

# A Brief Tutorial on GSI Infrastructures & Advanced Features

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This presentation is a brief guide to some of the basic infrastructure being added to GSI, namely:

- Interfacing to user-specific applications
- Introducing MetGuess\_Bundle & Chem\_Guess
- Remarks on adding new observing instruments
- Connecting math & code

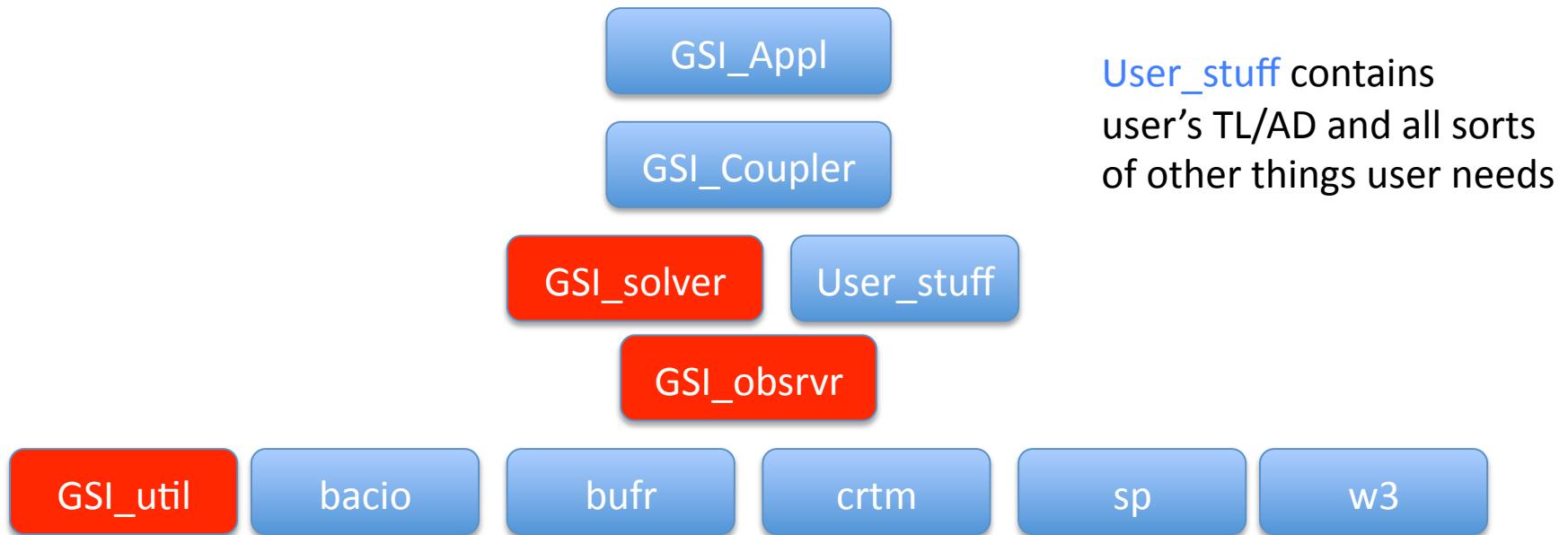
# OUTLINE

- Code Structure
- Interfacing user-specific components
  - General concept
  - Illustration 1: timing routines
  - Illustration 2: 4D-Var
  - Illustration 3: Hybrid Ensemble
  - Illustration 4: Aerosols
- Adding new instruments (obs. operator)
- MetGuess\_Bundle & Chem\_Guess
- Connecting Math & Code (time permitting)

# GSI Infrastructure:

## Split GSI into sub-libraries

- Schematic view of GSI & supporting libraries at GMAO



- Issues:
  - At present, **GSI\_solver** and **GSI\_obsrvr** cannot be separated
  - At present, **GSI\_util** cannot sit parallel to supporting libs due to its reliance on some of those

# GSI Infrastructure:

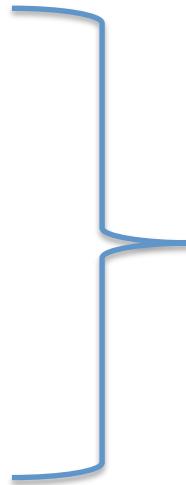
## General Code Organization

```
! Initialize defaults of vars in modules
call init_4dvar

! Read in user specification of state and control variables
call gsi_metguess_init
call gsi_chemguess_init
call init_anasv
call init_anacv

call init_constants_derived
call init_oneobmod
call init_qcvars
call init_obsmod_dflts
call init_directories(mype)
call init_pcp
call init_rad
    ● ● ●
! Initialize values in radinfo
call init_rad_vars

! Initialize values in aeroinfo
call init_aero_vars
```



Initialize  
gsimain\_initialize

```
call gsi_4dcoupler_setservices(rc=ier)
```

SetServices  
gsimain\_initialize

```
! Call the main gsi driver routine
call gsisub(mype, init_pass_,last_pass_)
```

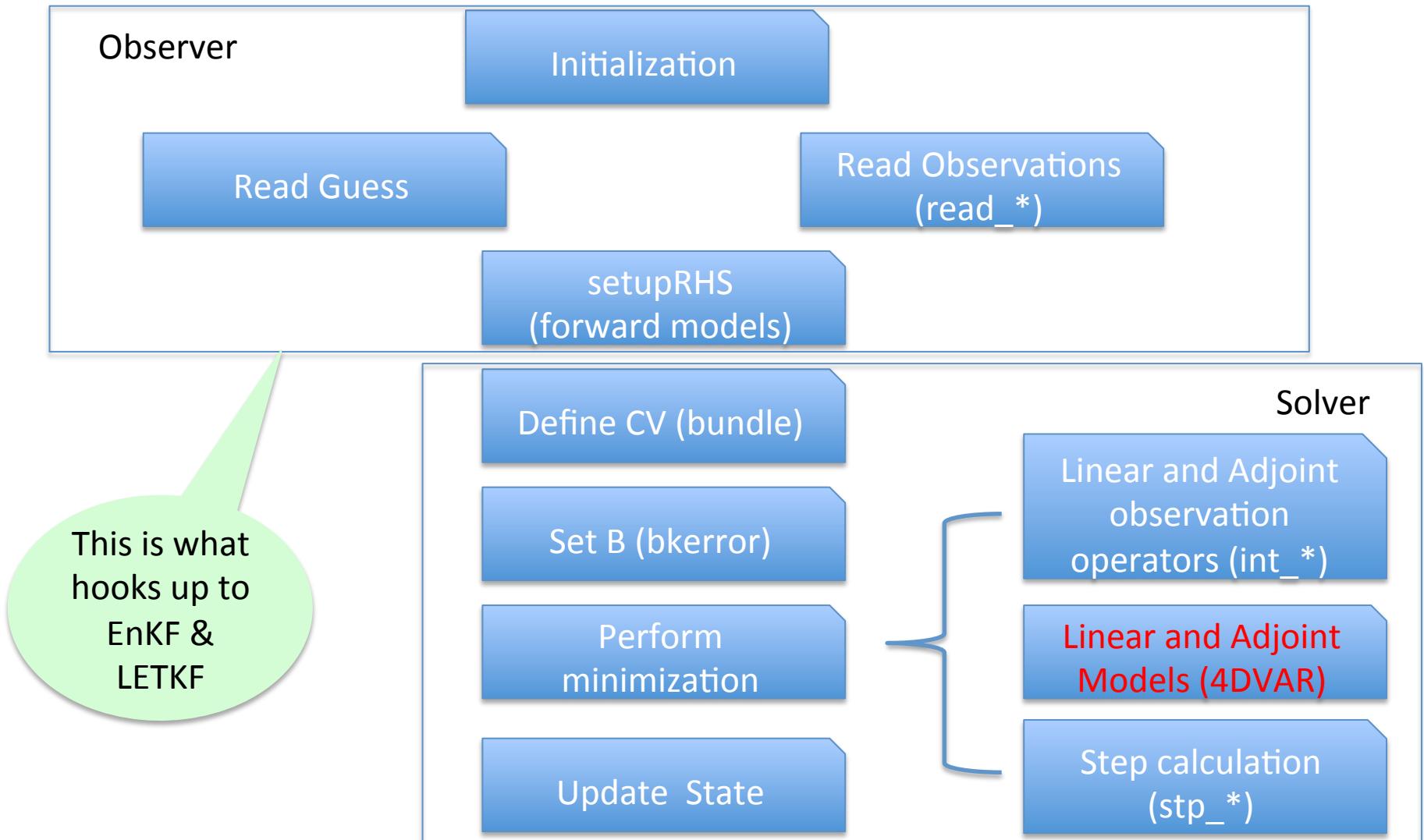
Run  
gsimain\_run

```
call final_aero_vars
call final_rad_vars
call clean_4dvar
call destroy_obsmod_vars
call destroy_mpi_vars
call final_anacv
call final_anasv
call gsi_chemguess_final
call gsi_metguess_final
```



Finalize  
gsimain\_finalize

# GSI Infrastructure: General Code Organization



# Interfacing to user-specific components

- Simplest possible paradigm: FORTRAN-77-like
  - No “use” statements allowed at interface level
  - No “ifdef’s” (preferred)
  - GSI Convention: package name stub\_XXX.F90
  - User Convention: (suggested) name cplr\_XXX.F90
- Current available GSI interfaces:
  - timermod.F90
  - gsi\_4dcouplermod.F90
  - gsi\_enscouplermod.F90
  - set\_crtm\_aerosolmod.F90
  - gsi\_nstmod.F90 (\*)
- Each of the interfaces is associated with a stub, respectively:
  - stub\_timermod.F90
  - stub\_pertmod.F90
  - stub\_ensmod.F90
  - stub\_set\_crtm\_aerosol.F90
  - stub\_nstmod.F90 (\*)

(\*) Not discussed in this presentation

# Interfacing to user-specific components

## Illustration I: **timermod**

- More often than not, timing routines are user and machine specific. **timermod** allows for the possibility of a user to supply its own timing mechanism.

Actual interface: **timermod.F90**

```
public timer_ini
public timer_fnl
public timer_pri

interface timer_ini
    subroutine timer_init_(str)
    implicit none
    character(len=*),intent(in ) :: str
    end subroutine timer_init_
end interface

interface timer_fnl
    subroutine timer_final_(str)
    implicit none
    character(len=*),intent(in ) :: str
    end subroutine timer_final_
end interface

interface timer_pri
    subroutine timer_pri_(lu)
    use kinds, only : i_kind
    implicit none
    integer(i_kind),intent(in ) :: lu
    end subroutine timer_pri_
end interface
```

This is a module; this what routines in GSI call

Stub routines: **stub\_timermod.F90**

```
subroutine timer_init_(str)
!$$$ subprogram documentation block
!
! subprogram: timer_init_      initialize procedure
!
! prgmmr: todling          org: gmao
!
! abstract: initializes timer
!
! program history log:
!   2007-10-01  todling
!
! input argument list:
!   str - string designation for process to be t
!
! output argument list:
!
! attributes:
!   language: f90
!   machine:
!
! $$$ end documentation block

implicit none
character(len=*),intent(in ) :: str
end subroutine timer_init_
```

This is a NOT module; ONLY called by timermod

Similar for other two routines, i.e., they are empty subroutines that do nothing

# Interfacing to user-specific components

## Illustration I: timermod

- If a user wants to specify its own timings, it should provide a Coupler for the timing routines, as in **cplr\_timermod** below:

User-specific routines: **cplr\_timermod.F90**

```
subroutine timer_init_(str)
use m_zeit, only: zeit_ci ! A GMAO module for timing
implicit none
character(len=*),intent(in ) :: str
call zeit_ci(str)          ! start GMAO timing for str
end subroutine timer_init_

subroutine timer_final_(str)
use m_zeit, only: zeit_co ! A GMAO module for timing
implicit none
character(len=*),intent(in ) :: str
call zeit_co(str)         ! stop GMAO timing for str
end subroutine timer_final_

subroutine timer_pri_(lu)
use kinds, only : i_kind
use mpimod, only : mype
use m_zeit, only : zeit_flush ! A GMAO module for timing
implicit none
integer(i_kind),intent(in ) :: lu
if(mype==0) call zeit_flush(lu,subname_at_end=.true.)
end subroutine timer_pri_
:
```

These are user functions GSI knows nothing of



Prologues stripped off for display only.

# Interfacing to user-specific components

## Illustration I: **timermod**

- The implications of adding user-specific functions/routines to GSI are the following:
  - The Make procedure in the **GSI directory** can no-longer create the **GSI executable**.
  - The Make procedure in the GSI directory **must** instead **create a GSI library**.
  - The corresponding dummy stub must be removed from the GSI library before the executable is created. This is easily accomplished by the flags of the archiving command. For example, in Linux, to remove the **stub\_timermod.o** object file that would be in the GSI library (called it **libgsi.a** for the time being), one can simply add the following line to the Makefile that creates the executable:
    - **ar -d libgsi.a stub\_timermod.o**
  - The Make procedure creating the executable can then load the GSI library, together with the user-library containing the Coupler, that is, in the example above **cplr\_timermod.o**, and whatever else is needed, plus the main program from GSI (**gsimain.F90**).
  - This means the **gsimain.F90** should be placed outside of GSI. For the time being, the GSI directory could still keep a copy of this program, but only for reference.

# Interfacing to user-specific components

## Illustration II: gsi\_4dcouplermod

- This provides the coupling mechanism to user-specific TL and AD models
- The companion stub file is **stub\_pertmod.F90**, that, as with other stubs, must be removed from the GSI library to allow the user to specify its own coupler.
- This interface is more complex than those of previous illustrations. Only a sketchy illustration follows.

### Methods in gsi\_4dcouplermod.F90

Actual interface:

```
interface GSI_4dCoupler_init_traj
    subroutine pertmod_initialize_(idmodel,rc)
        use kinds, only: i_kind
        implicit none
        logical,optional,intent(in):: idmodel
        integer(i_kind),optional,intent(out):: rc
    end subroutine pertmod_initialize_
end interface

Run ADM
    interface GSI_4dCoupler_model_ad
        subroutine pertmod_ADrun_(xini,xobs,iymd,ihms,ndt,rc)
            use kinds, only: i_kind
            use gsi_bundlemod, only: gsi_bundle
            implicit none
            type(gsi_bundle),intent(inout):: xini ! inout: adjoint increment perturbation
            type(gsi_bundle), pointer:: xobs ! input: adjoint perturbation state
            integer(i_kind),intent(in ):: iymd ! starting date (YYYYMMDD) of the adjoint perturbation state
            integer(i_kind),intent(in ):: ihms ! starting time (HHMMSS) of the adjoint perturbation state
            integer(i_kind ),intent(in ):: ndt ! Number of time steps to integrate TLM for
            integer(i_kind ),optional,intent(out):: rc   ! return status code
        end subroutine pertmod_ADrun_
    end interface
```

} Trajectory  
initialization

```
!
! !PUBLIC MEMBER FUNCTIONS:
!
public GSI_4dCoupler_parallel_init
public GSI_4dCoupler_setServices
public GSI_4dCoupler_init_traj
public GSI_4dCoupler_init_model_tl
public GSI_4dCoupler_model_tl
public GSI_4dCoupler_final_model_tl
public GSI_4dCoupler_init_model_ad
public GSI_4dCoupler_model_ad
public GSI_4dCoupler_final_model_ad
public GSI_4dCoupler_grtests
public GSI_4dCoupler_getpert
public GSI_4dCoupler_putpert
public GSI_4dCoupler_final_traj
```

# Interfacing to user-specific components

## Illustration II: `gsi_4dcouplermod`

- Both GMAO and NCEP have interfaced their TLM/ADM to GSI. The former has interfaced two different models, the most recent one being fully ESMF-capable; the latter has interfaced a perturbation model based on integrating the tendencies originally available in GSI.
- As illustration we show some of the NCEP perturbation model interface. This is composed mainly of two components:
  - `cplr_pertmod`: An f77-like coupler providing a replacement of `stub_pertmod`
  - `ncep_permod`: A f90 module providing the entry point to the perturbation model, and its TL and AD counterparts.
  - For now, a specific feature of the perturbation model implementation is that the observer must “run the non-linear model” (that is the perturbation model). Though quite unusual, the interface is general to easily accommodate this case.

# Interfacing to user-specific components

## Illustration II: gsi\_4dcouplermod

Actual interface: **cplr\_pertmod.F90**

```
subroutine pertmod_initialize_(idmodel,rc)
use kinds, only: i_kind
use mpimod, only: mype
use nonlinmod, only: ncep_model_nl_init
use nonlinmod, only: ncep_model_nl
use mpeu_util, only: tell,perr,die
use obsmod, only: lobserver
implicit none

logical,optional,intent(in):: idmodel
integer(i_kind),optional,intent(out):: rc      ! return status code
!~~~~~
character(len=*),parameter :: myname_=MYNAME//'::pertmod_initialize_'
logical:: idmodel_
integer(i_kind):: ier

if(present(rc)) rc=0
idmodel_=.true.
if(present(idmodel)) idmodel_=idmodel
call ncep_model_nl_init(ier)
  if(ier/=0) then
    call perr(myname_,'pertmod_initialize(), rc =',ier)
    if(.not.present(rc)) call die(myname_)
    rc=ier
    return
  endif
if(idmodel_) return
! For now, the observer runs the non-linear trajectory model
if(.not.lobserver) return ! _rt must be another param to control NL call
call ncep_model_nl

end subroutine pertmod_initialize_
```



Typically, this initializes the trajectory



Relies on nonlimod.F90, a module driving the pert model



In this case, it actually runs the perturbation to generate the trajectory – in the conventional case, the trajectory would simply be read-in

Prologues stripped off for display only.

# Interfacing to user-specific applications

## Illustration II: gsi\_4dcouplermod

Actual interface: **cplr\_pertmod.F90**

```
subroutine pertmod_TLrun_(p_xini,xobs,iymd,ihms,ntstep,rc)
use kinds, only: i_kind
use gsi_bundlemod, only: gsi_bundle
use ncep_pertmod, only: ncep_4dmodel_tl
use mpeu_util, only: tell,perr,die
implicit none

type(gsi_bundle), pointer:: p_xini      ! input: increment perturbation prop
type(gsi_bundle),intent(inout):: xobs     ! inout: TL perturbation state
integer(i_kind ),intent(in ):: iymd    ! staring date (YYYYMMDD) of the perturbatio
integer(i_kind ),intent(in ):: ihms    ! staring time (HHMMSS) of the perturbation
integer(i_kind ),intent(in ):: ntstep ! Number of time steps to integrate TLM for
integer(i_kind ),optional,intent(out):: rc   ! return status code

!! t := (nymdi,nhmsi); n:=ntstep; xi:=xini; yo:=xobs
!! e(t) = A(t)*xi(t)
!! z(t+n) = M(t+n,t)*[z(t)+e(t)]
!! yo(t+n) = G(t+n)*z(t)

!~~~~~
character(len=*),parameter :: myname_=MYNAME//'::pertmod_TLrun_'
integer(i_kind):: ier

if(present(rc)) rc=0
call ncep_4dmodel_tl(p_xini,xobs,iymd,ihms,ntstep,ier)
  if(ier/=0) then
    call perr(myname_,'pertmod_TLrun(), rc =',ier)
    if(.not.present(rc)) call die(myname_)
    rc=ier
    return
  endif
|
end subroutine pertmod_TLrun_
```

Typically, this runs the TLM



Relies on ncep\_pertmod.F90, a module driving the TL/AD pert model

NOTE: ncep\_permod.F90, and nonlinmod.F90 do not live inside GSI – they are part of the so-called NCEP\_Coupler library. This also includes various other codes specific to the perturbation model.



Procedure from ncep\_pertmod.F90 that actually integrates TLM

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# Interfacing to user-specific applications

## Illustration III: gsi\_enscouplermod

Actual interface: `cplr_pertmod.F90`

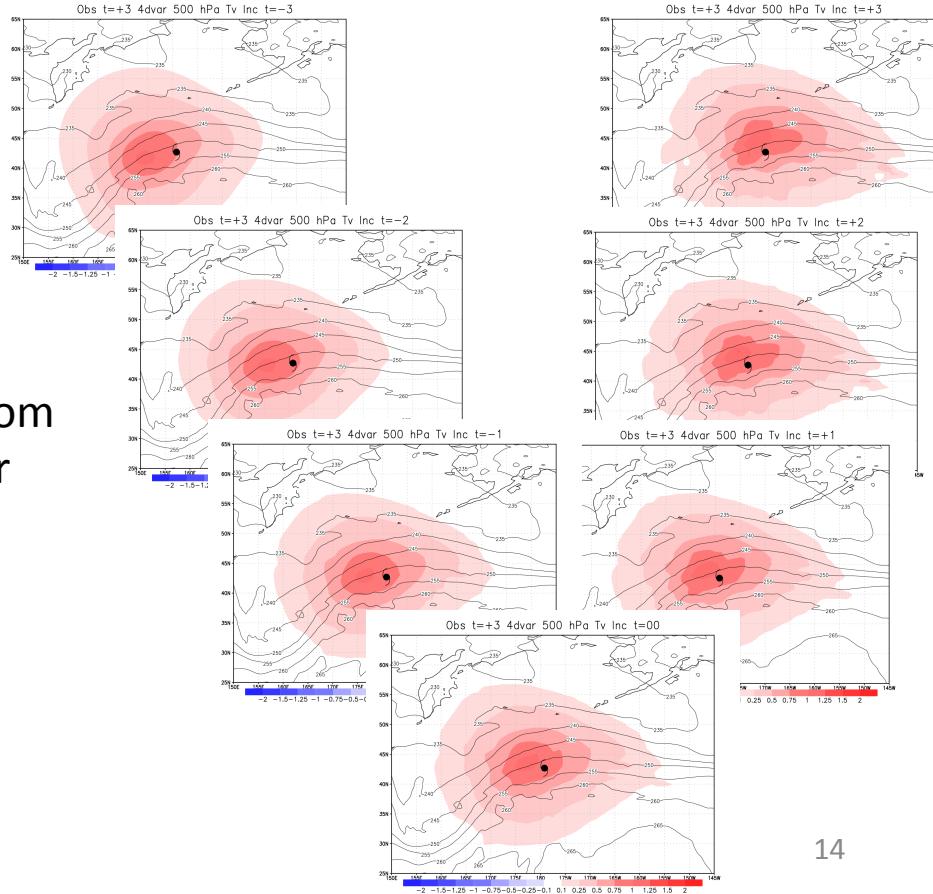
The handy put method: `GSI_4dCoupler_putpert` allows for writing of the Increment as it evolves within the assimilation window, see routine `view_st`

```
! write out perturbation vector
mydate = ibdate
do ii=1,nobs_bins
  nynd = 10000*mydate(1)+mydate(2)*100+mydate(3)
  nhms = 10000*mydate(4)
  ! iwrinc ...

  if(mype==0) then
    write(6,'(2a,i8.8,2x,i6.6)') trim(myname_),': start writing state on ', nynd
  endif
  call gsi_4dcoupler_putpert (sval(ii),nynd,nhms,'tlm',filename)

  ! increment mydate ...
  fha(:)=0.0; ida=0; jda=0
  fha(2)=nhr_obsbin! relative time interval in hours
  ida(1)=mydate(1) ! year
  ida(2)=mydate(2) ! month
  ida(3)=mydate(3) ! day
  ida(4)=0 ! time zone
  ida(5)=mydate(4) ! hour
  ! Move date-time forward by nhr_assimilation hours
  call w3movdat(fha,ida,jda)
  mydate(1)=jda(1)
  mydate(2)=jda(2)
  mydate(3)=jda(3)
  mydate(4)=jda(5)
enddo
```

The PUT from  
the coupler



Prologues stripped off for display only.

# Interfacing to user-specific applications

## Illustration III: `gsi_enscouplermod`

- At the moment this interface applies only to the Global option in GSI. In the future, a general interface will accommodate the regional option as well.
- The idea here is to allow users to inject their ensemble members in to GSI and its hybrid-ensemble component. For this, only a grid definition and a reader-like interface are needed. The bulk of what happens in these can be fully hidden from GSI; e.g., the GMAO interface does the read of the ensemble member through is ESMF-compliant reader.
- As illustration we show the general interface and a little detail of how the GMAO-coupling takes place. In GSI, the interfaces are defined through:
  - `gsi_enscouplermod`: An f90 interfacing defining available methods (see next page); and providing a replacement of `stub_ensmod` providing the f77 interface to allow GSI to build without the user-specific routines.
  - `cplr_ensmod`: is the set of programs defined by the user, that replace `stub_ensmod` at compilation (library build time).

# Interfacing to user-specific applications

## Illustration III: `gsi_enscouplermod`

Actual interface: `cplr_ensmod.F90`

```
!
! !PUBLIC MEMBER FUNCTIONS:
!
public GSI_EnsCoupler_localization_grid
public GSI_EnsCoupler_get_user_ens
public GSI_EnsCoupler_put_gsi_ens
```



The only methods currently needed are:

- a grid definition
- a get – to retrieve user's members
- a put to allow writing of ensemble perturbations

NOTE: none of these are yet general enough, in particular, the get is tied up to the variables currently participating in the hybrid covariance. Some time in the near future we'll make this general so the bundle user to feed the necessary fields for hybrid can carry whatever the user desires (e.g., aerosol members, or CO, etc).

# Interfacing to user-specific components

## Illustration IV: `set_crtm_aerosolmod`

- When having aerosols passed to CRTM one thing necessary is specification of the particle sizes. This is done via a model-specific Mie calculation that requires the environment relative humidity and aerosol type. This is where the **aerosol interface** comes into play.

Actual interface: `set_CRTM_aerosolmod.F90`

```
module set_crtm_aerosolmod
implicit none
private
public Set_CRTM_Aerosol
interface Set_CRTM_Aerosol
subroutine Set_CRTM_Aerosol_ ( km, na, aero_name, aero_conc, rh, aerosol)
use kinds, only: i_kind,r_kind
use mpimod, only: mype
use CRTM_Aerosol_Define, only: CRTM_Aerosol_type
implicit none
integer(i_kind) , intent(in) :: km           ! number of levels
integer(i_kind) , intent(in) :: na           ! number of aerosols
character(len=*), intent(in) :: aero_name(na) ! [na] GOCART aerosol names: du0001, etc.
real(r_kind),   intent(in) :: aero_conc(km,na) ! [km,na] aerosol concentration (Kg/m2)
real(r_kind),   intent(in) :: rh(km)          ! [km]    relative humidity [0,1]
type(CRTM_Aerosol_type), intent(inout) :: aerosol(na)! [na]  CRTM Aerosol object
end subroutine Set_CRTM_Aerosol_
end interface
end module set_crtm_aerosolmod
```

This provides  
a general  
interface

Stub routines: `stub_set_crtm_aerosol.F90`

```
subroutine Set_CRTM_Aerosol ( km, na, aero_name, aero_conc, rh, aerosol)
! USES:
use kinds, only: i_kind,r_kind
use mpimod, only: mype
use CRTM_Aerosol_Define, only: CRTM_Aerosol_type
implicit none
! !ARGUMENTS:
integer(i_kind) , intent(in) :: km           ! number of levels
integer(i_kind) , intent(in) :: na           ! number of aerosols
character(len=*), intent(in) :: aero_name(na) ! [na] GOCART aerosol names: du0001, etc.
real(r_kind),   intent(in) :: aero_conc(km,na) ! [km,na] aerosol concentration (Kg/m2)
real(r_kind),   intent(in) :: rh(km)          ! [km]    relative humidity [0,1]
type(CRTM_Aerosol_type), intent(inout) :: aerosol(na)! [na]  CRTM Aerosol object
if(mype==0) then
print*, 'Stub Set_CRTM_Aerosol: Call'
print*, 'Stub Set_CRTM_Aerosol'
endif
end subroutine Set_CRTM_Aerosol
```

This  
doesn't do  
anything.

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# Interfacing to user-specific components

## Illustration IV: `set_crtm_aerosolmod`

- Aerosols can be brought into GSI via the ChemBundle. For example, to bring the 15 GOCART aerosols GMAO sets the `chem_guess` table as

```
chem_guess::  
#   GOCART Aerosols  
# ----- Dust -----  
du001 72 1 10 dust DU001  
du002 72 1 10 dust DU002  
du003 72 1 10 dust DU003  
du004 72 1 10 dust DU004  
du005 72 1 10 dust DU005  
# ----- Sea-salt -----  
ss001 72 1 10 ssam SS001  
ss002 72 1 10 sscm1 SS002  
ss003 72 1 10 sscm2 SS003  
ss004 72 1 10 sscm3 SS004  
ss005 72 1 10 sea_salt SS005  
# ----- Sulfates -----  
so4 72 1 10 sulfate SO4  
# ----- Carbonaceous (main) -----  
bcphobic 72 1 10 dry_black_carbon BCPHOBIC  
bcphilic 72 1 10 wet_black_carbon BCPHILIC  
ocphobic 72 1 10 dry_organic_carbon OCPHOBIC  
ocphilic 72 1 10 wet_organic_carbon OCPHILIC  
::
```

These are the internal GSI names

In ChemBundle a value of 10 means aerosol.

These are the names of the fields in file

- The settings above allow aerosols to be passed to CRTM, but the GSI Jacobians do not take into account the sensitivity of fields to the aerosols – only the radiance feel the aerosols, but not the conventional fields. It's very simple to have the Jacobian augmented to take such sensitivities into account.

# Interfacing to user-specific components

## Illustration IV: `set_crtm_aerosolmod`

- A user wanting to exercise the aerosol capability should provide it's own coupler. In the case of GMAO, the coupler looks something like this:

### Actual GMAO coupler: `cplr_set_CRTM_aerosolmod.F90`

```
' subroutine Set_CRTM_Aerosol ( km, na, aero_name, aero_conc, rt
! USES:
use kinds, only: i_kind,r_kind
use CRTM_Aerosol_Define, only: CRTM_Aerosol_type
use crtmaerosol, only: SetAerosol

implicit none

! !ARGUMENTS:
integer(i_kind) , intent(in)    :: km                      ! number
integer(i_kind) , intent(in)    :: na                      ! number
character(len=*), intent(in)   :: aero_name(na)           ! [na]
real(r_kind),   intent(in)    :: aero_conc(km,na)        ! [km,r
real(r_kind),   intent(in)    :: rh(km)                  ! [km]

type(CRTM_Aerosol_type), intent(inout) :: aerosol(na)! [na]

call setAerosol (aero_name, aero_conc, rh, aerosol)

end subroutine Set_CRTM_Aerosol
```

f77-like Coupler  
calls user-  
specific f90  
routine

```
module crtmaerosol
! !USES:
use kinds, only: i_kind,r_kind
use CRTM_Aerosol_Define, only: CRTM_Aerosol_type
use CRTM_Aerosol_Define, only: DUST_AEROSOL, SEASALT_SSAM_AEROSOL, &
SEASALT_SSCM1_AEROSOL, SEASALT_SSCM2_AEROSOL, &
SEASALT_SSCM3_AEROSOL, SEASALT_SSCM3_AEROSOL, &
BLACK CARBON_AEROSOL, ORGANIC CARBON_AEROSOL, &
SULFATE_AEROSOL

use Chem_RegistryMod, only: Chem_Registry, Chem_RegistryCreate, Chem_RegistryDestroy
use Chem_MieMod,      only: Chem_Mie, Chem_MieCreate, Chem_MieDestroy, &
Chem_MieQueryIdx, Chem_MieQuery
use m_chars,
use m_die,
implicit none
! !PUBLIC METHODS:
public setAerosol
! !PUBLIC DATA MEMBERS:
! -----
type(Chem_Registry), pointer :: aerReg => null() ! Aerosol Registry
type(Chem_Mie),     pointer :: Mie => null()     ! Mie tables

! !REVISION HISTORY:
!
! 23feb2011 da Silva Initial version.
!
! EOP
```

Prologues stripped off for display only.

# Interfacing to user-specific components

## Illustration IV: `set_crtm_aerosolmod`

- As with `timermod` when we want **to replace the stub** with the real thing, we need to remove the stub from the GSI library and add our own (user-specific) library containing, in this case, the Coupler with the aerosol-specific calculations.
- This must **follow** the same mechanism through the **Makefiles** as discussed in Illustration I.

# MetGuess/ChemGuess\_Bundle

- Presently, ChemGuess\_Bundle allows flexible input of Chem-related fields (tracers and aerosols) to GSI.
- A desirable similar flexibility to handle all of the other (meteorological) guess fields, motivates introduction of MetGuess\_Bundle.
- Just as with ChemGuess, MetGuess\_Bundle is controlled by a table named met\_guess added to the anavinfo resource file. Examples are given below:

met_guess::					met_guess::				
!var	level	crtm_use	desc	orig_name	!var	level	crtm_use	desc	orig_name
cw	72	10	cloud_condensate	qctot	cw	64	10	cloud_condensate	qctot
ql	72	-1	Water	qltot	#ql	64	-1	Water	qltot
qi	72	-1	Ice	qitot	#qi	64	-1	Ice	qitot
#qr	72	10	Rain	qrtot	#qr	64	10	Rain	qrtot
#qs	72	10	Snow	qstot	#qs	64	10	Snow	qstot
#qg	72	10	Graupel	qg	#qg	64	10	Graupel	qg
#qh	72	10	Hail	qh	#qh	64	10	Hail	qh
#cf	72	2	cloud_frac4rad(fcld)	cloud	#cf	64	2	cloud_frac4rad(fcld)	cloud
::					::				

GMAO

NCEP

# MetGuess\_Bundle: Methods

- As with ChemGuess, MetGuess **does not handle parallelization**; e.g., fields are on subdomains. This means filling up this bundle must be done by the user after reading the guess and distributing it onto subdomains.
- Presently, the available **methods** in MetGuess are:

```
public :: gsi_metguess_create_grids  
public :: gsi_metguess_destroy_grids  
public :: gsi_metguess_init  
public :: gsi_metguess_get  
public :: gsi_metguess_final
```

- The trickiest of the Methods is the GET. It's easy to use but has multiple capability. Examples of the GET function are given in the **ProTex documentation** available in the source code. Here a couple of simple examples follow:

# MetGuess\_Bundle: Methods

- Examples of using the GET Method:
  - Say a routine wants to know whether or not the variable `cw` is in `MetGuess_Bundle`. This can be done simply with the call  
*call gsi\_metguess\_get ( 'var:cw', ivar, ier )*  
if `ivar` is greater than zero, the variable is present in the bundle.
  - Say a routine wants to get the number of all 3d cloud fields in the `MetGuess_Bundle`, this can be done by use the tag `clouds::3d`, as in:  
*call gsi\_metguess\_get ( 'clouds::3d', n, ier )*  
notice this uses the same interface as in the example above, but returns information about something else.
  - Say a routine wants the name of all 3d cloud-fields  
*call gsi\_metguess\_get ('clouds::3d', cld3dnames, ier)*  
now the returned variable `cld3dnames` is a character array with the names of all 3d-cloud-guess. Notice it is important to inquire before hand about the number of 3d-cloud fields available and to properly allocate space for the character arrays `cld3dnames`, and only then make the call above.
  - Other functionalities and inquire modes are available.

# MetGuess/Chem\_Guess\_Bundle

## Remarks and Work in Progress

- As ChemGuess\_Bundle, MetGuess\_Bundle is treated as a common block.
  - This means you **cannot**, for the time being, **instantiate** it.
- As ChemGuess\_Bundle, MetGuess\_Bundle is an **almost opaque** object.
  - This means only methods are available to the outside world, and the bundle itself (common block, for now)
- In the present (upcoming, June 2011) version of the GSI NCEP trunk, **only clouds** are being handled by MetGuess. That is, winds, temperature, specific humidity, and all other meteorological fields are still handled in guess\_grids (as the ges\_X variables). This will change in the near future.

# General Remarks: Adding new observing instruments

- We all know adding new instruments involves changes to the following files/procedures:
  - obsmod
  - read\_obs
  - setuprhsall (and addition of corresponding new setupNEW)
  - intjo, stpjo
  - addition of intNEW and stpNEW

# General Remarks: Adding new observing instruments

- What many may not know is that adding new obs-instruments also requires changes to:
  - `read_obsdiags/write_obsdiags`
  - `setupyobs`
  - `obs_sensitivity`
  - `m_rhs` (possibly, when stats involved)
- Invariably when these are not changed the basic mode of running GSI may work, but hardly any of the advanced features will.

# General Remarks: Others

- Use general **intrinsic math functions**, instead of specific (only) functions, that is:
  - Sqrt() rather than Dsqrt()
  - Abs() rather than Dabs()
  - Etc
- Bundle supports both single and double precision. It is important to specify the bundle KIND when creating a bundle, as in for example:

```
write(bname,'(a)') 'State Vector'  
call GSI_BundleCreate(yst,grid,bname,ierror, &  
    names2d=svars2d,names3d=svars3d,edges=edges, &  
    bundle_kind=r_kind)
```

## Four-dimensional Variational Approach

The general cost function of the variational formulation

$$\begin{aligned} J(\mathbf{x}) &= \frac{1}{2} (\mathbf{x}_0 - \mathbf{x}^b)^T \mathbf{B}^{-1} (\mathbf{x}_0 - \mathbf{x}^b) + J_x \\ &+ \frac{1}{2} \sum_{k=0}^K [\mathbf{h}(\mathbf{x}_k) - \mathbf{y}_k]^T \mathbf{R}_k^{-1} [\mathbf{h}(\mathbf{x}_k) - \mathbf{y}_k] \\ &+ \frac{1}{2} \sum_{k=1}^K [\mathbf{m}(\mathbf{x}_k) - \mathbf{x}_k]^T \mathbf{Q}_k^{-1} [\mathbf{m}(\mathbf{x}_k) - \mathbf{x}_k] \end{aligned}$$

where

- ▷  $\mathbf{x} \equiv [\mathbf{x}_0, \mathbf{x}_1, \dots, \mathbf{x}_K]^T$  is a 4d state vector;
- ▷  $\mathbf{h}_k$  and  $\mathbf{m}_k$  are the nonlinear observation and dynamical model operators, respectively;
- ▷  $\mathbf{B}$ ,  $\mathbf{Q}_k$ , and  $\mathbf{R}_k$  are the background, model, and observation error covariances, respectively.
- ▷ Strong constraint formulation:  $\mathbf{Q}_k \rightarrow \infty$ ;
- ▷ Weak constraint formulation,  $\mathbf{Q} \neq 0$  accounts for imperfections in the model  $\mathbf{m}$ ;
- ▷  $J_x$  represents extra constraint (e.g., balance).

## Strong Constraint Incremental 4DVAR

For simplicity consider now the strong constraint case. In incremental 4DVAR the cost function at the  $j$ -th iteration is

$$\begin{aligned} J_j(\delta \mathbf{x}_j) &= \frac{1}{2} (\delta \mathbf{x}_j - \delta \mathbf{x}_j^b)^T \mathbf{B}^{-1} (\delta \mathbf{x}_j - \delta \mathbf{x}_j^b) \\ &+ \frac{1}{2} \sum_{k=0}^K (\mathbf{H}_{j,k} \mathbf{M}_{j,k} \delta \mathbf{x}_j - \mathbf{d}_{j,k})^T \mathbf{R}^{-1} (\mathbf{H}_{j,k} \mathbf{M}_{j,k} \delta \mathbf{x}_j - \mathbf{d}_{j,k}) \end{aligned}$$

where  $\mathbf{d}_{j,k} \equiv \mathbf{y}_k - \mathbf{h}_k(\mathbf{m}_k(\mathbf{x}^b))$ ,  $\delta \mathbf{x}_j^b \equiv \mathbf{x}^b - \mathbf{x}_{j-1}$ , and

- ▷  $\delta \mathbf{x}_j \equiv \mathbf{x}_j - \mathbf{x}_{j-1}$  is the control variable;
- ▷ The inner loop minimization of  $J_j$  can be solved by
  - Conjugate gradient
  - Quasi-Newton (such as L-BFGS)
  - Lanczos
- ▷ Conditioning of the  $J_j$  minimization is determined by the Hessian  $\nabla^2 J_j = \mathbf{B}^{-1} + \sum_k \mathbf{M}_{j,k}^T \mathbf{H}_{j,k}^T \mathbf{R}^{-1} \mathbf{M}_{j,k} \mathbf{H}_{j,k}$ , which spectrum is such that a good preconditioning is essential, particularly in 4DVAR.

# Connecting Math and Code

## gsisub

- The main entry point of GSI decides whether to run the observer or the minimization

In 4dvar:

This is part of  
in outer loop  
During NL model  
integration

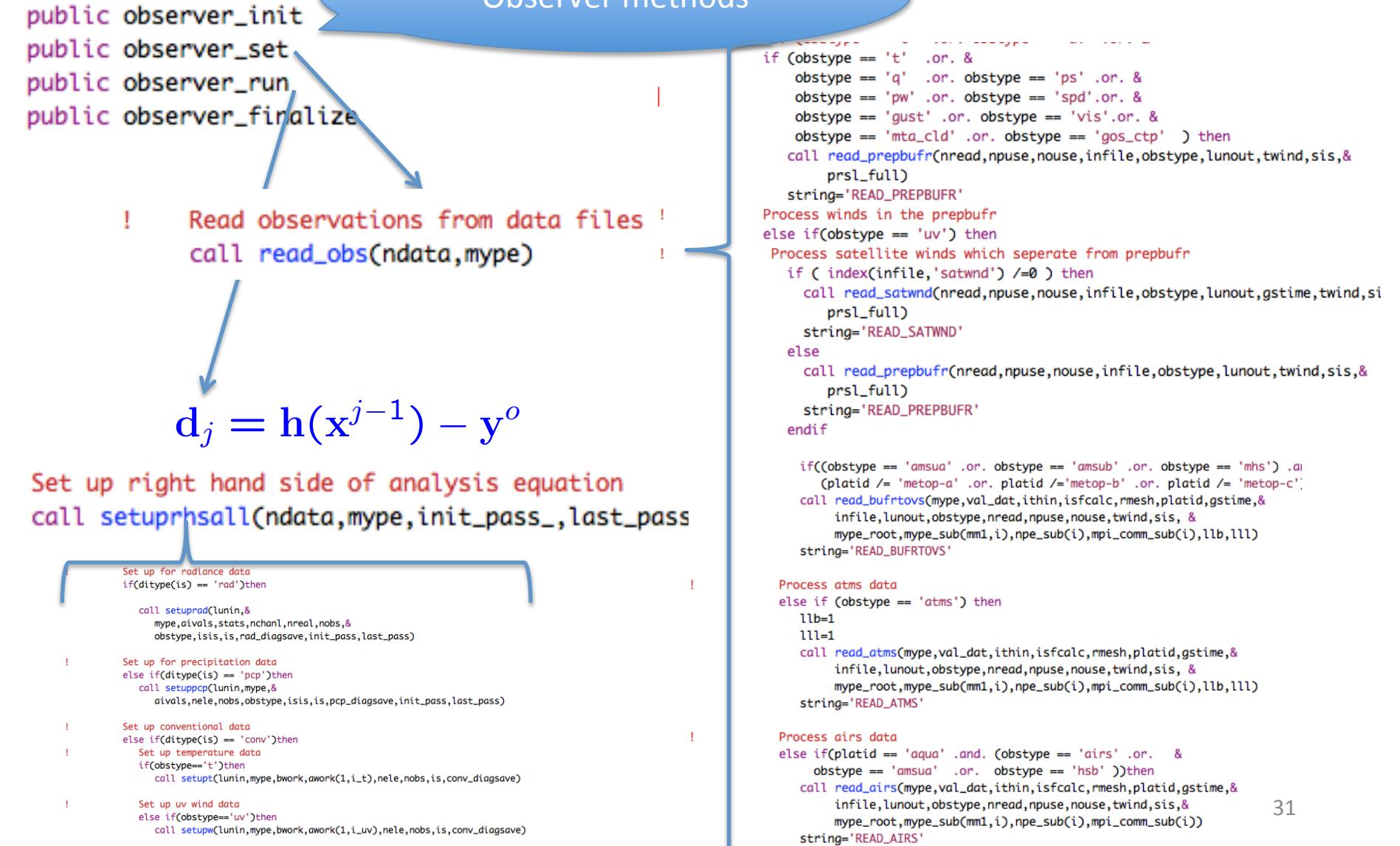
This becomes  
the inner loop

```
! Decide whether to do observer or minimization
if (lobserver) then
    ! Do observer only
    call observer_init
    call observer_run
    call observer_finalize
else
    ! Complete setup and execute external and internal minimization loops
    call glbsoi(mype)
endif
```

In 3dvar, this calls the observer

- The observer gets called by the forward model via the ESMF interface

# observer



# glbsoi

$$(B^{-1} + H_j^T R^{-1} H_j) \delta x_j = H_j^T R^{-1} d_j + B^{-1} b_{j-1}$$

! Set up right hand side of analysis equation  
 call setuprhsall(ndata,mype,.true.,.true.)

$$d_j = h(x^{j-1}) - y^o$$

Prepare RHS of Eq

$$b_{j-1} = x^b - x_{j-1}$$

Only in Adjoint Mode:  
 Replace RHS with model sensitivity

! Set up right hand side of adjoint of analysis equation  
 if (lsensrecompute) lobsensfc=(jiter==jiterend)  
 if (lobsensfc.or.iobsconv>0) call init\_fc\_sens

! Call inner minimization loop

if (laltmin) then

  if (lsqrtn) then

    if (mype==0) write(6,\*)"GLBSOI: Using sqrt(B), jiter=",jiter

    call sqrtmin

$$(I + B^{1/2} H_j^T R^{-1} H_j B^{1/2}) z_j = B^{1/2} H_j^T R^{-1} d_j + B^{-1/2} b_{j-1}$$

$$z_j = B^{-1/2} \delta x_j$$

  endif

  if (lbicg) then

    if (mype==0) write(6,\*)"GLBSOI: Using bicg, jiter=",jiter

    call bicg

  endif

$$(I + B H_j^T R^{-1} H_j) \delta x_j = B H_j^T R^{-1} d_j + b_{j-1}$$

else

  Standard run

  if (mype==0) write(6,\*)"GLBSOI: START pcgsoi jiter=",jiter

  call pcgsoi

endif

$$z + H_j^T R^{-1} H_j \delta x_j = H_j^T R^{-1} d_j + B^{-1} b_{j-1}$$

$$z_j = B^{-1} \delta x_j$$

## sqrtmin

Adjoint minimization

Ideal minimization scheme  
when running 4dvar

When inner loop is linear,  
this is equivalent to default  
PCGSIO (double CG) min, but  
not identical.

```
if (lbfgsmin) then
    call mlqn3 (xhat,costf,gradx,eps,itermax,npert,nwrvecs)

elseif (lcongrad) then
! Setup CONGRAD
    if (.not.ltlint) then
        write(6,*)"sqrtmin: congrad requires ltlint"
        call stop2(308)
    end if
    call setup_congrad(mype,npert,jiter,jiterstart,itermax,nwrvecs, &
                      14dvar,lanczosave,ltcost)
    lsavev=(.not.lobsensfc)
    if(jsiga<miter) lsavev=lsavev.and.(jiter<miter)

    if (lobsensfc.and.lobsensadj) then
        ! Get Lanczos vectors
        if ( llancdone ) then      ! Lanczos vecs already computed, read them in
            call read_lanczos(itermax)
        else
            ! Do forward min to get Lanczos vectors
            call congrad(xhat,costf,gradx,eps,itermax,iobsconv,lsavev)
        endif

        ! Compute sensitivity
        zgg=dot_product(fcsens,fcsens,r_quad)
        if (mype==0) write(6,888) trim(myname),': Norm fcsens=',sqrt(zgg)
        xhat=fcsens
        call congrad_ad(xhat,itermax)
    else
        ! Compute increment
        call congrad(xhat,costf,gradx,eps,itermax,iobsconv,lsavev)
        ! Calculate estimate of analysis errors
        if(jsiga==jiter) call getsiga()
    endif
    ! Finish CONGRAD
    call save_precond(lsavev)

else ! plain conjugate gradient
    if (.not.ltlint) then
        write(6,*)"sqrtmin: pcgsqrt requires ltlint"
        call stop2(309)
    end if
    iprt=0
    if (ladtest .or. lgrtest .or. ltcost) iprt=1
    call pcgsqrt(xhat,costf,gradx,itermax,iprt)
endif
```

## pcgsqrt

Vanilla CG algorithm,  
it reproduces doubleCG  
when under linearized  
Inner loop and proper  
selection of options to  
within roundoff.

```
! Perform inner iteration
inner_iteration: do iter=1,itermax
    if (mype==0) write(6,*) trim(myname),': Minimization iteration',iter

    ! Search direction
    do ii=1,dirx%lencv
        dirx%values(ii)=-gradx%values(ii)+beta*dirx%values(ii)
    end do

    ! Estimate
    do ii=1,xtry%lencv
        xtry%values(ii)=dirx%values(ii)
    end do

    ! Evaluate cost and gradient
    call evaljgrad(xtry,zfk,grtry,lsavinc,0,myname)

    ! Get A q_k
    do ii=1,grtry%lencv
        grtry%values(ii)=grtry%values(ii)-grad0%values(ii)
    end do

    ! Calculate stepsize
    dkqk=dot_product(dirx,grtry,r_quad)
    alpha=zero_quad
    if(abs(dkqk)>tiny_r_kind) alpha = zgk/dkqk

    ! Update estimates
    do ii=1,xhat%lencv
        xhat%values(ii) =xhat%values(ii) +alpha* dirx%values(ii)
        gradx%values(ii)=gradx%values(ii)+alpha*grtry%values(ii)
    end do

    ! Orthogonormalize against previous gradient
    if(iorthomax>0) then
        iortho=min(iter,iorthomax)
        do jj=iortho,1,-1
            zlda = dot_product(gradx,cglwork(jj))
            do ii=1,gradx%lencv
                gradx%values(ii) = gradx%values(ii) - zlda*cglwork(jj)%values(ii)
            enddo
        enddo
        beta=zero_quad
        if(abs(zgk)>tiny_r_kind) beta=zgnew/zgk
        zgk=zgnew

        ! Evaluate cost for printout
        if (nppt>=1) call evaljgrad(xhat,zfk,gradf,lsavinc,nppt,myname)

    end do inner_iteration
```



Calculating  $\nabla J$  is at the core of the minimization

## evaljgrad

going backwards

```
! Contribution from background term  
gradx = xhat  
  
if (lsaveobsens) then  
! Observation sensitivity right hand side  
do ii=1,gradx%lenCV  
gradx%values(ii) = gradx%values(ii) - fcsens%values(ii)  
enddo  
else  
! Contribution from previous background term  
do ii=1,gradx%lenCV  
gradx%values(ii) = gradx%values(ii) + xhatsave%values(ii)  
enddo  
endif
```

going forwards

$$\nabla \hat{J}_j = \lambda + L_j^T M_j^T H_j^T R^{-1} (H_j M_j L \lambda_j - d_j)$$

```
! Convert from control space to model space  
call control2model(xhat,mval,sbias)  
  
! Run TL model to fill sval  
if (l4dvar) then  
call model_tl(mval,sval,llprt)  
else  
do ii=1,nobs_bins  
sval(ii)=mval(1)  
enddo  
end if  
  
! Compare obs to solution and transpose back to grid (H^T R^{-1} H)  
do ibin=1,nobs_bins  
call intjo(yobs(ibin),rval(ibin),rbias,sval(ibin),sbias)  
end do  
!  
! Evaluate J_0  
call evaljo(zjo,iobs,nppt,llouter)
```

## control2model

$$\delta\mathbf{x} = \mathbf{L}\delta\lambda$$

(\*)

```

! Loop over control steps
do jj=1,nsubwin

    ! Multiply by sqrt of background error (ckerror)
    ! -----
    ! Apply sqrt of variance, as well as vertical & horizontal parts of background
    ! error
    call ckgcov(xhat%step(jj)%values(:),workst,workvp, &
                 sval(jj)%t,sval(jj)%p,workrh,sval(jj)%oz, &
                 sval(jj)%sst,sval(jj)%cw,nnn)

    ! Balance equation
    call balance(sval(jj)%t,sval(jj)%p,workst,workvp,fpsproj)

    ! Apply strong balance constraint
    call strong_bk(workst,workvp,sval(jj)%p,sval(jj)%t,sval(jj)%oz,sval(jj)%cw)

    ! -----
    ! Get 3d pressure
    call getprs_tl(sval(jj)%p,sval(jj)%t,sval(jj)%p3d)

    ! Convert input normalized RH to q
    call normal_rh_to_q(workrh,sval(jj)%t,sval(jj)%p3d,sval(jj)%q)

    ! Calculate sensible temperature
    call tv_to_tsen(sval(jj)%t,sval(jj)%q,sval(jj)%tsen)

    ! Convert streamfunction and velocity potential to u,v
    call getuv(sval(jj)%u,sval(jj)%v,workst,workvp)

end do

! Bias correction terms
do ii=1,nsclen
    bval%predr(ii)=xhat%predr(ii)*sqrt(varprd(ii))
enddo

```

NOTE: Same remark  
 as from model2control  
 applies here: this is  
 a convolution of variable  
 transformations and the  
 application of a part  $\mathbf{L}$  of  
 the square-root  
 decomposition of  $\mathbf{B}$  (see \*)

## model\_tl

j-th iteration propagation  
with the tangent linear  
model

$$\delta \mathbf{x}_{k;j} = \mathbf{M}_{k,k-1;j} \delta \mathbf{x}_{k-1;j}$$

```
! Run TL model
do istep=0,nstep-1

    ! Locate (istep) in xini, if any. Then apply TL model from istep
    ! (p_xini and xxpert) to istep+1 (xxpert).
    p_xini => istep_locate_(xini,istep,nfrctl,
                             ldprt_,myname//'.xini-',nymdi,nhmsi)

    call gsi_4dcoupler_model_tl(p_xini,xxpert,nymdi,nhmsi,ndt,rc=ierr)
        if(ierr/=0) call die(myname,'gsi_4dcoupler_model_tl(), rc = ',ierr)

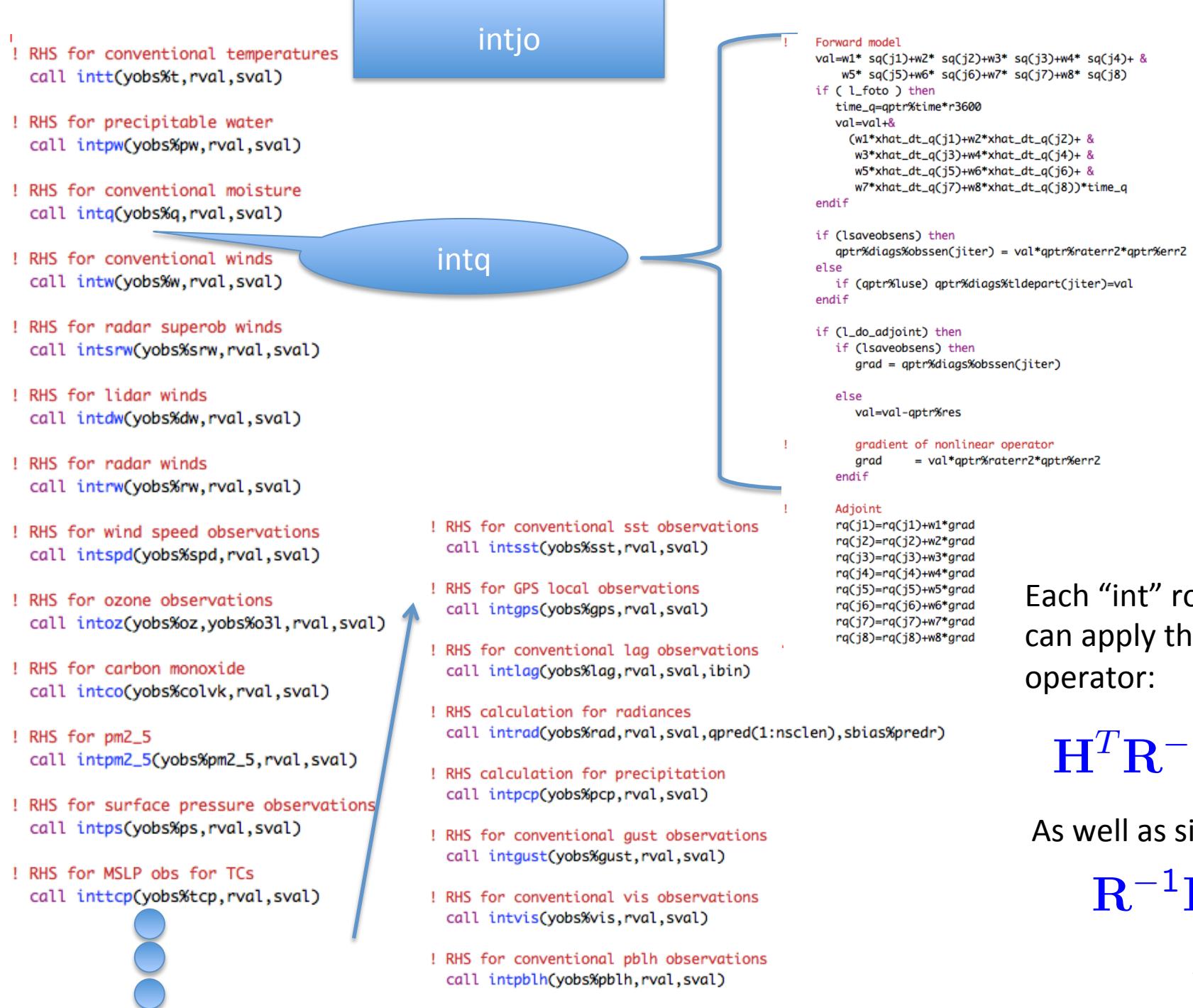
    ! Update the clock to (istep+1)
    call tick (nymdi,nhmsi,dt)

    ! Locate (istep+1) in xini, if any. Then add this increment to the
    ! current state (xxpert).
    p_xini => istep_locate_(xini,istep+1,nfrctl,
                             ldprt_,myname//'.xini+',nymdi,nhmsi)

    if(associated(p_xini)) call self_add(xxpert,p_xini)

    ! Locate istep in xobs at (istep+1), if any. Then store the current
    ! state (xxpert) to xobs.
    p_xobs => istep_locate_(xobs,istep+1,nfrobs,
                             ldprt_,myname//'.xobs+',nymdi,nhmsi)

    if(associated(p_xobs)) then
        p_xobs = xxpert
    endif
enddo|
```



Each “int” routine can apply the full operator:

$$\mathbf{H}^T \mathbf{R}^{-1} \mathbf{H}$$

As well as simply:

$$\mathbf{R}^{-1} \mathbf{H}$$

## evalgrad

Evaluate cost due to various constraints

```
if (l_do_adjoint) then
! Moisture constraint
zjl=zero_quad
if (.not.ltlint) then
do ibin=1,nobs_bins
call evalqlim(sval(ibin)%q,zjl,rval(ibin)%q)
enddo
endif

if (ljcdfi) then
call evaljcdfi(sval,zjc,rval)
else
! Jc and other 3D-Var terms
! Don't know how to deal with Jc term so comment for now...
! call eval3dvar(sval,zjc,rval,zdummy)
zjc=zero_quad
endif
```

Similarly to int routines, evalgrad can be used to apply only part of operator ...  $\mathbf{R}^{-1}\mathbf{H}_j\mathbf{M}_j\mathbf{L}\lambda_j$

$$\nabla \hat{J}_j = \lambda + \mathbf{L}_j^T \mathbf{M}_j^T \mathbf{H}_j^T \mathbf{R}^{-1} (\mathbf{H}_j \mathbf{M}_j \mathbf{L} \lambda_j - \mathbf{d}_j)$$

```
! Run adjoint model
if (l4dvar) then
call model_ad(mval,rval,llprt)
else
mval(1)=rval(1)
do ii=2,nobs_bins
call self_add(mval(1),rval(ii))
enddo
end if

! Adjoint of convert control var to physical space
call model2control(mval,rbias,gradx)

! Cost function
fjcost=zjb+zjo+zjc+zjl

endif
```

## evaljgrad

Evaluate cost due to various constraints

```
if (l_do_adjoint) then
! Moisture constraint
zjl=zero_quad
if (.not.ltlint) then
do ibin=1,nobs_bins
call evalqlim(sval(ibin)%q,zjl,rval(ibin)%q)
enddo
endif

if (ljcdfi) then
call evaljcdfi(sval,zjc,rval)
else
! Jc and other 3D-Var terms
! Don't know how to deal with Jc term so comment for now...
! call eval3dvar(sval,zjc,rval,zdummy)
zjc=zero_quad
endif
```

Similarly to int routines, evaljgrad can be used to apply only part of operator ...  $R^{-1}H_j M_j L \lambda_j$

$$\nabla \hat{J}_j = \lambda + L_j^T M_j^T H_j^T R^{-1} (H_j M_j L \lambda_j - d_j)$$

```
! Run adjoint model
if (l4dvar) then
call model_ad(mval,rval,llprt)
else
mval(1)=rval(1)
do ii=2,nobs_bins
call self_add(mval(1),rval(ii))
enddo
end if

! Adjoint of convert control var to physical space
call model2control(mval,rbias,gradx)

! Cost function
fjcost=zjb+zjo+zjc+zjl

endif
```

## model\_ad

j-th iteration propagation  
with the adjoint of the  
tangent linear model

$$\delta \mathbf{x}_{k-1;j} = \mathbf{M}_{k,k-1;j}^T \delta \mathbf{x}_{k;j}$$

```
! Run AD model
do istep=nstep-1,0,-1
  ! Locate (istep+1) in xobs, if any. Then apply AD model from istep+1
  ! (xxpert, p_xobs) to istep (xxpert).
  p_xobs => istep_locate_(xobs,istep+1,nfrobs, &
                           ldprt_.and.mype==0,myname//".xobs+",nymdi,nhmsi)

  ! get (date,time) at (istep).
  call tick(nymdi,nhmsi,-dt)

  call gsi_4dcoupler_model_ad(xxpert,p_xobs,nymdi,nhmsi,ndt,rc=ierr)
  if(ierr/=0) call die(myname,'gsi_4dcoupler_model_ad()', rc '=',ierr)

  ! Locate (istep) in xobs, if any. Then add adjoint increment to
  ! the current adjoint state (xxpert).
  p_xobs => istep_locate_(xobs,istep,nfrobs, &
                           ldprt_.and.mype==0,myname//".xobs-",nymdi,nhmsi)

  if(associated(p_xobs)) call self_add(xxpert,p_xobs) ! xxpert += p_xobs

  ! Locate (istep) in xini, if any. Then store the current adjoint
  ! state (xxpert) to xini.
  p_xini => istep_locate_(xini,istep,nfrctl, &
                           ldprt_.and.mype==0,myname//".xini-",nymdi,nhmsi)

  if(associated(p_xini)) then
    call self_add(p_xini,xxpert) ! p_xini += xxpert
  endif

enddo
```

## model2control

$$\delta\lambda = \mathbf{L}^T \delta\mathbf{x}$$

NOTE: This procedure is indeed a convolution of variable transformations and the application of a part of  $\mathbf{L}^T$  the square-root decomposition of  $\mathbf{B}$  (see \*)

```

! Loop over control steps
do jj=1,nsubwin

  workst(:,:,:)=zero
  workvp(:,:,:)=zero
  workrh(:,:,:)=zero

  ! Convert RHS calculations for u,v to st/vp for application of
  ! background error
  call getstvp(rval(jj)%u,rval(jj)%v,workst,workvp)

  ! Calculate sensible temperature
  call tv_to_tsen_ad(rval(jj)%t,rval(jj)%q,rval(jj)%tsen)

  ! Adjoint of convert input normalized RH to q to add contribution of moisture
  ! to t, p , and normalized rh
  call normal_rh_to_q_ad(workrh,rval(jj)%t,rval(jj)%p3d,rval(jj)%q)

  ! Adjoint to convert ps to 3-d pressure
  call getprs_ad(rval(jj)%p,rval(jj)%t,rval(jj)%p3d)

  ! Multiply by sqrt of background error adjoint (ckerror_ad)
  ! -----

```

```

! Apply transpose of strong balance constraint
call strong_bk_ad(workst,workvp,rval(jj)%p, &
                  rval(jj)%t,rval(jj)%oz,rval(jj)%ow)

! Transpose of balance equation
call tbalance(rval(jj)%t,rval(jj)%p,workst,workvp,fpsproj)

```

```

! Apply variances, as well as vertical & horizontal parts of background error
gradz(:)=zero

```

```

call ckgcov_ad(gradz,workst,workvp,rval(jj)%t,rval(jj)%p,workrh,&
                rval(jj)%oz,rval(jj)%sst,rval(jj)%ow,nnn)

```

```

do ii=1,nval_lenz
  grad%step(jj)%values(ii)=grad%step(jj)%values(ii)+gradz(ii)
enddo

```

```

! -----
end do

```

```

! Bias predictors are duplicated
do ii=1,nsclen
  zwork(ii)=bval%predr(ii)
enddo
do ii=1,npclen
  zwork(nsclen+ii)=bval%predp(ii)
enddo

```

(\*)

# 4DVAR namelist settings

- Observer (1<sup>st</sup> outer loop)
- 1<sup>st</sup> inner loop

```
&SETUP
miter=2,niter(1)=100,niter(2)=150,
niter_no_qc(1)=999,niter_no_qc(2)=999,
write_diag(1)=.true.,write_diag(2)=.false.,
write_diag(3)=.true.,
gencode=82,qoption=2,
factqmin=0.005,factqmax=0.005,deltim=
$DELTIM,
ndat=62,npred=5,iguess=-1,
oneobtest=.false.,retrieval=.false.,
l_foto=.false.,use_pbl=.false.,
l4dvar=.true.,jiterstart=1,
lobserver=.true.,
/
```

```
&SETUP
miter=2,niter(1)=100,niter(2)=150,
niter_no_qc(1)=999,niter_no_qc(2)=999,
write_diag(1)=.true.,write_diag(2)=.false.,
write_diag(3)=.true.,
gencode=82,qoption=2,
factqmin=0.005,factqmax=0.005,deltim=
$DELTIM,
ndat=62,npred=5,iguess=-1,
oneobtest=.false.,retrieval=.false.,
l_foto=.false.,use_pbl=.false.,
l4dvar=.true.,jiterstart=1,
lsqrtnb=.true.,ltlint=.true.,lcongrad=.true.,
nhr_assimilation=6,nhr_obsbin=1,
idmodel=.false.,lwrtinc=.true.,
/
```

## The Linear 4d-Analysis Adjoint

A linear analysis system calculates:

$$\begin{aligned}\delta\mathbf{x} = \mathbf{K}\mathbf{d} &= (\mathbf{B}^{-1} + \mathbf{H}^T \mathbf{R}^{-1} \mathbf{H})^{-1} \mathbf{H}^T \mathbf{R}^{-1} \mathbf{d} && \text{phy-space} \\ &= \mathbf{B} \mathbf{H}^T (\mathbf{H} \mathbf{B} \mathbf{H}^T + \mathbf{R}) \mathbf{d} && \text{obs-space}\end{aligned}$$

and its adjoint calculates:

$$\begin{aligned}\delta\mathbf{z} = \mathbf{K}^T \mathbf{g} &= \mathbf{R}^{-1} \mathbf{H} (\mathbf{B}^{-1} + \mathbf{H}^T \mathbf{R}^{-1} \mathbf{H})^{-1} \mathbf{g} && \text{phy-space} \\ &= (\mathbf{H} \mathbf{B} \mathbf{H}^T + \mathbf{R}) \mathbf{H} \mathbf{B} \mathbf{g} && \text{obs-space}\end{aligned}$$

Obtaining the adjoint in practice:

- ▷ Direct, line-by-line, adjoint (Zhu & Gelaro 2007)
- ▷ Operator manipulation:
  - Observation space (Baker & Daley 2000):

$$(\mathbf{H} \mathbf{B} \mathbf{H}^T + \mathbf{R}) \delta\mathbf{z} = \mathbf{H} \mathbf{B} \mathbf{g}$$

Either one  
of these  
can be done  
with GSI

- Physical space (Trémoloet 2008):  $\delta\mathbf{z} = \mathbf{R}^{-1} \mathbf{H} \delta\mathbf{g}$   
 $(\mathbf{B}^{-1} + \mathbf{H}^T \mathbf{R}^{-1} \mathbf{H}) \delta\mathbf{g} = \mathbf{g}$
- Approximate Hessian:  $\tilde{\mathbf{A}}^{-1} = \mathbf{U} \Lambda \mathbf{U}^T \sim \sqrt{\mathbf{B}^{-1} + \mathbf{H}^T \mathbf{R}^{-1} \mathbf{H}}$   
 $\delta\mathbf{z} = \mathbf{R}^{-1} \mathbf{H} \tilde{\mathbf{A}} \mathbf{g}$

## obs\_sensitivity

```
!      read and convert output of GCM adjoint
do ii=1,nsubwin
    call allocate_state(fcgrad(ii))
end do
call allocate_preds(zbias)
zbias=zero
call gsi_4dcoupler_getpert(fcgrad,nsubwin,'adm') } Read forecast sensitivity
call model2control(fcgrad,zbias,fcsens) } Convert sensitivity to control vector
do ii=1,nsubwin
    call deallocate_state(fcgrad(ii))
end do
call deallocate_preds(zbias)
endif
```

- The above prepares the right-hand-side of the equation to be solved:

$$(\mathbf{I} + \mathbf{L}^T \mathbf{H}^T \mathbf{R}^{-1} \mathbf{H} \mathbf{L}) \delta g = \mathbf{L}g$$

- This is solved via `sqrtmin` through multiple calls to `evaljgrad`
- To finally get the observation sensitivity

$$\delta z = \mathbf{R}^{-1} \mathbf{H} \mathbf{L} \delta g$$

we need to call `evaljgrad` one more time without invoking the adjoint option.

# 3DVAR-ADJ namelist settings

- Square-root(B) CG
- ADJ square-root(B) CG

```
&SETUP
miter=2,niter(1)=100,niter(2)=150,
niter_no_qc(1)=999,niter_no_qc(2)=999,
write_diag(1)=.true.,write_diag(2)=.false.,
write_diag(3)=.true.,
gencode=82,qoption=2,
factqmin=0.005,factqmax=0.005,deltim=
$DELTIM,
ndat=62,npred=5,iguess=-1,
oneobtest=.false.,retrieval=.false.,
l_foto=.false.,use_pbl=.false.,
lsqrtb=.true.,ltlint=.true.,
/
```

```
&SETUP
miter=2,niter(1)=100,niter(2)=150,
...
lsqrtb=.true.,ltlint=.true.,
jiterstart=1,jiterend=2,
lobsensmin=.true.,
lsensrecompute=.true.,lobsensfc=.true.,
lobsdiagsave=.true.,
/
```

```
&SETUP
miter=2,niter(1)=100,niter(2)=150,
...
lsqrtb=.true.,ltlint=.true.,
jiterstart=1,jiterend=1,
lobsensmin=.true.,
lsensrecompute=.true.,lobsensfc=.true.,
lobsdiagsave=.true.,
/
```

Note: new opts are minimal set suggested opts, that have been tested.

# Closing Remarks

- Please know MetGuess and ChemGuess are *still* under development.
- Please note that, some of the code shown above has already changed from the version that is presently available via the DTC repository.
- Comments and concerns are always welcome.