

HWRF v3.9a Tutorial
24 January 2018 College Park, MD

Python Scripts in HWRF

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Many slides contributed by
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Outline

- Resources for Users
- System design
- Object-oriented programming basics
- Configuring HWRF
- Data communication
- Logging

Resources for Users

User webpage

Documentation

Doxygen website

Python website

User support webpage

HURRICANE WRF USERS PAGE

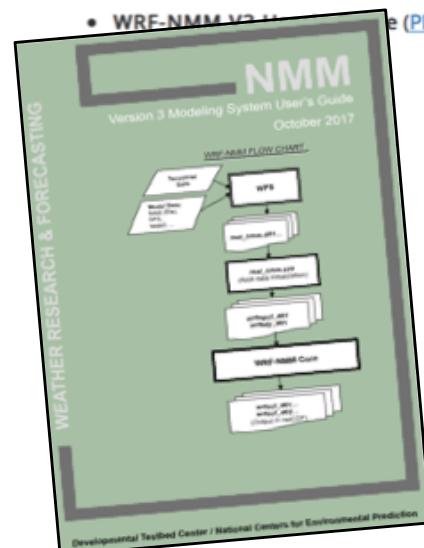
- Home
- Terms of Use
- Overview
- User Support ►
- Downloads ►
- Documentation**
- Idealized
- Tutorials & Workshops ►
- Testing and Evaluation
- HWRF Developers Info
- Additional Links

WRF FOR HURRICANES DOCUMENTS AND PUBLICATIONS

Hurricane WRF Documents

HWRF Documents

- 2017 Documents (for HWRF v3.9a release)
 - HWRF Users' Guide v3.9a ([PDF](#))
 - HWRF Scientific Documentation - October 2017 ([PDF](#))
 - WRF-NMM V3 User's Guide ([PDF](#))
- 2016 Documents (for HWRF v3.8a release)
 - HWRF Users' Guide v3.8a ([PDF](#))
 - HWRF Scientific Documentation - November 2016 ([PDF](#))
 - WRF-NMM V2 User's Guide ([PDF](#))



Community HWRF Users' Guide v3.9a

October 2017

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EVENTS

AMS 2018 NWP using Docker Containers

01.06.2018 to 01.06.2018
Location: AMS Annual Meeting in Austin, TX

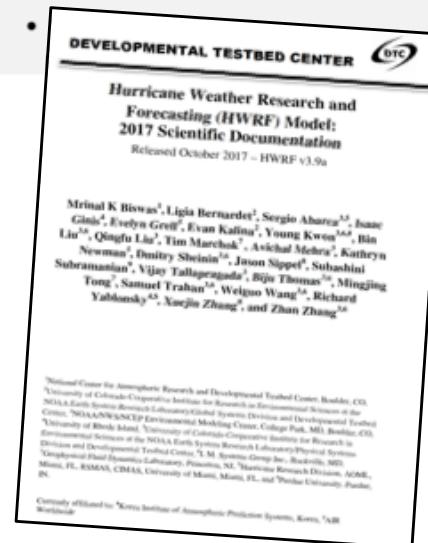
2018 Hurricane WRF Tutorial

01.23.2018 to 01.25.2018
Location: College Park, MD

ANNOUNCEMENTS

- 23-25 January 2018

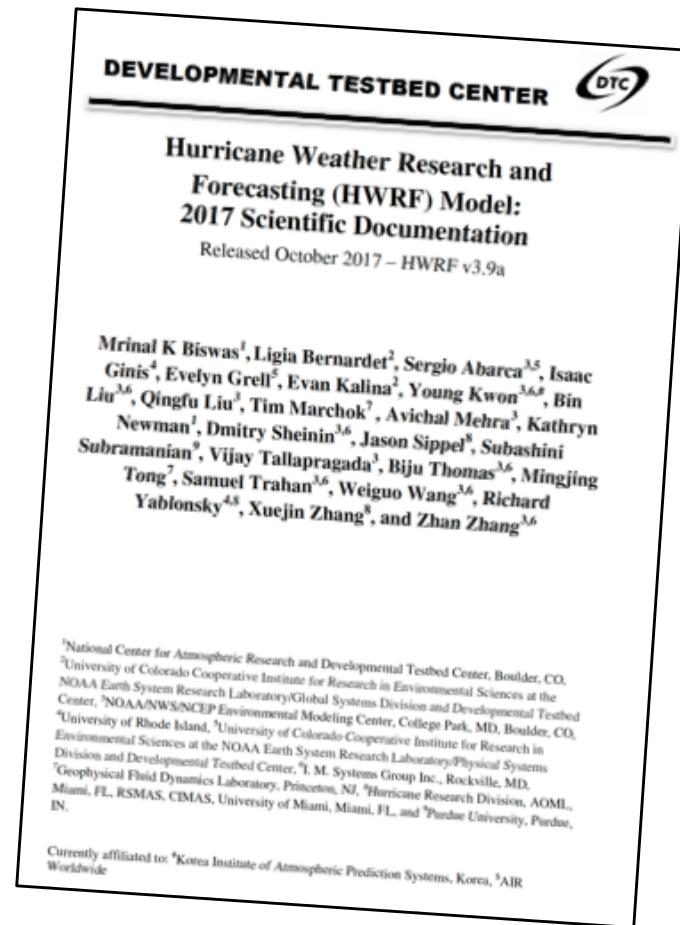
[Hurricane WRF Tutorial](#)



Scientific Documentation

- Technical information covering each HWRF component
 - Authorship includes developers and experts
 - Chapters covering:
 - HWRF introduction
 - HWRF Initialization
 - MPI POM-TC
 - Physics Packages in HWRF
 - Design of moving nest
 - Use of GFDL Vortex Tracker
 - The idealized HWRF framework

https://dtcenter.org/HurrWRF/users/docs/scientific_documents/HWRFv3.9a_ScientificDoc.pdf



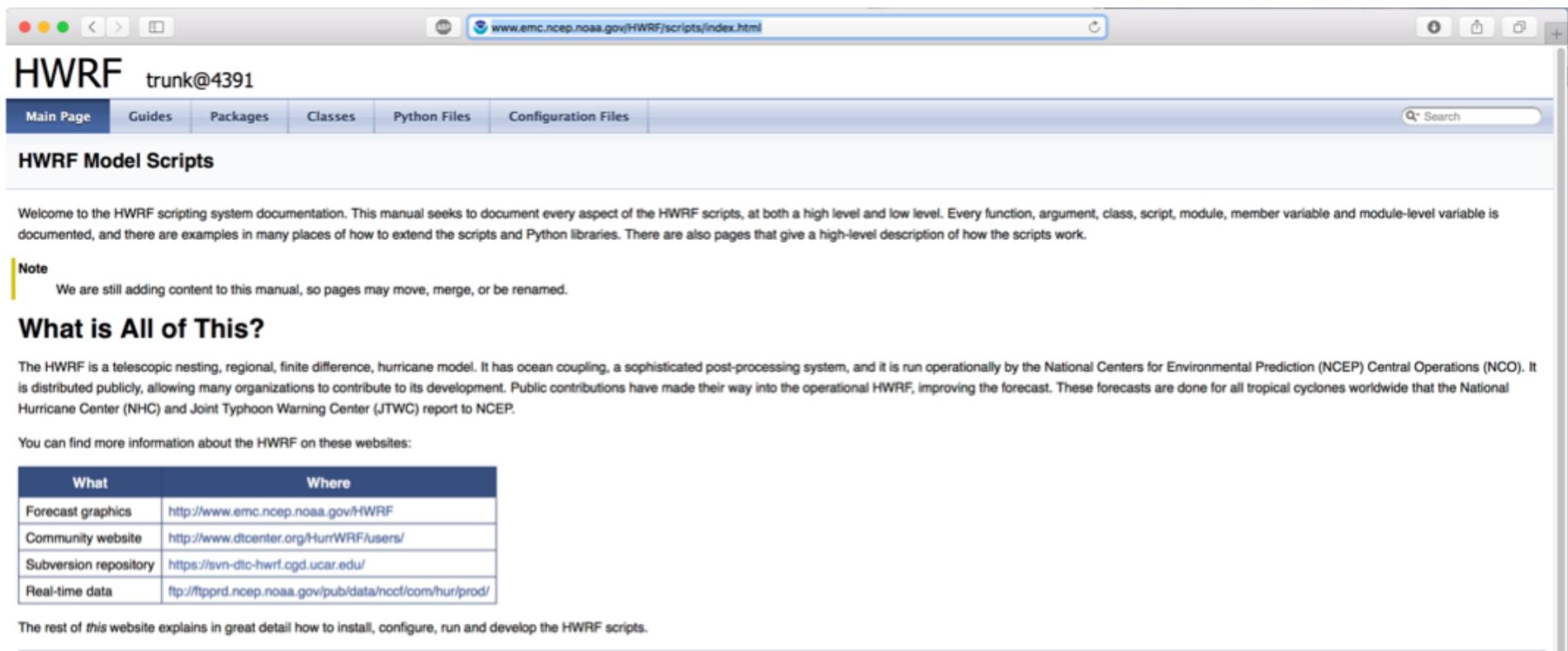
HWRF v3.9a User's Guide

- Includes detailed instructions on running each component
 - Specific to the public release
 - Explains how to run with provided wrapper scripts
- Content:
 - Introduction & software installation
 - Running HWRF
 - HWRF preprocessing system
 - Vortex Relocation
 - DA
 - Merge
 - MPIPOM-TC
 - Forecast Model
 - Post processor
 - Forecast products
 - Idealized

https://dtcenter.org/HurrWRF/users/docs/users_guide/HWRF_v3.9a_UG.pdf

Doxygen Website

- Detailed information about the HWRF configuration files and Python scripts



The screenshot shows a web browser displaying the "HWRF Model Scripts" documentation. The URL in the address bar is www.emc.ncep.noaa.gov/HWRF/scripts/index.html. The page title is "HWRF trunk@4391". The navigation menu includes "Main Page", "Guides", "Packages", "Classes", "Python Files", "Configuration Files", and a search bar. The main content area is titled "HWRF Model Scripts" and contains a welcome message: "Welcome to the HWRF scripting system documentation. This manual seeks to document every aspect of the HWRF scripts, at both a high level and low level. Every function, argument, class, script, module, member variable and module-level variable is documented, and there are examples in many places of how to extend the scripts and Python libraries. There are also pages that give a high-level description of how the scripts work." A "Note" section states: "We are still adding content to this manual, so pages may move, merge, or be renamed." Below this is a section titled "What is All of This?" which provides a brief overview of the HWRF model. It mentions that the HWRF is a telescopic nesting, regional, finite difference, hurricane model with ocean coupling and a sophisticated post-processing system, run operationally by NCEP Central Operations. It is distributed publicly, contributing to its development and improving forecasts for tropical cyclones worldwide. The section also lists where to find more information, including forecast graphics, community websites, subversion repositories, and real-time data sources.

Welcome to the HWRF scripting system documentation. This manual seeks to document every aspect of the HWRF scripts, at both a high level and low level. Every function, argument, class, script, module, member variable and module-level variable is documented, and there are examples in many places of how to extend the scripts and Python libraries. There are also pages that give a high-level description of how the scripts work.

Note
We are still adding content to this manual, so pages may move, merge, or be renamed.

What is All of This?

The HWRF is a telescopic nesting, regional, finite difference, hurricane model. It has ocean coupling, a sophisticated post-processing system, and it is run operationally by the National Centers for Environmental Prediction (NCEP) Central Operations (NCO). It is distributed publicly, allowing many organizations to contribute to its development. Public contributions have made their way into the operational HWRF, improving the forecast. These forecasts are done for all tropical cyclones worldwide that the National Hurricane Center (NHC) and Joint Typhoon Warning Center (JTWC) report to NCEP.

You can find more information about the HWRF on these websites:

What	Where
Forecast graphics	http://www.emc.ncep.noaa.gov/HWRF
Community website	http://www.dtcenter.org/HurrWRF/users/
Subversion repository	https://svn-dtc-hwrf.cgd.ucar.edu/
Real-time data	ftp://ftpprd.ncep.noaa.gov/pub/data/nccf/com/hur/prod/

The rest of *this* website explains in great detail how to install, configure, run and develop the HWRF scripts.

General Python help

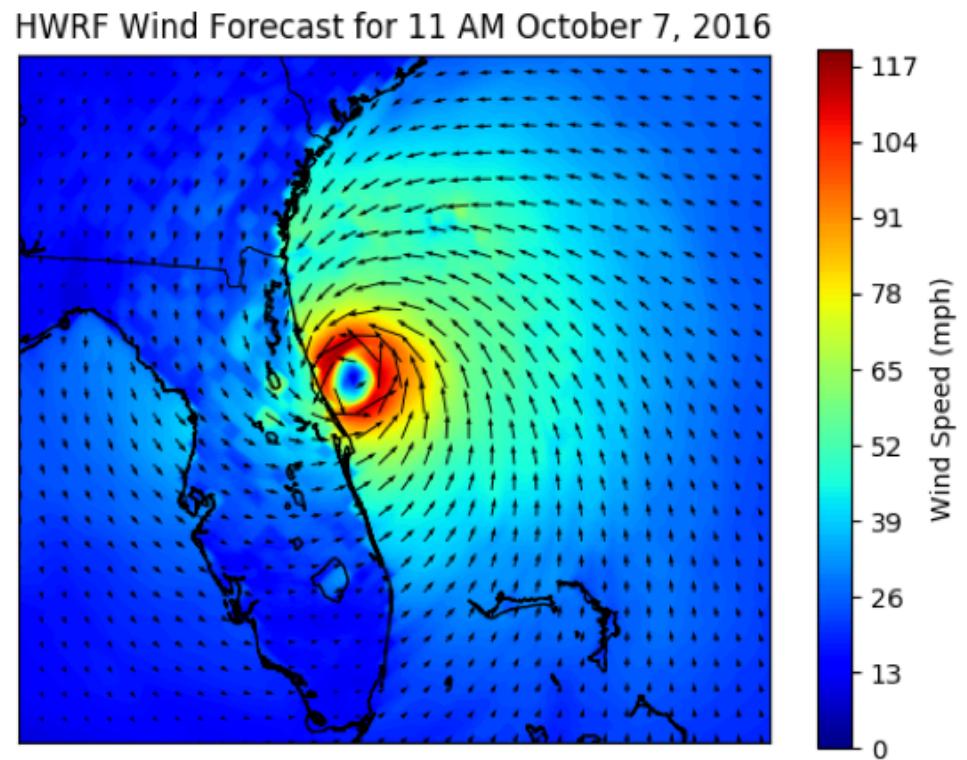
- Online (<https://docs.python.org/release/2.6.6/>)
- Open python in a terminal and use help() function for particular function. An example to get information with a Python list:

```
$ python  
$ help(list)
```

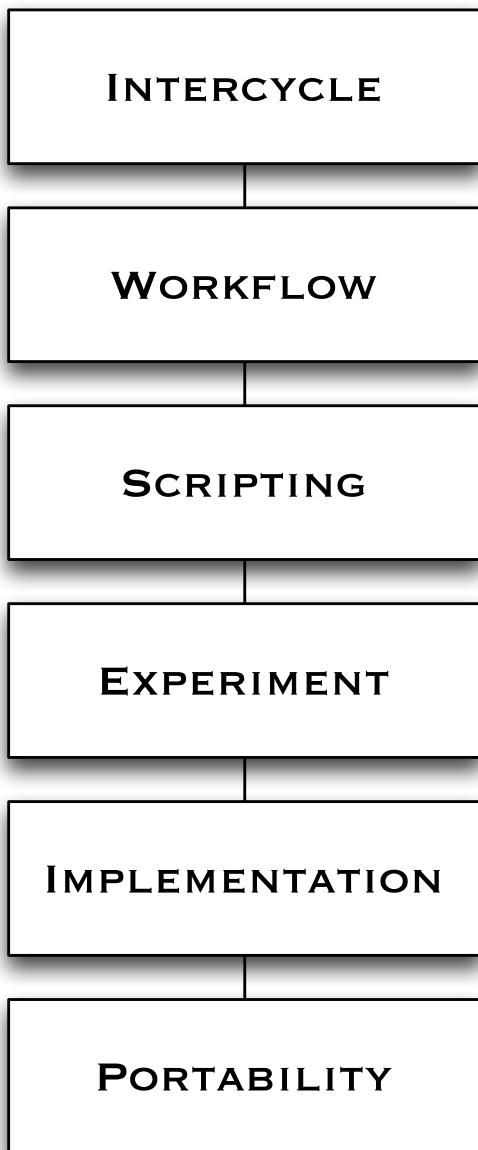
- The officially supported version for HWRF is Python v2.6.6.
 - Your version of Python should be version 2.6.6 or higher.
 - Version 3 is basically a different language.

HWRF System Overview

Overview of the system design



HWRF System: Overview

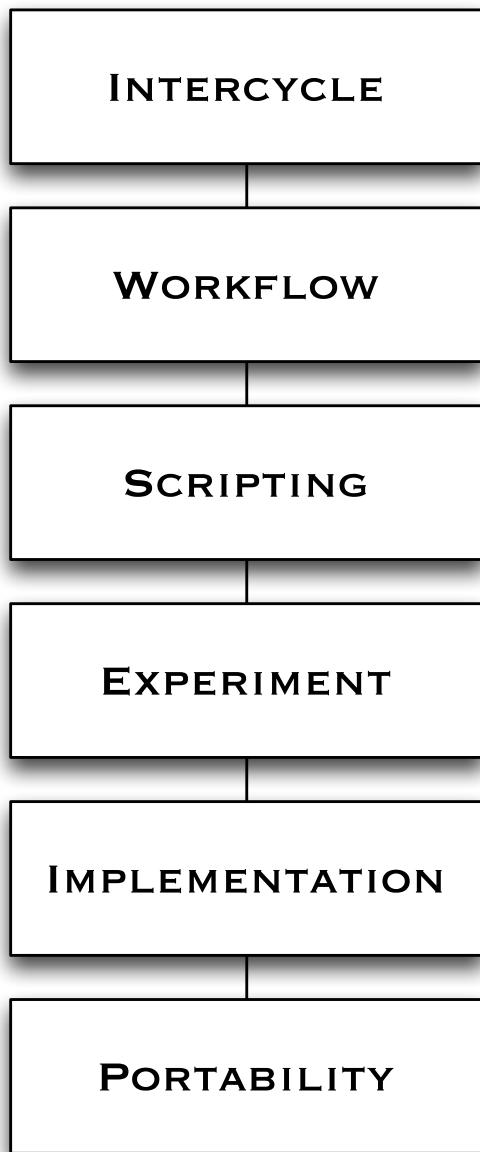


- 6 layers of scripts that are responsible for preparing the environment and data for and running the ~80 HWRF executables of the end-to-end system
- Most of these layers are written using an object-oriented (O-O) Python design
- O-O design makes the system highly configurable and reduces the footprint of the system drastically

HWRF Directory Structure

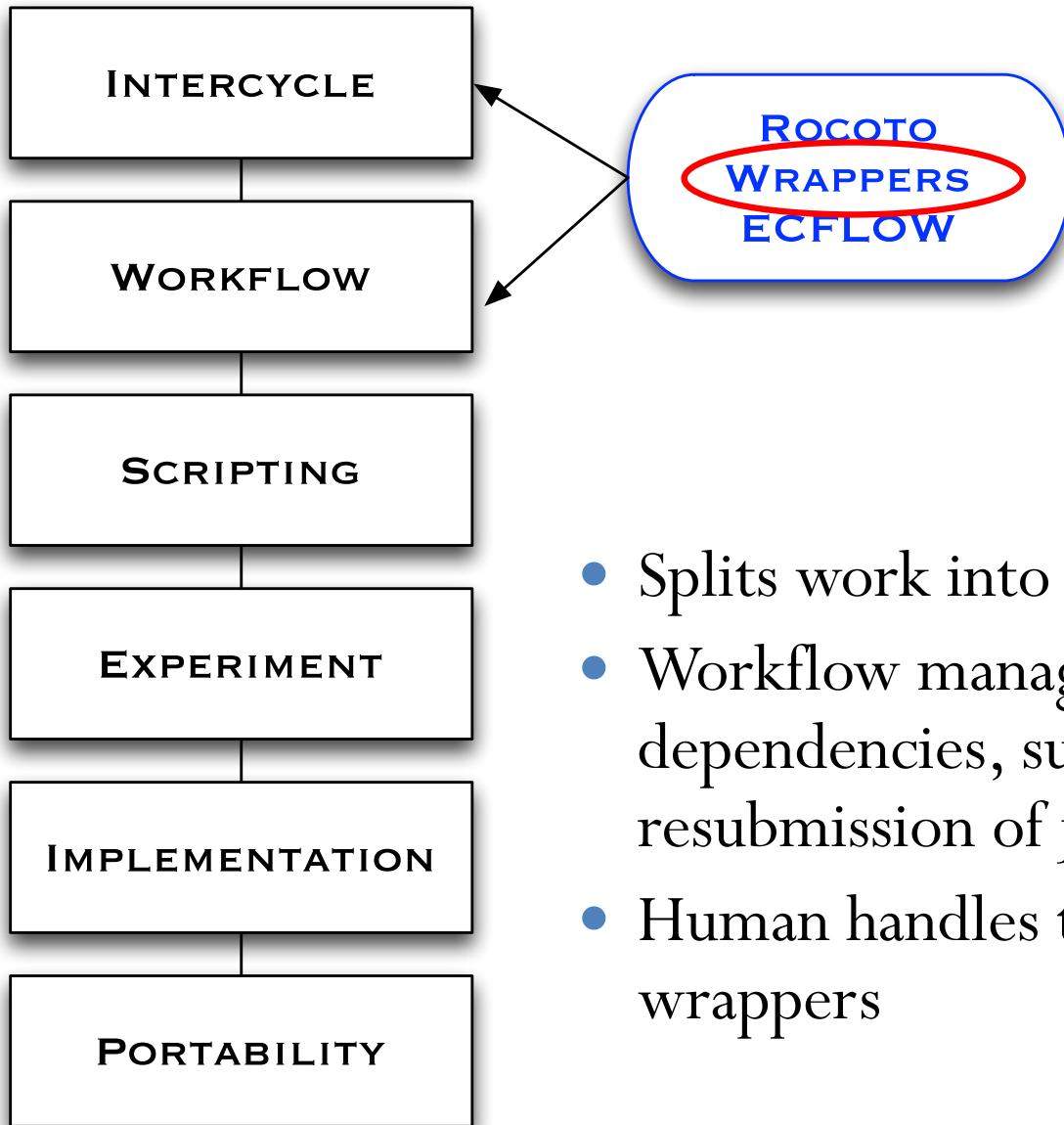
```
hwrfrun/
  doc/
  parm/ ..... *.conf
  scripts/ ..... exhwrf_*.py
  sorc/ { doc/
          gfdl-vortextracker/ pomtc/
          GSI/ UPP/
          hwrf-utilities/ WPSV3/
          ncep-coupler/ WRFV3/
  ush/ ..... hwrf_expt.py
        ..... produtil/
        ..... hwrf/
        ..... pom/
wrappers/
```

HWRF System: Intercycle Layer



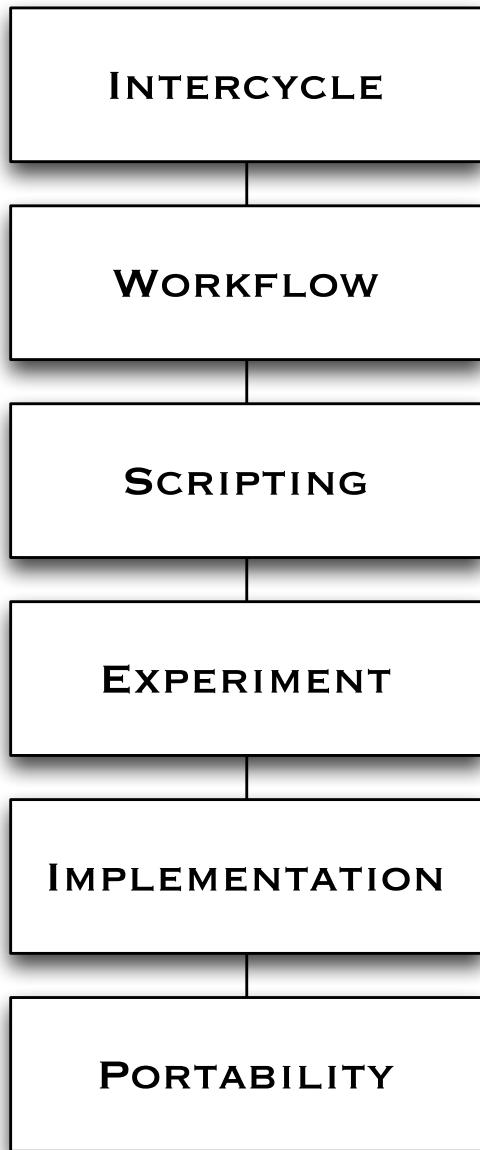
- Handles interactions between several cycles
 - Complex dependencies
 - Files passed between them
- Automation is not needed for a case study
- Critical for a large retrospective study, and for real-time automation

HWRF System: Workflow Layer



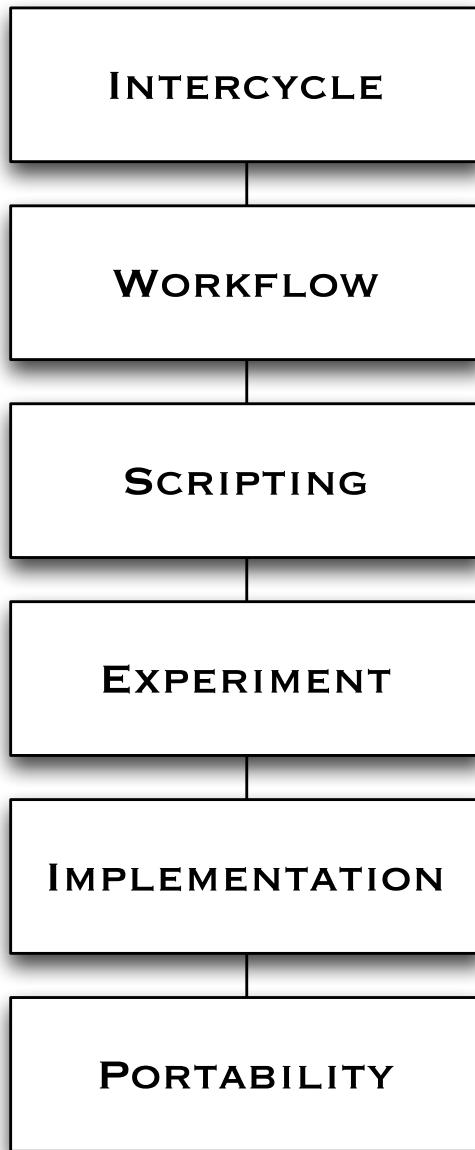
- Splits work into multiple batch jobs
- Workflow managers handle dependencies, submission, failures, and resubmission of jobs
- Human handles this process when using wrappers

HWRF System: Scripting Layer



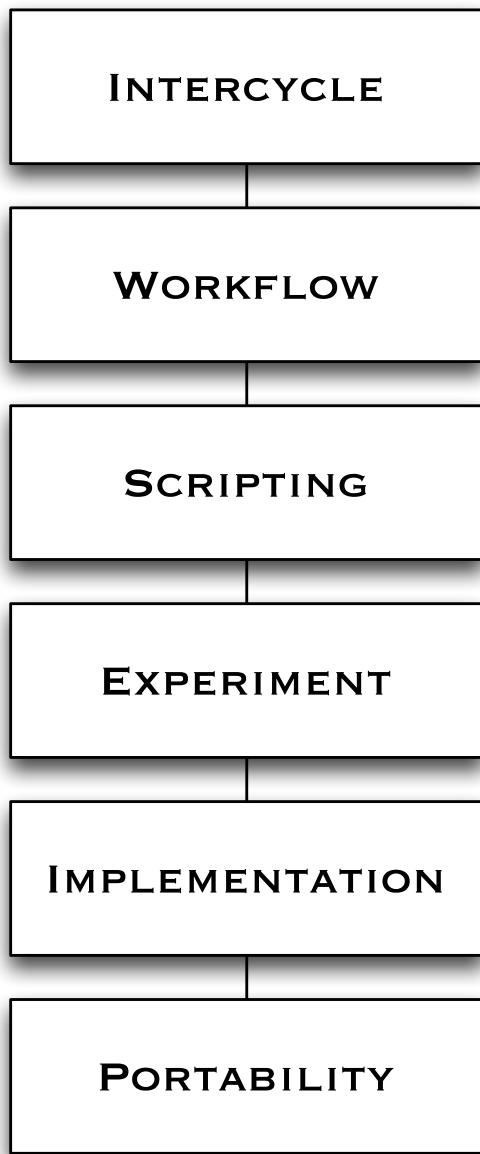
- Loads programs and libraries into computing environment
 - Ensures connection to file system on compute node
-
- Passes file and executable locations to the next lower layer
 - Layer is optional – can be done manually by user

HWRF System: Experiment Layer



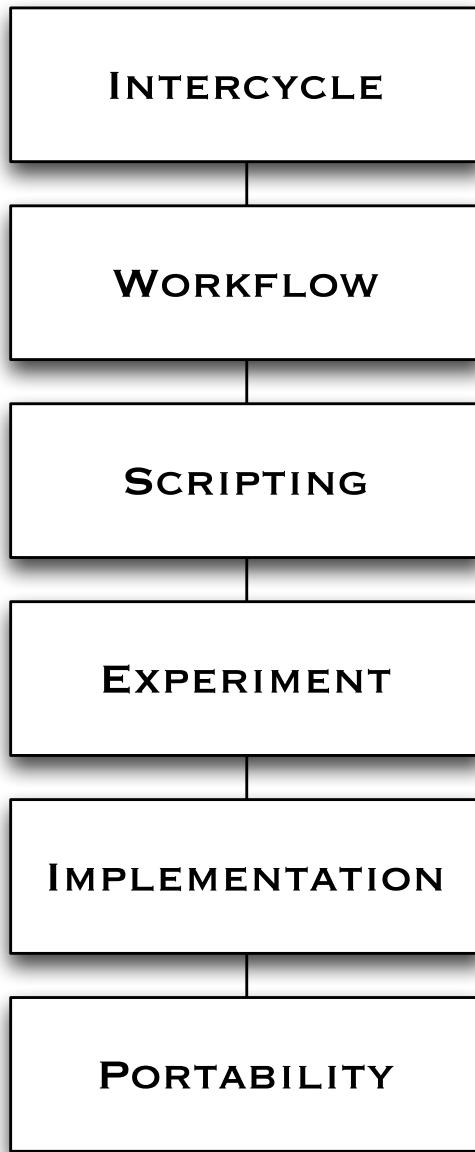
- Describes the HWRF workflow
- Creates the object structure that connects all the pieces
 - i.e. GSI should use input from the GDAS relocation output
 - Each object has a run() function to perform the actual task

HWRF System: Implementation Layer



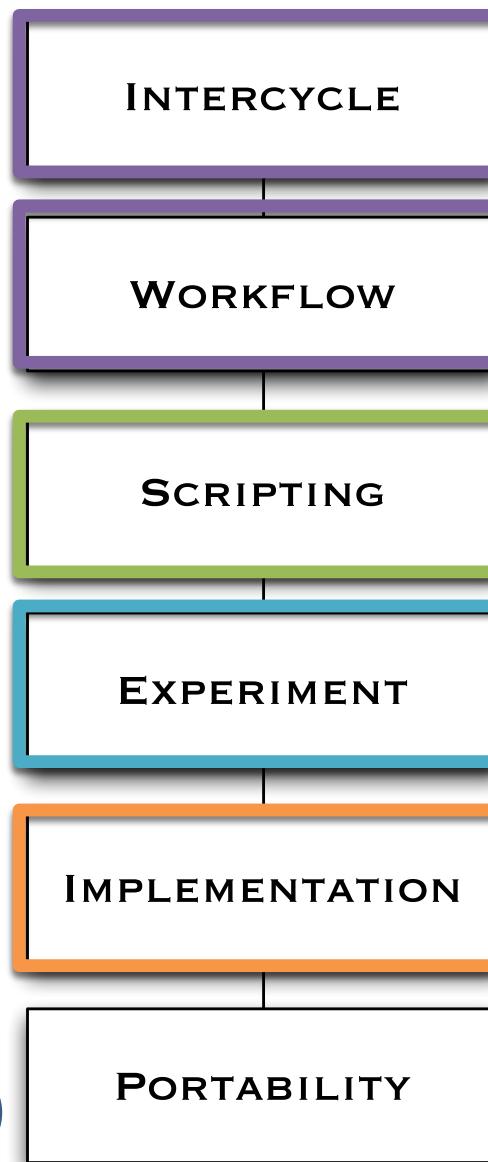
- A set of Python classes and functions used by the Experiment layer to run HWRF
- Each component has its own class and set of functions
- Some classes perform utilities to support the system, such as predicting filenames and performing time/date arithmetic
- Includes two packages
 - pom – Princeton Ocean Model initialization
 - hwrf – Implementation of most of the HWRF system

HWRF System: Portability Layer



- Implements cross-platform methods of performing common tasks
 - MPI implementation
 - OpenMP
 - Serial programs
 - File operations
 - Batch system interaction
 - Manipulate resource limitations
 - Interact with database file

Workflow Object Structure



wrappers/post_wrapper

```
export TOTAL_TASKS=24
```

```
$EXhwrf/exhwrf_post.py
```

scripts/exhwrf_post.py:

```
import hwrf_expt
```

```
hwrf_expt.init_module()
```

```
hwrf_expt.post.run_post()
```

ush/hwrf_expt.py:

```
post=HWRFPost('/path/to/infile',  
              '/path/to/fixd',  
              '/path/to/hwrf_post',  
              to_datetime('2015081818'))
```

ush/hwrf/post.py:

```
class HWRFPost
```

```
def run_post
```

Object-oriented Programming

A real-world example

Object-oriented programming: Some definitions

- A **class** is a blueprint (e.g., for building/riding a bike). It defines all of the characteristics (**attributes** – e.g., color) and behaviors (**methods** – e.g., coasting) of that **object** (e.g., a bike).
- An **object** is created from a **class**. From the blueprint provided by the class, you can build many different kinds of bikes (fast red bike, slow blue bike, etc.). Each object (bike) is a specific instance of the bike class.
- Helpful hints for distinguishing between **objects**, **methods**, and **attributes**:
 - Objects: think nouns: person, place, or thing
 - Methods: think action verbs: behaviors that can be performed
 - Attributes: think adjectives: characteristics that describe the object

Object-oriented Python

- Instantiation
 - `sam = bicycle()`



Hello, I'm
sam, an instance of
the bicycle class

Object-oriented Python

- Attributes
 - sam.make = “raleigh”
 - sam.model = “revenio”
 - sam.wheel_diameter = 700 # in mm



Hello, I'm

sam, an instance of
the bicycle class

Object-oriented Python

- Methods
 - `sam.ride("College Park, MD", "Boulder, CO")`
 - `sam.tuneup(3000)`



Hello, I'm

sam, an instance of
the bicycle class

Putting it all together

```
class bicycle: # this is a class

    def __init__(self,make,model,wheel_diameter):
        # this is a special method called by Python to create the class
        self.make=make
        self.model=model
        self.wheel_diameter=wheel_diameter

    def ride(self,start,finish): # this is another method
        self.lats=[]
        self.lons=[]
        # some logic here to calculate the optimal path
        self.lats=[38.99, 39.10, 40.02]
        self.lons=[-76.94, -94.58, -105.27]
        return self

    def tuneup(self,num_km): # this is another method
        self.todo=[]
        if (num_km >= 3000. and num_km < 5000.):
            self.todo=['replace tires', 'replace chain', 'clean frame']
        # insert additional logic for other maintenance milestones
        return self
```

Your program that calls the bicycle class

```
# Instantiate the bicycle class
sam = bicycle('rayleigh','revenio',700.)
# sam is an object. A specific instance of the bicycle class.

# Call the ride method
sam = sam.ride('College Park, MD', 'Boulder, CO')
print(sam.lats, sam.lons)

# Call the tuneup method
sam = sam.tuneup(3000)
print(sam.todo)
```

```
[Evan.Kalina@fe2 python]$ python
Python 2.7.13 |Anaconda 4.3.1 (64-bit)|
```

```
>>> execfile("bike.py")
([38.99, 39.1, 40.02], [-76.94, -94.58, -105.27])
['replace tires', 'replace chain', 'clean frame']
```

Object-oriented Programming

An example for HWRF

An example for UnifiedPost

```
class UnifiedPost:
```

```
    def __init__(self,infile,fixd,postexec,when):  
        (self.infile,self.fixd,self.postexec,self.when)=\  
            infile, fixd, postexec, when
```

```
    def run_post(self):
```

```
        self.link_fix()
```

```
        self.make_itag()
```

```
        make_symlink(self.infile,"INFILE",  
                    logger=self.log(),force=True)
```

```
        cmd=mpirun(mpi(self.postexec)<"itag")
```

```
        checkrun(cmd,all_ranks=true,logger=self.log())
```

```
    def link_fix(self):
```

```
        fixes=[f for f in glob.glob(self.fixd+"/*")]
```

```
        make_symlinks_in(fixes,".",logger=self.log())
```

An example for UnifiedPost

```
class HWRFPost(UnifiedPost):
```

```
    def make_itag (self):
```

```
        with open("itag","wt") as f:
```

```
            itagdata=self.when.strftime(
```

```
                "INFILE\nnetcdf\n%Y-%m-%d_%H:%M:%S" "\nNMM NEST\n")
```

```
            f.write(itagdata)
```

```
class NEMSPost(UnifiedPost):
```

```
    def make_itag (self):
```

```
        with open("itag","wt") as f:
```

```
            itagdata=self.when.strftime(
```

```
                "INFILE\nnetcdf\n%Y-%m-%d_%H:%M:%S"\n"NEMS\n")
```

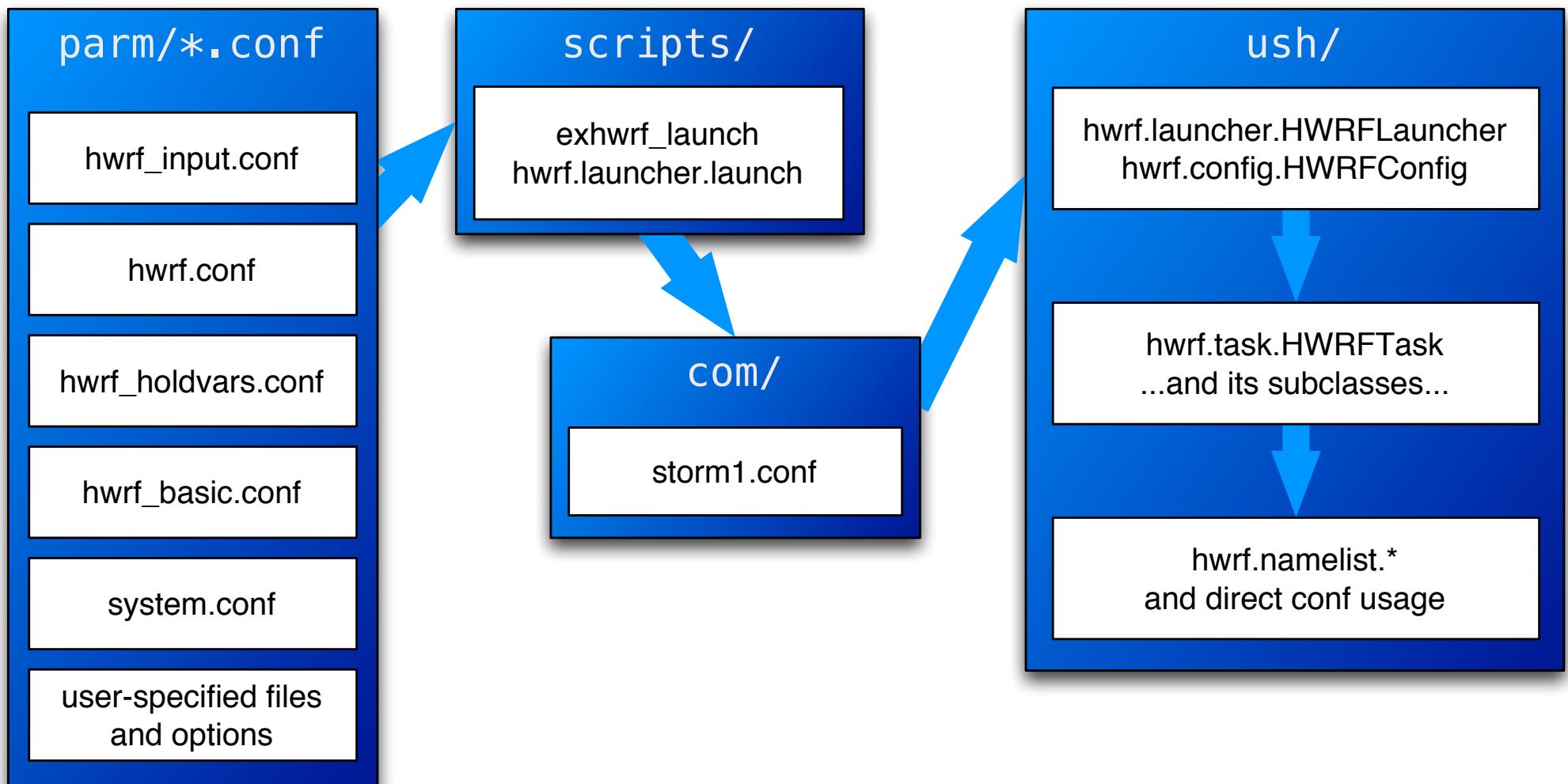
```
            f.write(itagdata)
```

Configuring HWRF

Conf files

hwrf_expt.py

Configuring HWRF Overview



Unix .conf Files

Simple format

parm/*.conf

hwrf_input.conf

hwrf.conf

hwrf_holdvars.conf

hwrf_basic.conf

system.conf

user-specified files
and options

```
# This is a comment
[section]
key=value ; This is also a comment
key2=value2
```

Doxygen format

```
## Short description of section
#
# Long description of section
# @note Doxygen+markdown syntax
[section]
key=value ;; short description of key
## Short description of key2
#
# long description of key2
key2=value2
```

Unix Conf Files

- String substitution

[myprog]

basedir = /some/path

exename = myexe.x

exepath = {basedir}/exec/{exename}

exepath = /some/path/exec/myexe.x



- String substitution with formatting

[myprog]

gridnum = 5

exename = myexe_{gridnum:02d}.x

exepath = {basedir}/exec/{exename}

exename = myexe_05.x



- Substitute from other sections

[grid]

num = 5

[myprog]

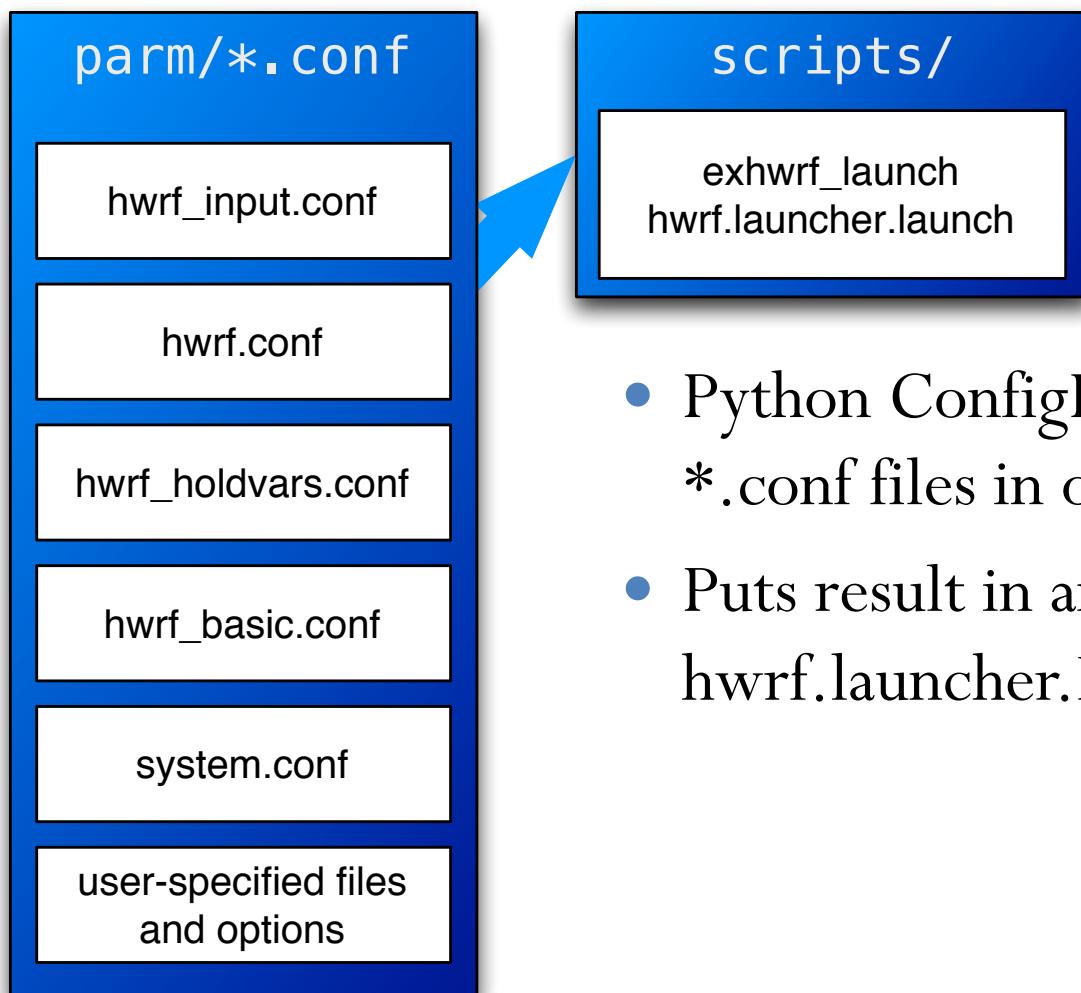
exename = myexe_{grid/num:02d}.x

exepath = {basedir}/exec/{exename}

exename = myexe_05.x

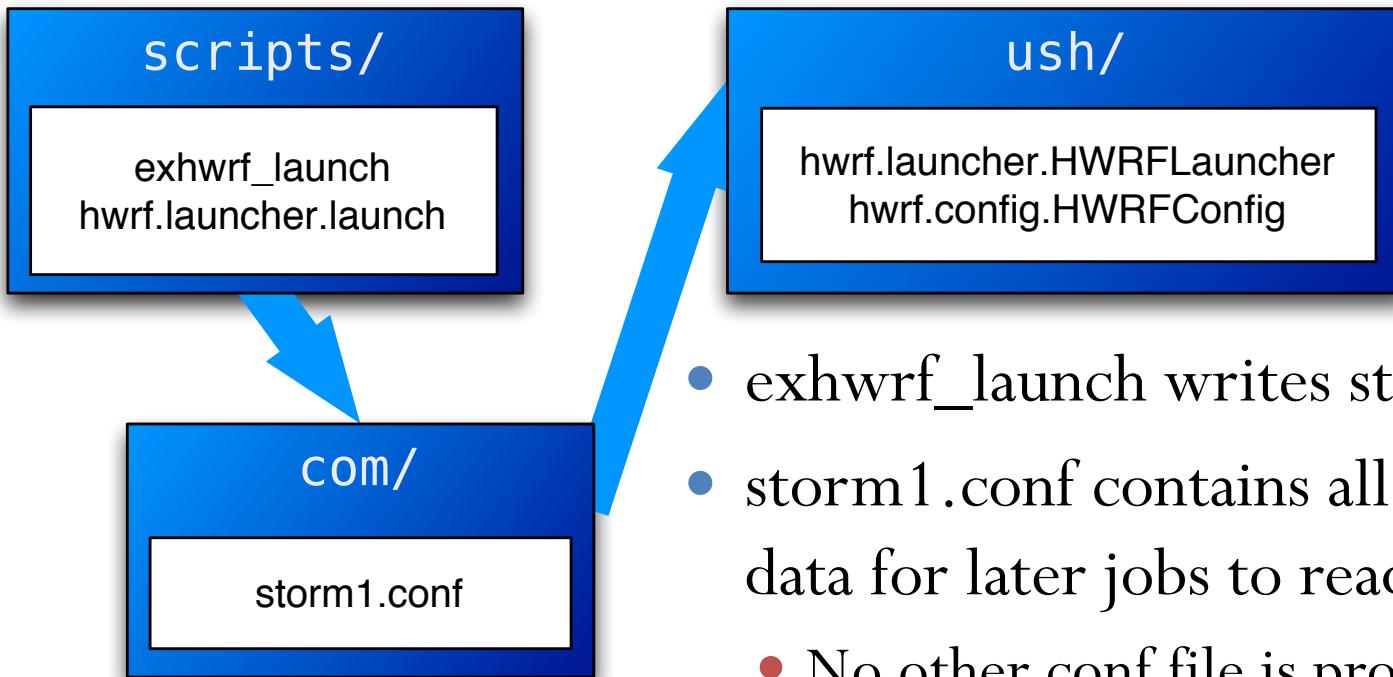


Config Processing



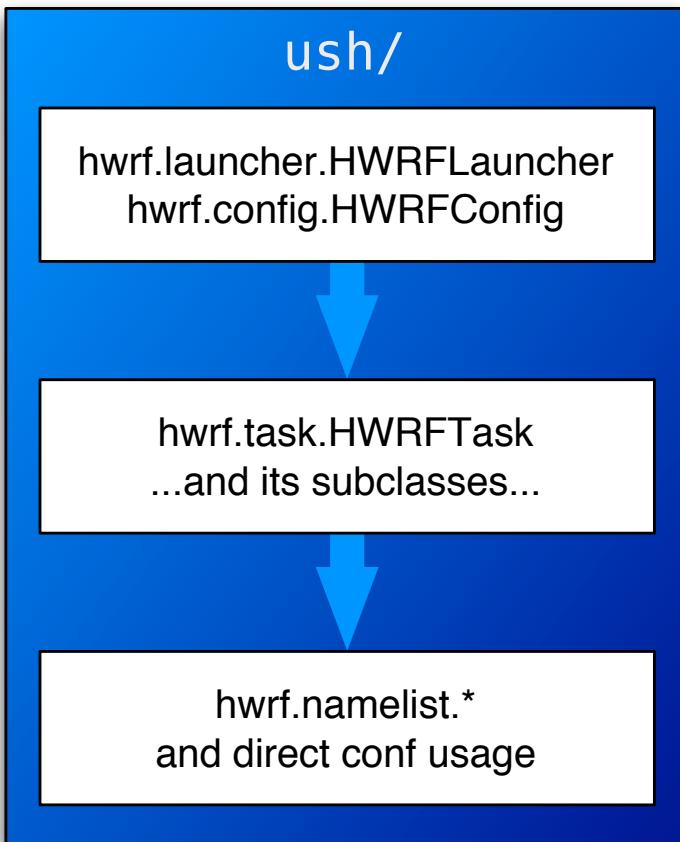
- Python `ConfigParser.ConfigParser` parses the `*.conf` files in order
- Puts result in an in-memory `hwrf.launcher.HWRFLauncher` object

storm1.conf



- exhwrf_launch writes storm1.conf
- storm1.conf contains all the processed config data for later jobs to read
 - No other conf file is processed
- Later jobs read storm1.conf using hwrf.launcher.load
- hwrf.launcher.HWRFLauncher contains many convenience functions for using the conf info

HWRF Python Tasks



- HWRFLauncher & HWRFConfig
 - Classes that access conf data
 - getstr(section, key, default)
 - Returns default value if none specified in storm1.conf
 - getint, getfloat, getbool, etc. (see docs for full list)
- HWRFTask is an instance of each of the tasks to be completed
 - Examples include GeogridTask, WRFAtmos, etc.
 - Has a database task name, a conf section, and an HWRFConfig
- hwrf.namelist.NamelistInserter reformats storm1.conf information into Fortran namelist files needed for various components

Data Communication

Database introduction

Passing around information

HWRF Database

- HWRF needs to know the status/availability of files millions of times per cycle
- When a file becomes available, a Python script puts its location, availability, and other metadata into an SQLite3 database

Table “products”

id	available	location	type
geogrid::geo_nmm_nest	0	/path/to/file	Product

Table “metadata”

id	key	value
geogrid::geo_nmm_nest	minsize	100000000

HWRF Database & prooutil

- The prooutil package contains all the HWRF utilities to write to and query the SQLite3 database
- prooutil includes methods to check, deliver, and “undeliver” files
 - prod.check – Check for file of specified minimum size and age
 - Returns status as RUNNING, COMPLETED, FAILED
 - prod.undeliver – Remove file from working area
 - prod.deliver – Deliver file to specified location
- You can query the database on your own like any other SQLite3 database
- For a list of the input/output needed for HWRF, see `hwrf.fcsttask.WRFTaskBase`

Logging

stderr and stdout

- Located in the \$HOMEhwrf/wrappers directory
- stdout files contain all the logging (info, error, critical level) messages from the Python scripts
- stderr files contain all the error and critical messages, plus the submission information for the job (PROLOGUE, EPILOGUE)
- Can be separated into *.out and *.err, or joined into one stream. Name and location depend on your job submission script.
- At least one set/file for each task.
- Multiple processor jobs have multiple sets of logs
 - post, products, tracker, etc.

Writing to the standard out

- Adding log messages can be done from the ush scripts with a few simple commands

```
logger=self.log()
```

```
logger.info('This is the value of some_variable:  
           %s' %(some_variable))
```

```
logger.warning('This is a warning!')
```

```
logger.error('This is an error')
```

```
logger.critical('This is really bad!')
```

Result:

```
01/08 04:34:45.706 hwrf.gfsinit (relocate.py:353) INFO: This  
is the value of some_variable: 270.0
```

```
01/08 04:34:45.902 hwrf.gfsinit (relocate.py:354) WARNING:  
This is a warning!
```

Python Exception Stacks

- Several lines you get when you fail.

```
Traceback (most recent call last):
```

```
  File "/pan2/projects/dtc-
hurr/dtc/HWRF_training//scripts/exhwrf_gsi.py", line 60, in <module>
    main()
  File "/pan2/projects/dtc-
hurr/dtc/HWRF_training//scripts/exhwrf_gsi.py", line 53, in main
    hwrf_expt.gsi_d02.run()
  File "/pan2/projects/dtc-hurr/dtc/HWRF_training/ush/hwrf/gsi.py",
line 982, in run
    self.grab_enkf_input()
  File "/pan2/projects/dtc-hurr/dtc/HWRF_training/ush/hwrf/gsi.py",
line 285, in grab_enkf_input
    self.grab_gfs_enkf()
  File "/pan2/projects/dtc-hurr/dtc/HWRF_training/ush/hwrf/gsi.py",
line 607, in grab_gfs_enkf
    %(there,))
GSIInputError: required input file is empty or non-existent:
/pan2/projects/dtc-
hurr/dtc/HWRF_training/pytmp/HWRF_training/2015082000/17W/hwrfdata/en
kf.2015081918/sfg_2015081918_fhr06s_mem001
```

Output from components

- Many components have their own log files
- For example:
 - WRF: rsl.out.* and rsl.err.*
 - WPS: metgrid.log.*, geogrid.log.*, ungrid.log
 - GSI: stdout
 - Coupler: cpl.out

Questions?
