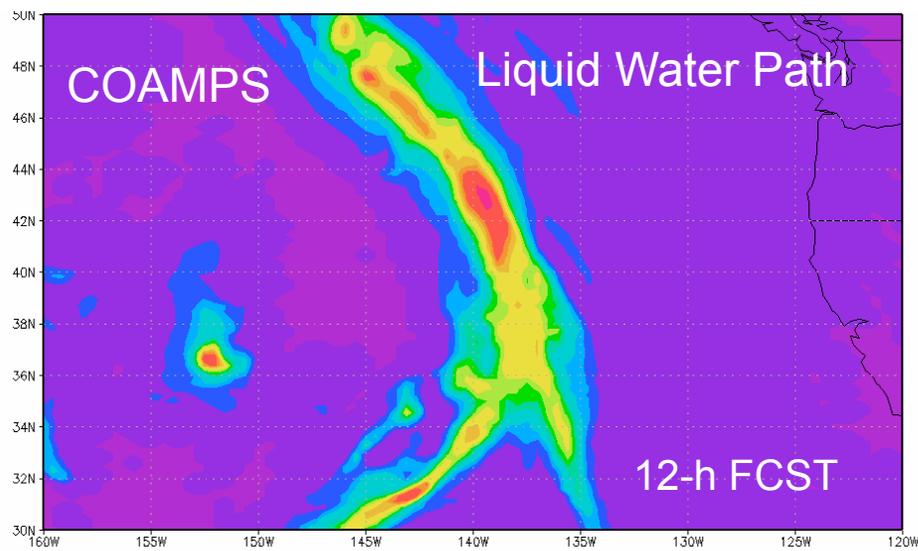
- 30 levels
- 6-hour data assimilation cycle using NAVDAS 3-D Var
- Microphysics based on Rutledge and Hobbs
- Kain-Fritsch cumulus parameterization

## Observations

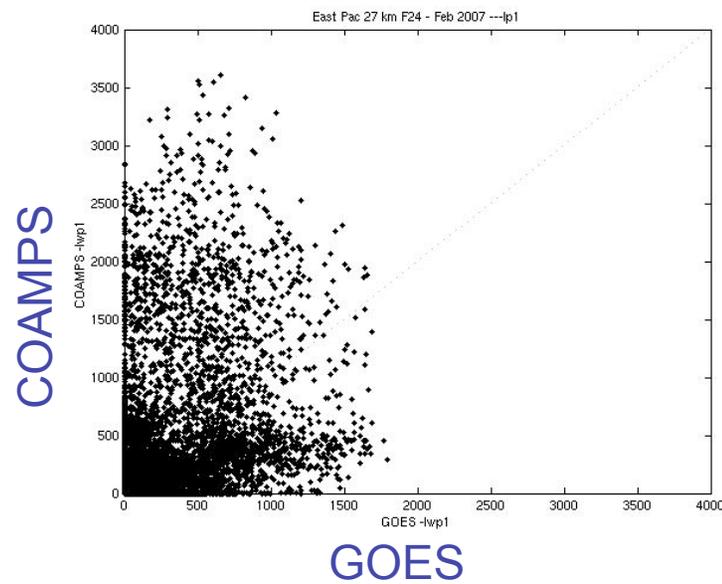


- GOES satellite retrievals
  - Cloud top temperature
  - Cloud top height (based on NOGAPS) temperature profile
  - Liquid (includes ice) water path (daylight hours only)
  - Cloud type
- Subset area of forecast grid
- 4 km footprint interpolated to forecast grid
- Bias calibration performed
- Scores derived for Feb-May 2007

# Is this a good Forecast?

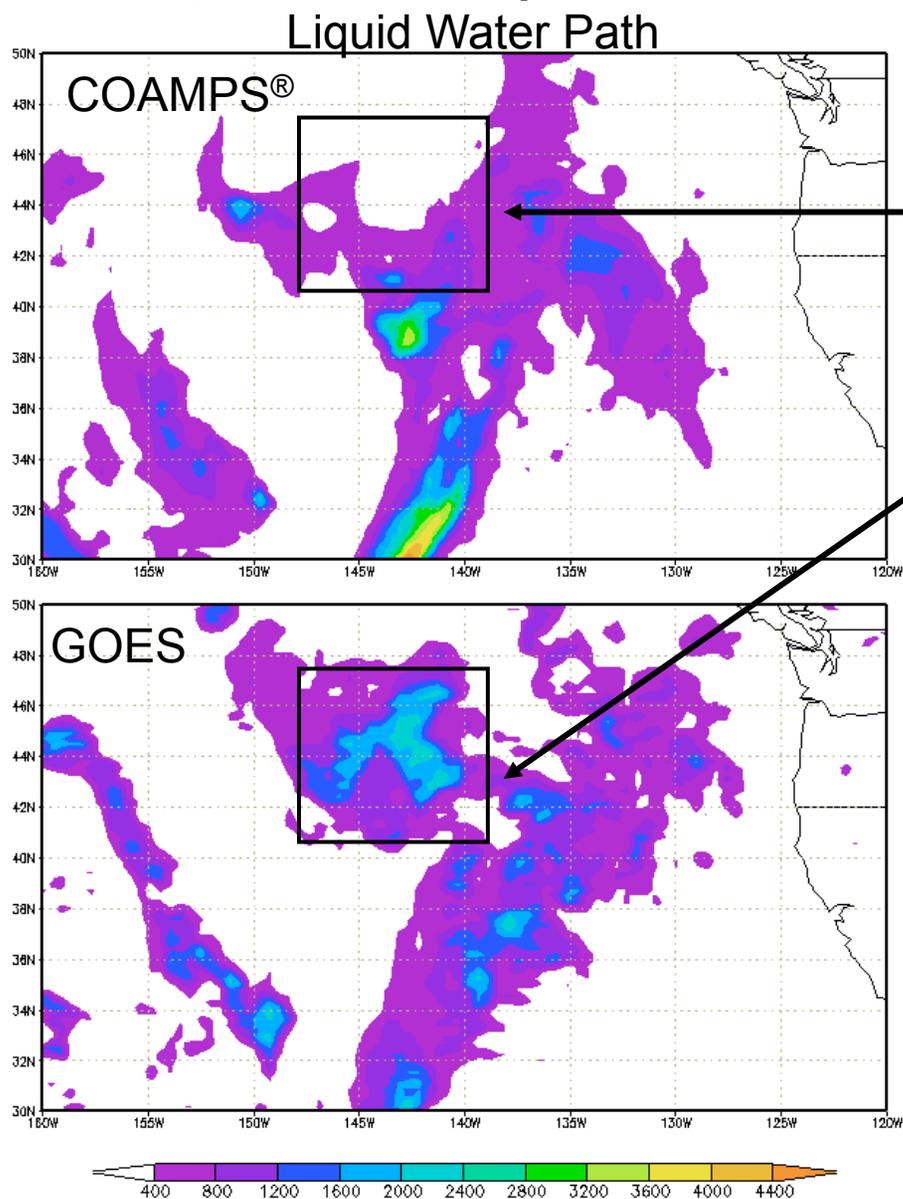


## Point-to-Point Comparison



- General features well positioned
- Positive model bias
- Spatial error correlation not measured
- How to quantify this?

# Composite (Event-based) Verification



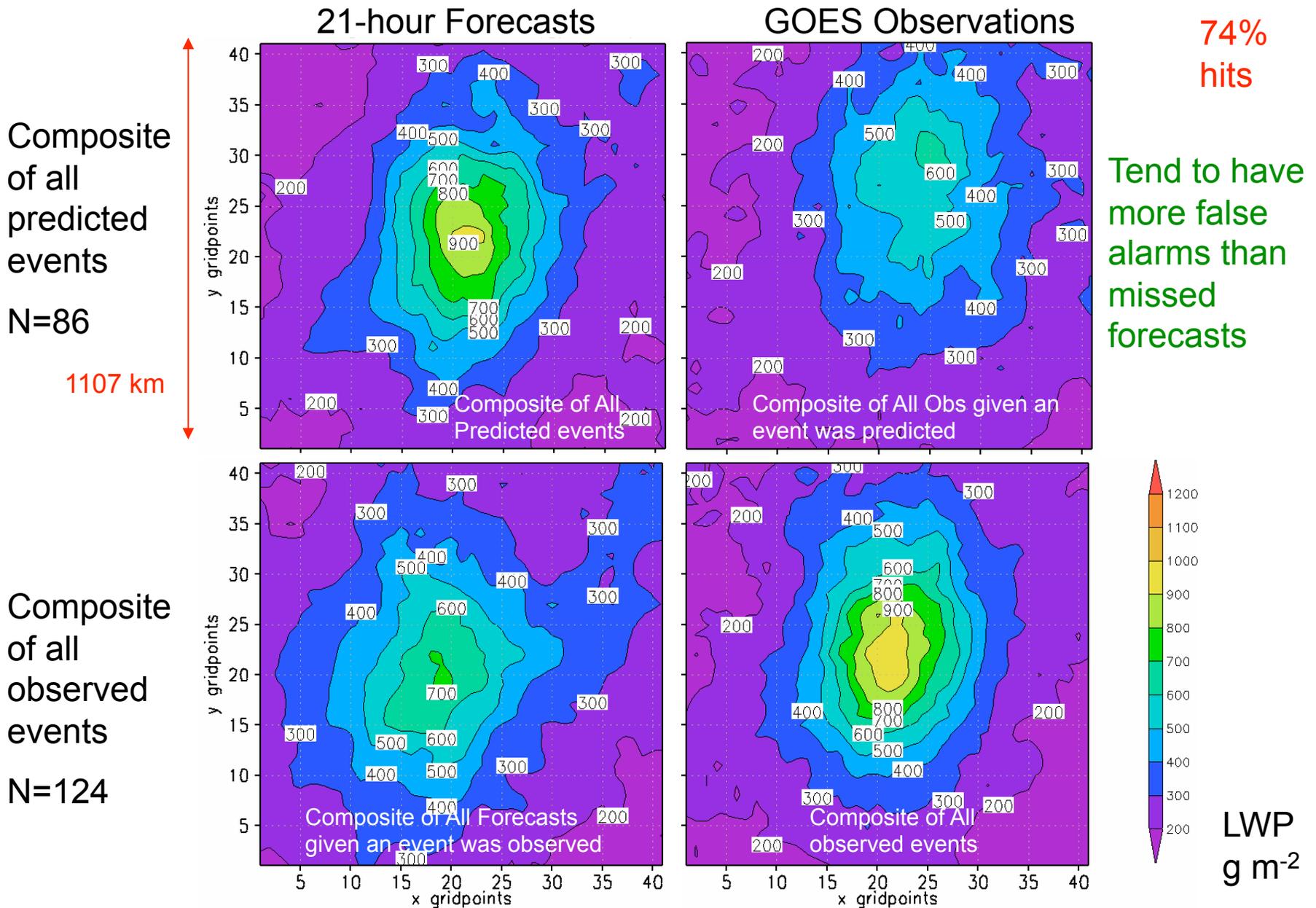
## Event Statistics

- Collect samples of multiple events of similar scale
- Investigate systematic forecast errors

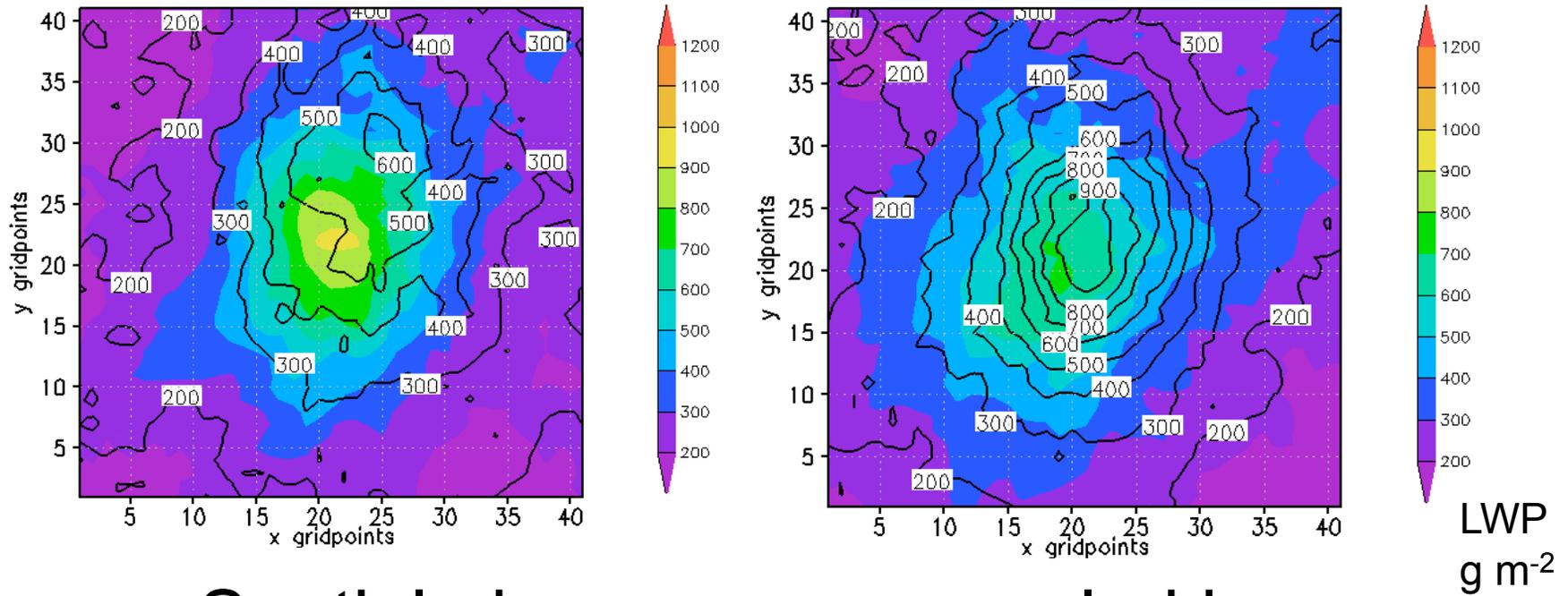
## Method:

- Identify events of interest
  - all events with  $LWP \geq 500 \text{ g m}^{-2}$
  - 100-600; 600-3000 points
- Composite all predicted events
- Composite all observed events

# Small (~350 km) Events LWP $\geq 500$ g m<sup>-2</sup>

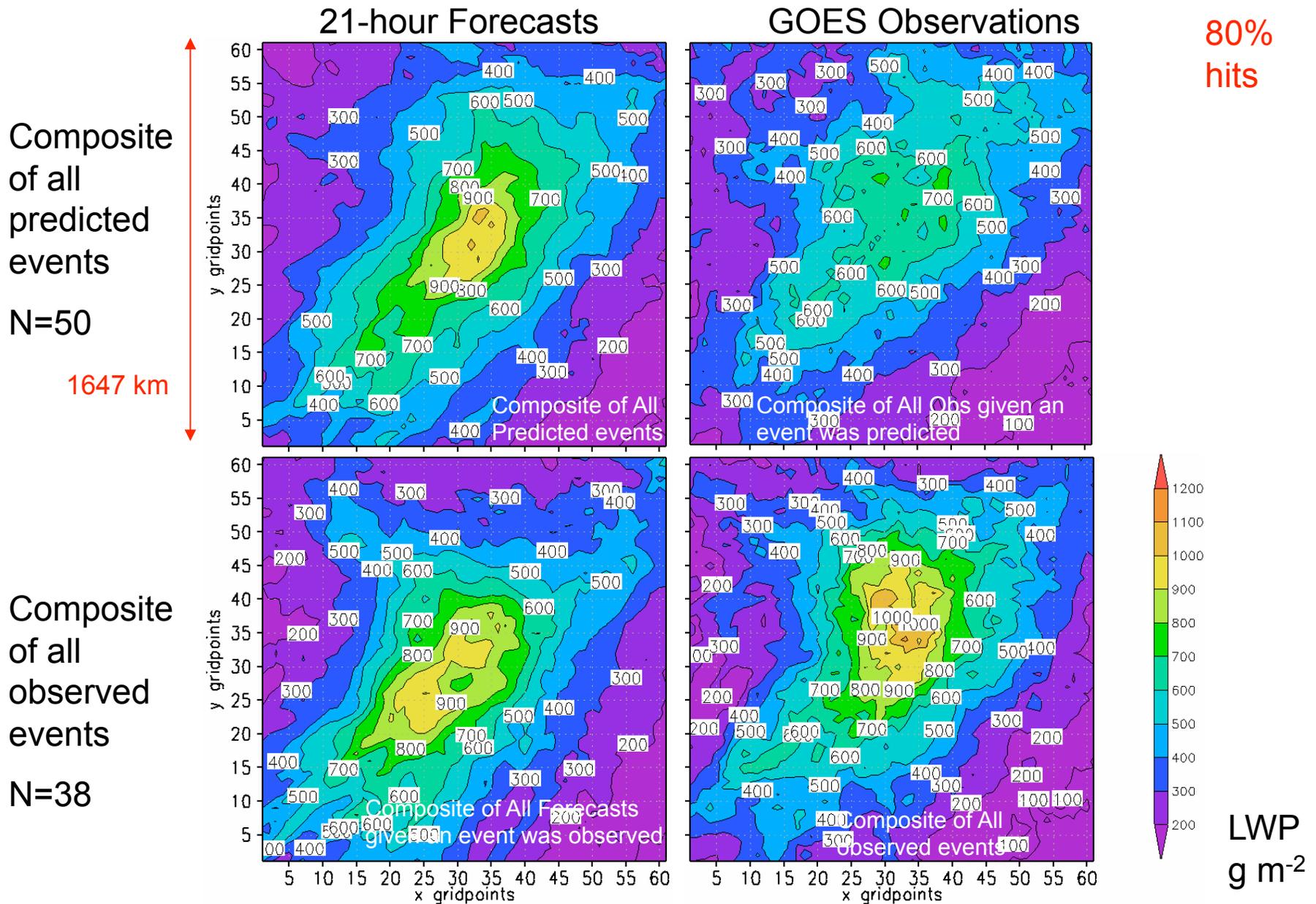


# Small (~350 km) Events $LWP \geq 500 \text{ g m}^{-2}$



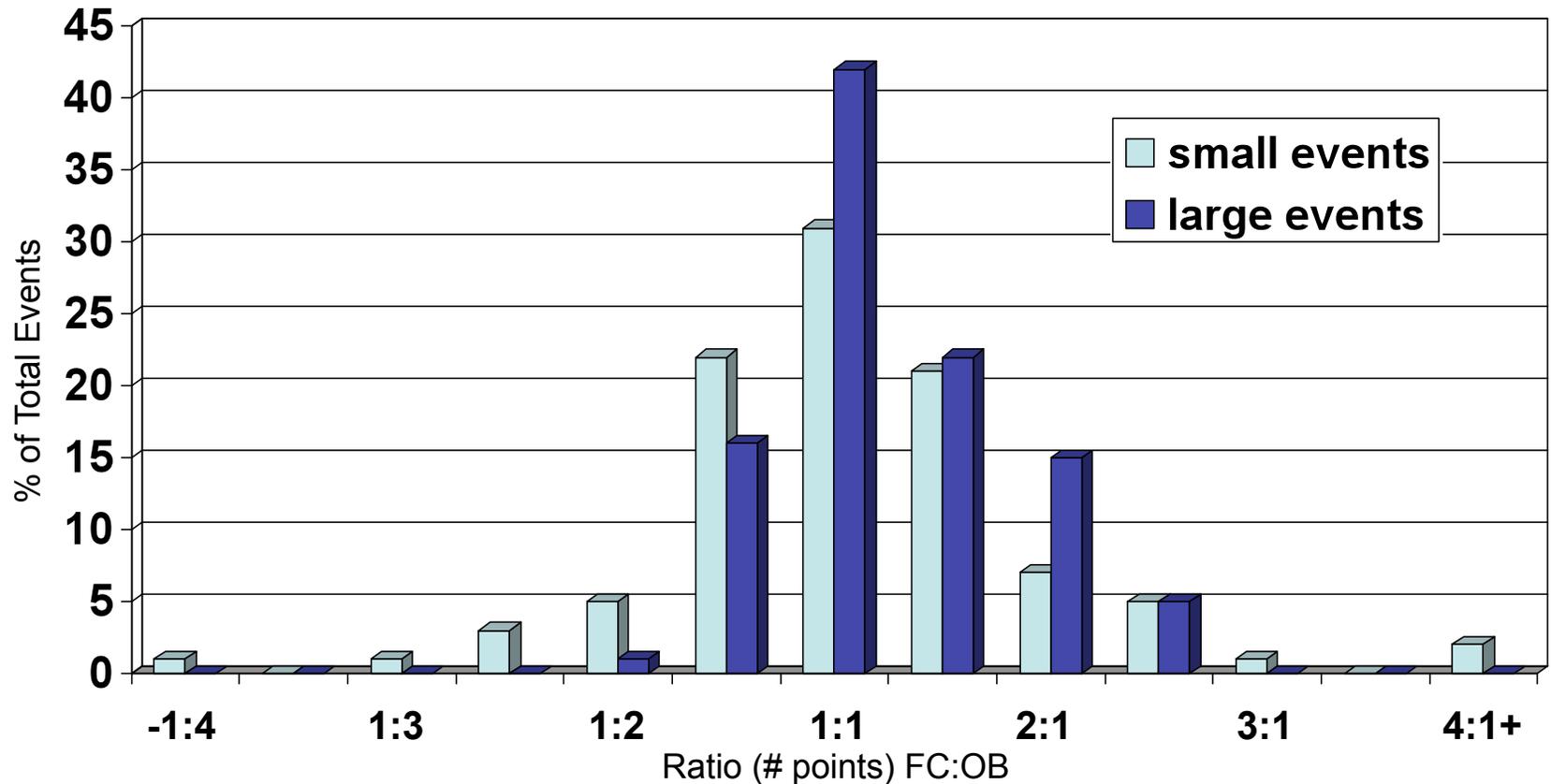
- Spatial phase errors revealed by overlaying distributions
- Must display predicted and observed events separately

# Large (~1000 km) Events LWP $\geq 500$ g m<sup>-2</sup>



# Percentage of Events with Given Fcst:Obs Ratios

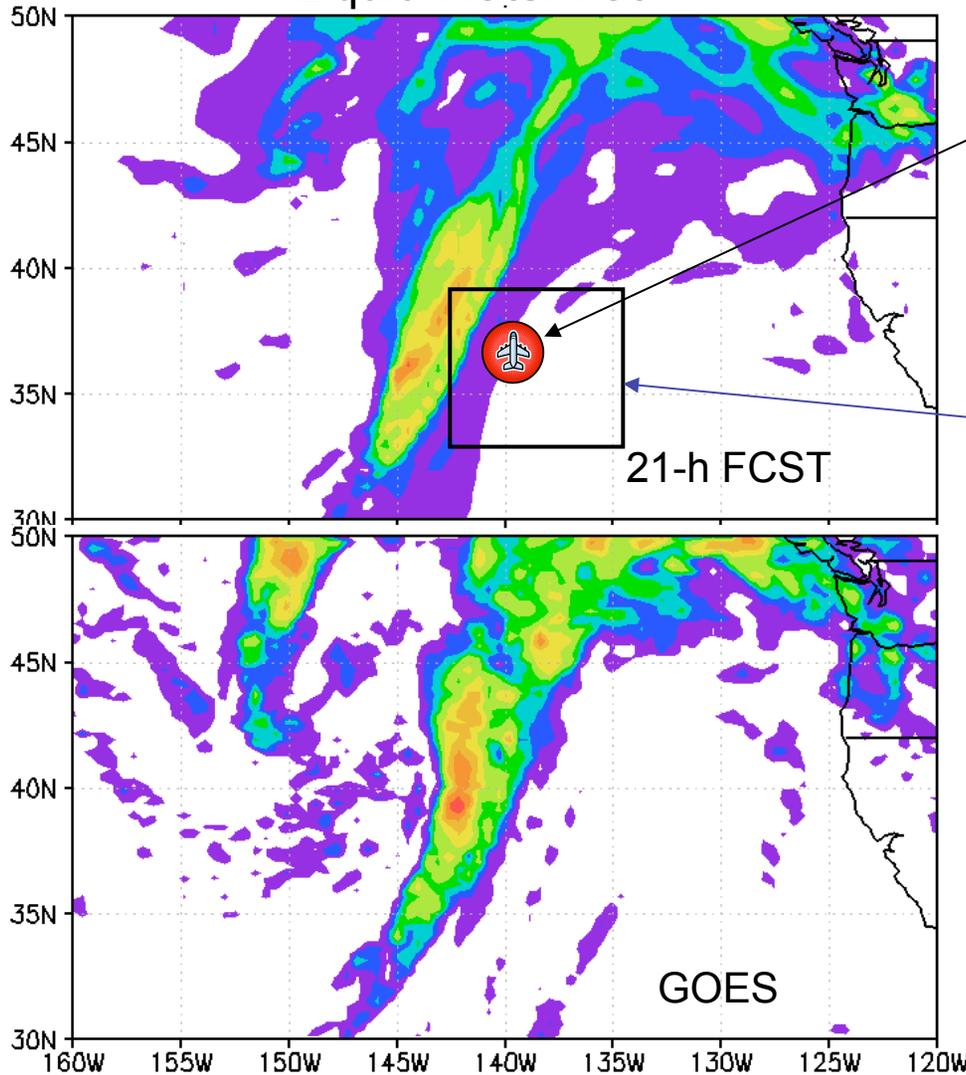
Feb-May 2007



← Under-forecasts (too few deep clouds)      Hits (Fcst similar to obs) 80% LG; 74% SM      Over-forecasts (too many deep clouds) →

# Quantifying Uncertainty

Liquid Water Path



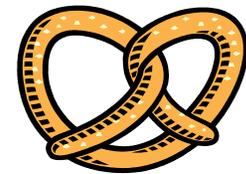
We want to go here

And avoid the front

But we're flexible...

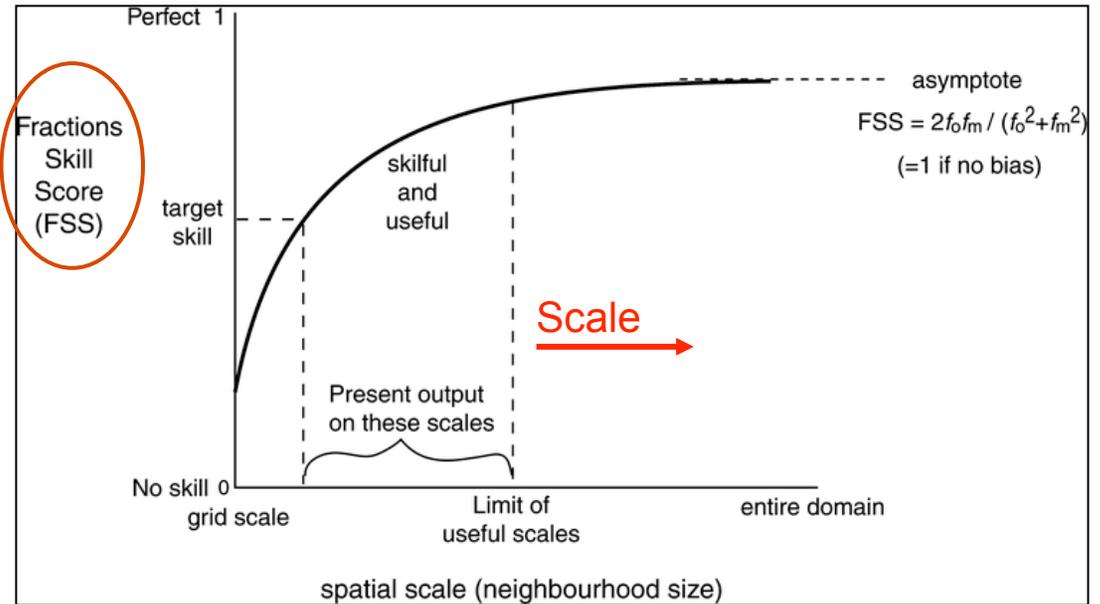
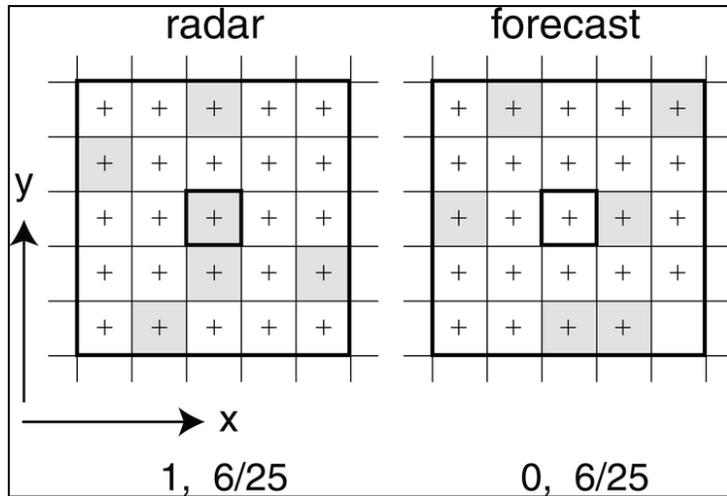
Because the forecast is not perfect

How flexible do we need to be?



# Fuzzy Neighborhood Method

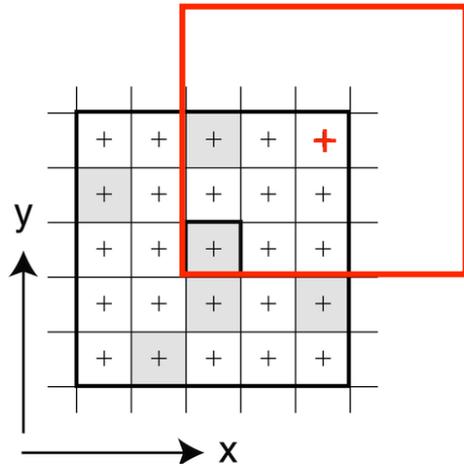
From Roberts and Lean (2008)



- Use threshold to create a binary field.
- Calculate Fractions Skill Score.
- $FSS=1$  (perfect) when forecast coverage=obs coverage.

# Fuzzy Neighborhood Method

A Few Caveats



$$FSS_{(n)} = 1 - \frac{MSE_{(n)}}{MSE_{(n)ref}}$$

$$MSE_{(n)} = \frac{1}{N_x N_y} \sum_{i=1}^{N_x} \sum_{j=1}^{N_y} (O_{(n)i,j} - M_{(n)i,j})^2$$

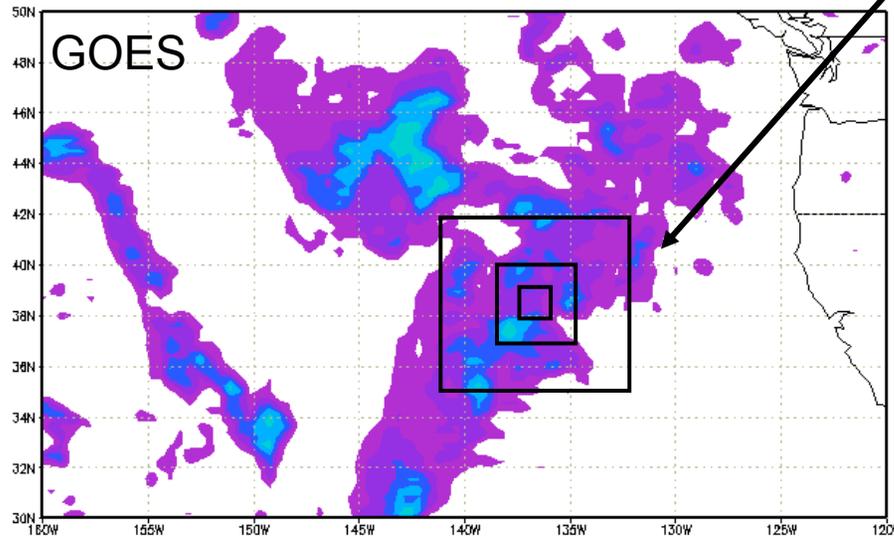
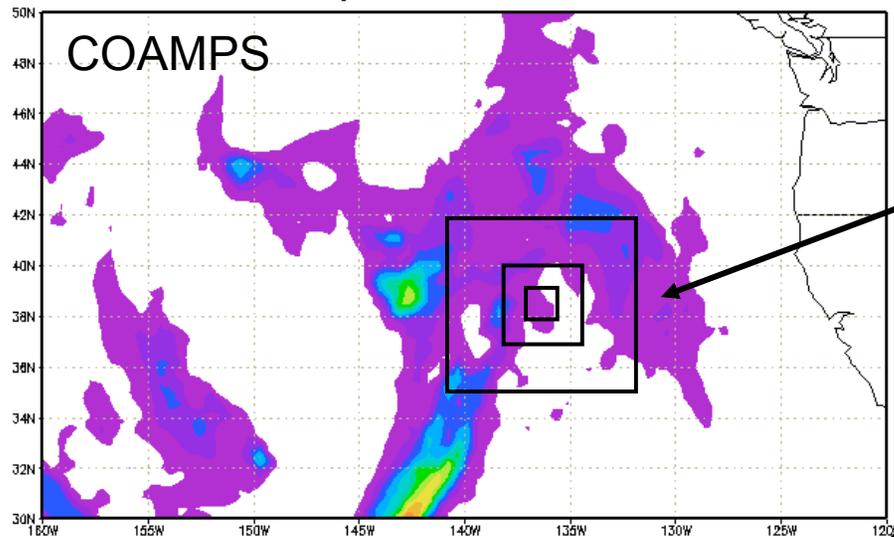
$$MSE_{(n)ref} = \frac{1}{N_x N_y} \left[ \sum_{i=1}^{N_x} \sum_{j=1}^{N_y} O_{(n)i,j}^2 + \sum_{i=1}^{N_x} \sum_{j=1}^{N_y} M_{(n)i,j}^2 \right]$$

- Large scale samples exceed grid bounds
- May cause aliasing

- Reference MSE not a true climatology
- Changes with each forecast
- Positive bias leads to large  $MSE_{ref}$  and improved FSS

# Calculating Scale-Dependent Scores

## Liquid Water Path



## Fuzzy Statistics

- Collect samples at all points at multiple scales
- Determine the smallest scale to possess an acceptable error

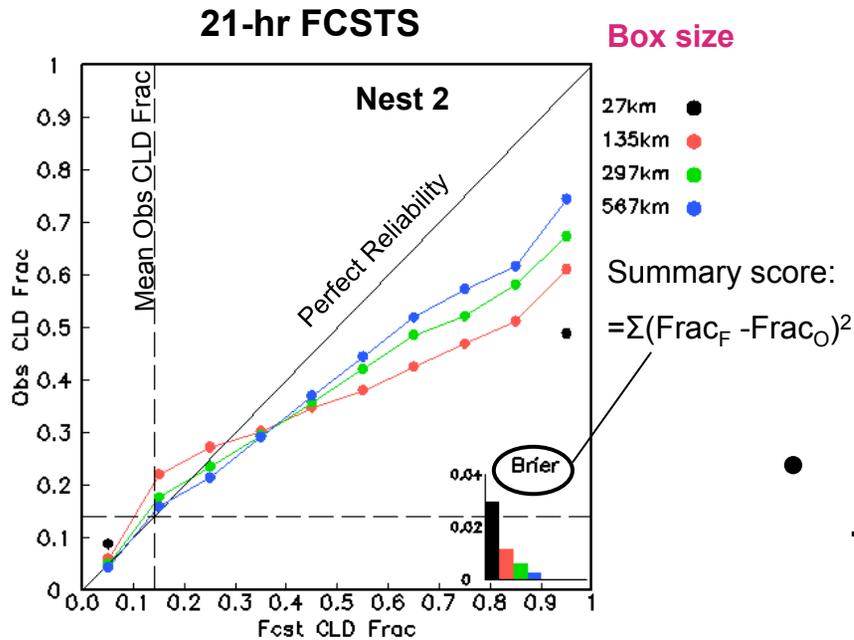
## Method:

- Identify a threshold of interest
  - $LWP \geq 500 \text{ g m}^{-2}$
- Create binary field based on the threshold
- Examine the observed and predicted fractional coverage at each scale

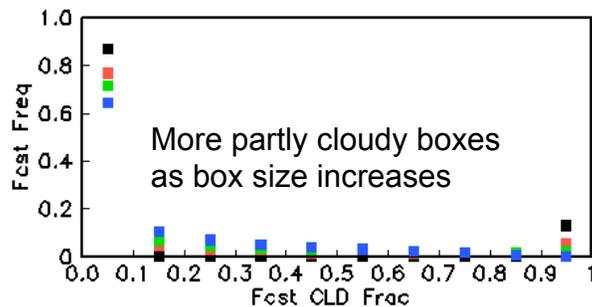
Roberts and Lean (2008)

# Forecast Uncertainty

## Scale-Based Statistics



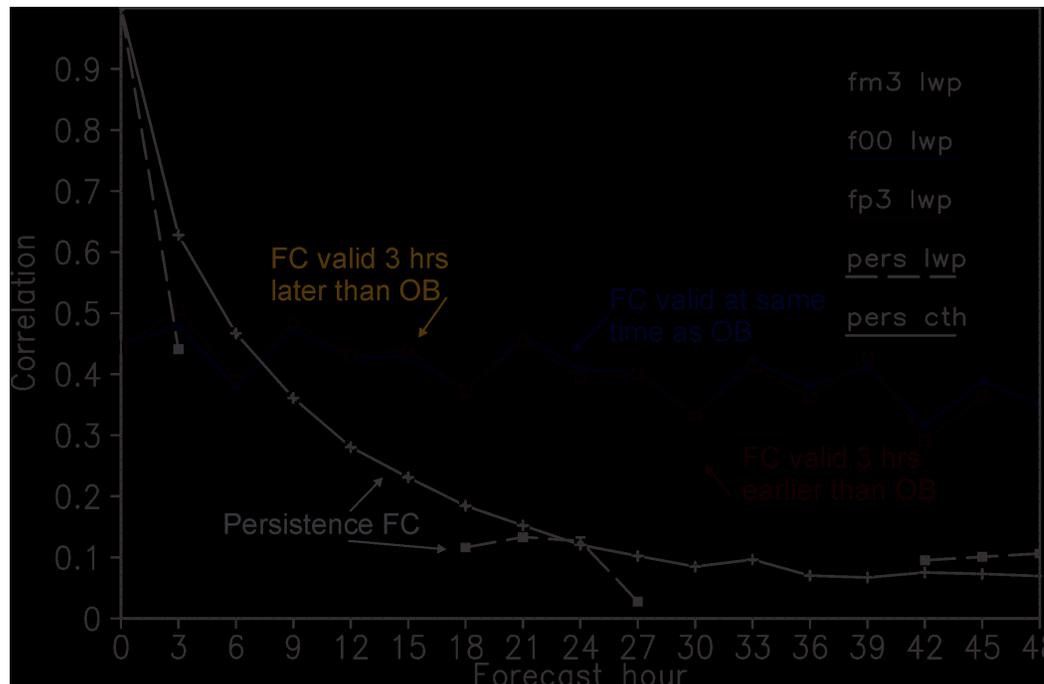
Results are best plotted using reliability diagrams.



- Compute average cloud fractions over increasingly large areas.
- Forecasts for large areas are more reliable but less spatially certain.

# Timing Errors

LWP Correlations (Feb-Oct 2007)



- Compute lagged correlations at varying lead times
- Highest correlations indicate best agreement
- Similar to Ebert and McBride (2000) CRA method
- Could also use MSE

- +3 hr lag Fcst almost as good as 0 hr due to phase errors
- Model beats persistence after ~ 6-9 hours

# Summary

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- The characterization of mesoscale uncertainty is a challenging problem.
- Traditional methods do not account for spatial error correlation.
  - Good forecasts can have large errors.
  - Low spatial error correlations are desired.
- Composites provide useful performance information.
  - Focused on specific events.
  - Hard to characterize the entire forecast.
- Fuzzy verification provides useful statistical information.
  - Entire forecast solution is characterized.
  - Uncertainty is quantified over a range of scales.
  - Threshold value is required.